



Satellite Instrument Calibration Issues: Experience Gained from SSMIS

W. Bell, S. English, S. Swadley¹ & G. Kelly²

¹ Naval Research Laboratory, Monterey, CA, US

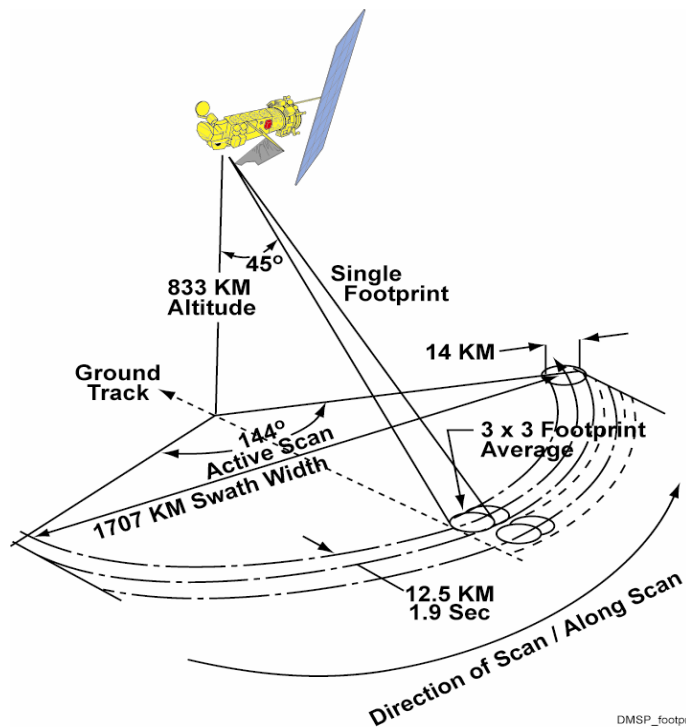
² ECMWF, Reading, UK

Acknowledgements : B.Candy, F.Hilton, A. Smith, N.Atkinson, J. Eyre
organisers & participants in *SSMIS mini-workshop*, NRL, Oct 2005

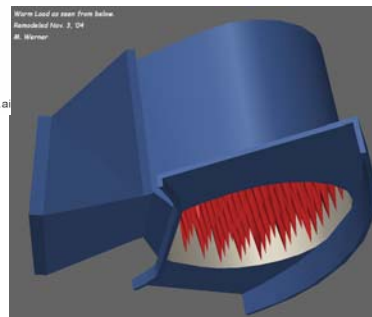
Bias Estimation and Correction in Data Assimilation, ECMWF, 8 -11 November 2005

- Background
- Instrumental biases & correction strategies :
 - Warm load solar intrusions
 - Intrusion mapping (Met Office)
 - Gain correction (NRL, NOAA)
 - Reflector emission
 - Empirical correction
 - Physical basis
- Radiance monitoring & analysis increments
- Initial forecast impact studies at ECMWF
- Future developments
- Summary & conclusions

Background: Instrument and scan geometry



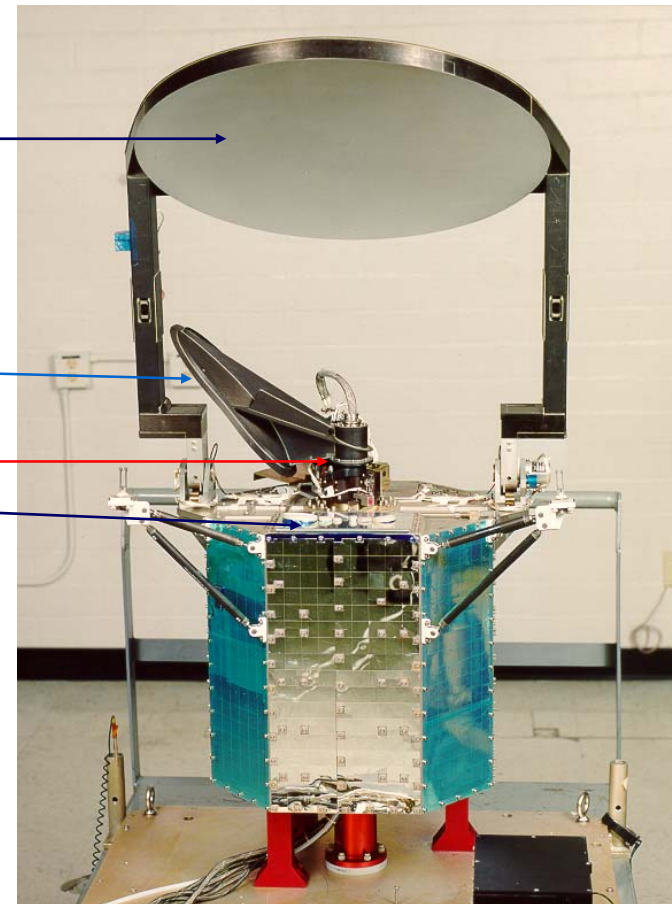
DMSP_footprint.a



Main Reflector

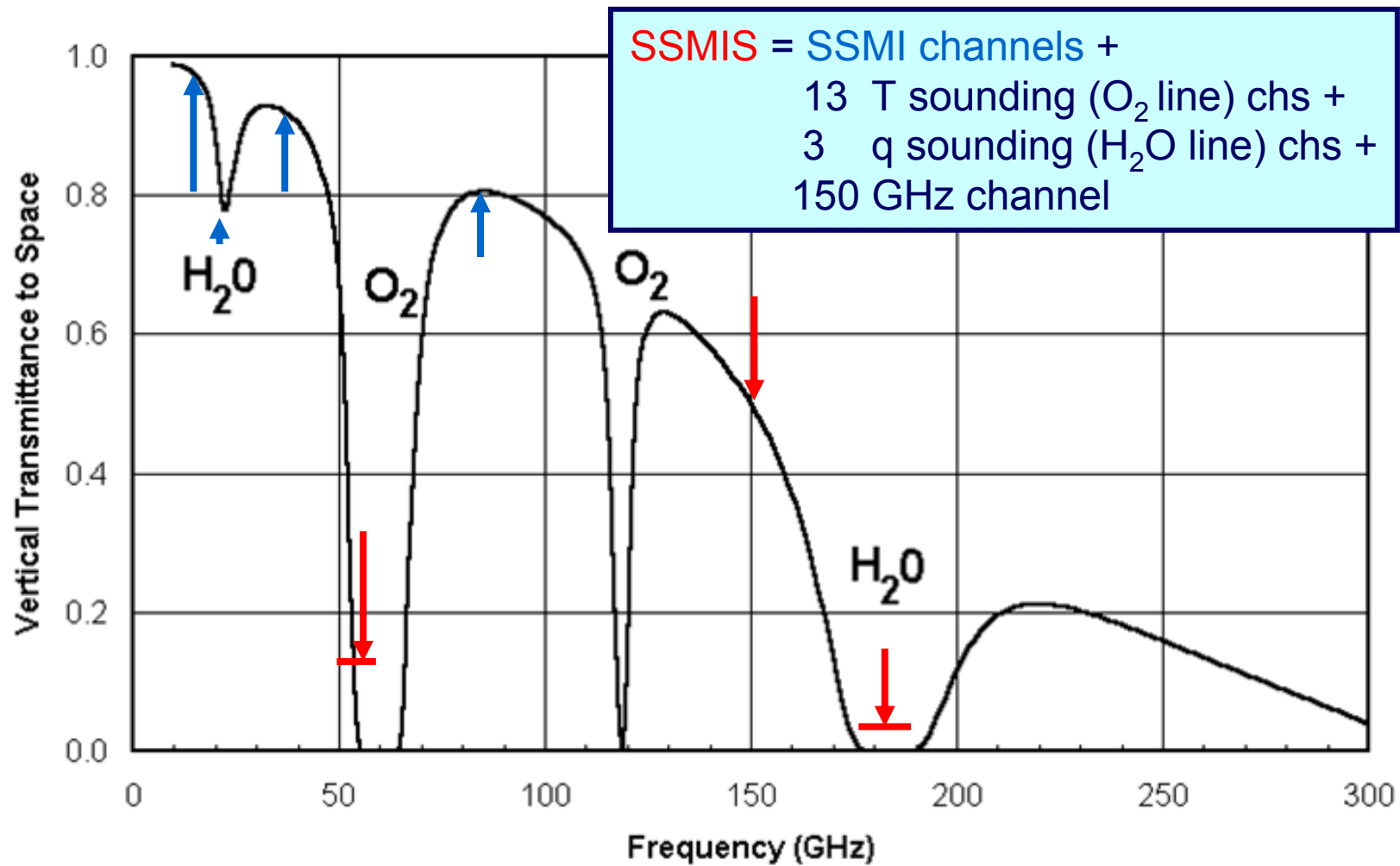
Cold Calibration Reflector

Warm Load Feedhorns

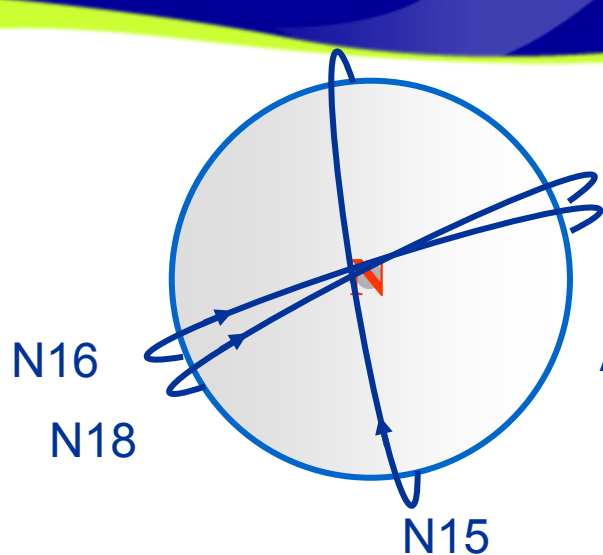


Special Sensor Microwave Imager/Sounder (SSMIS)

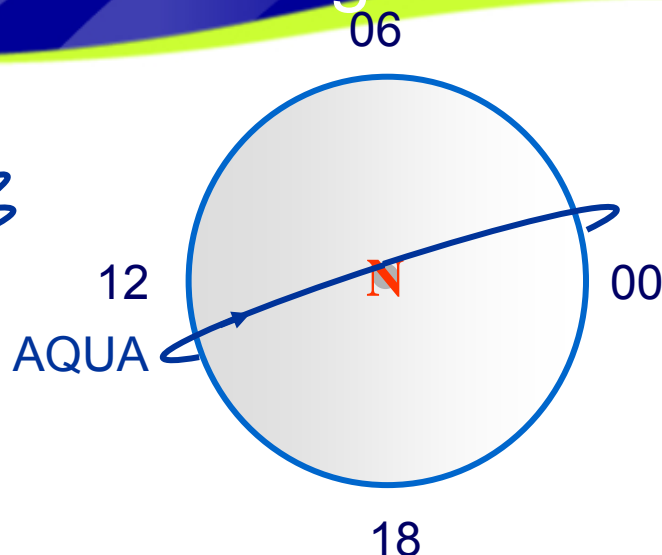
Background: SSMIS Channels



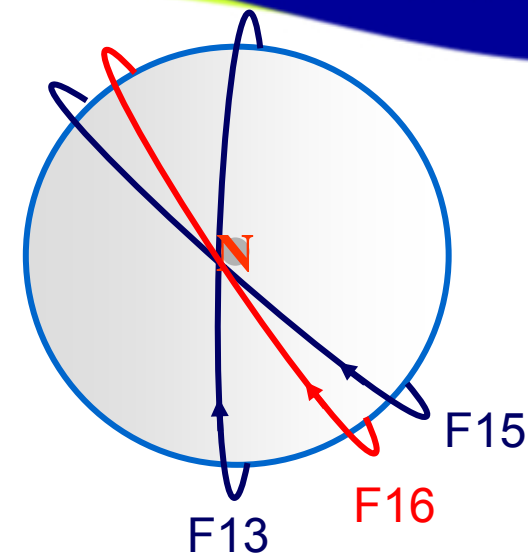
Background - orbit coverage of operationally assimilated sounders / imagers



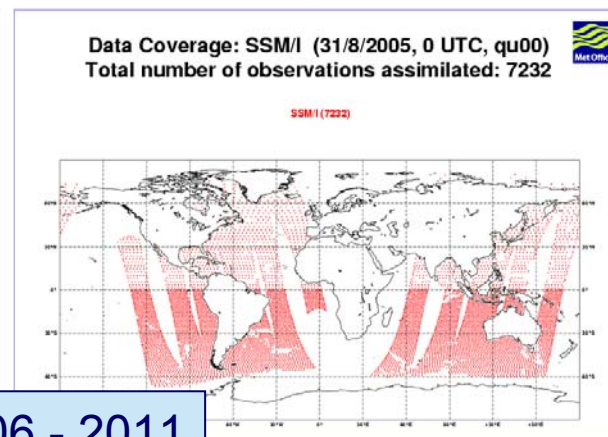
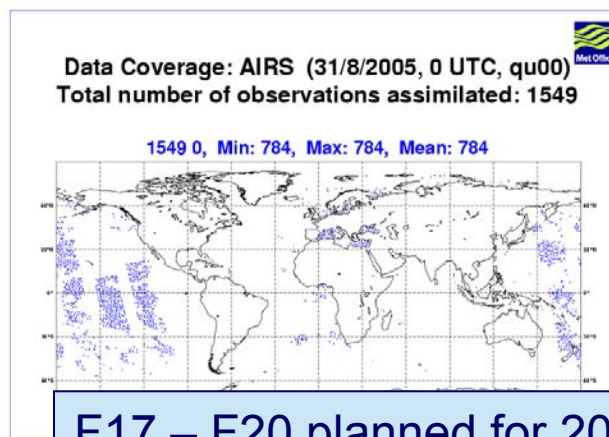
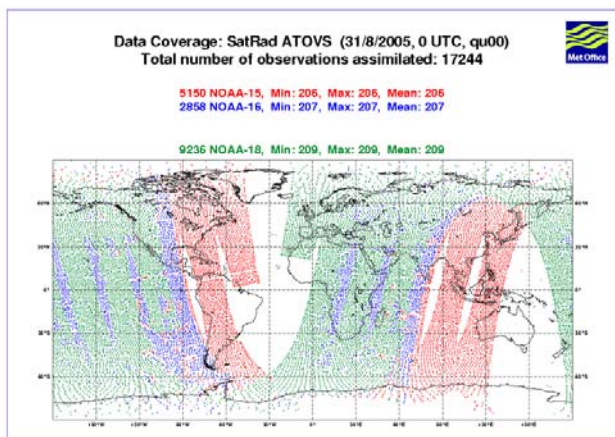
ATOVS (T & q)



AIRS (T & q)

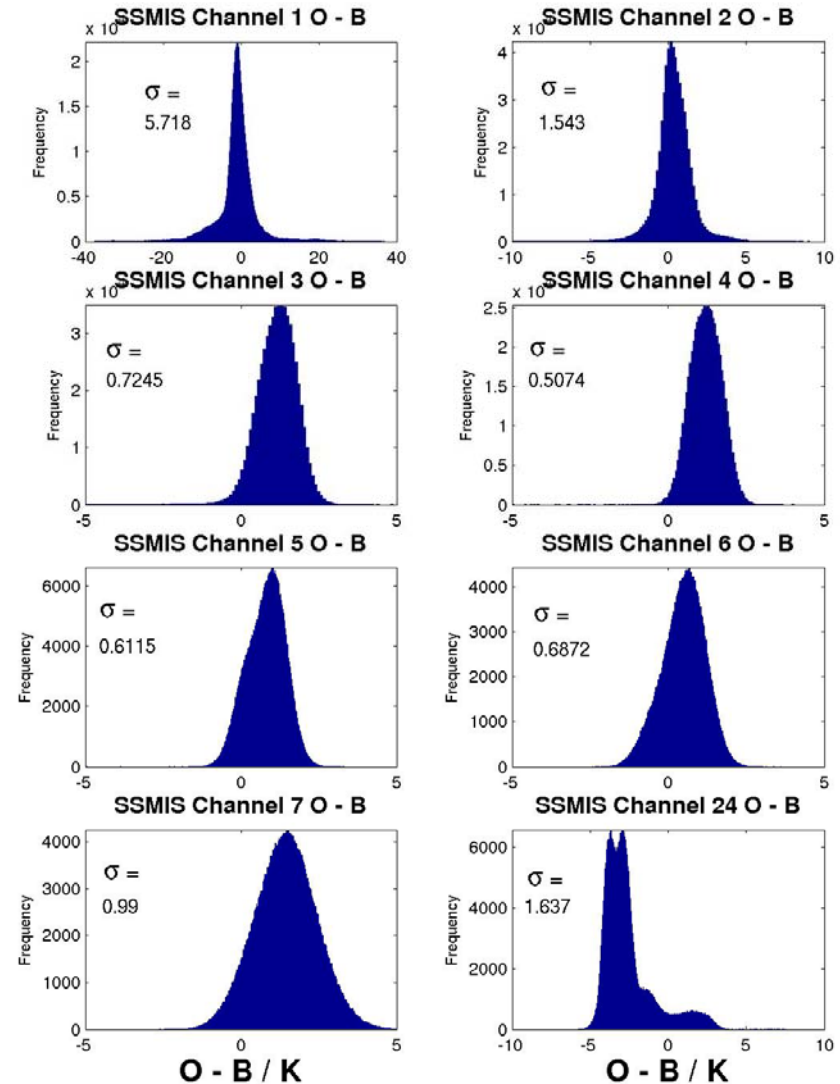
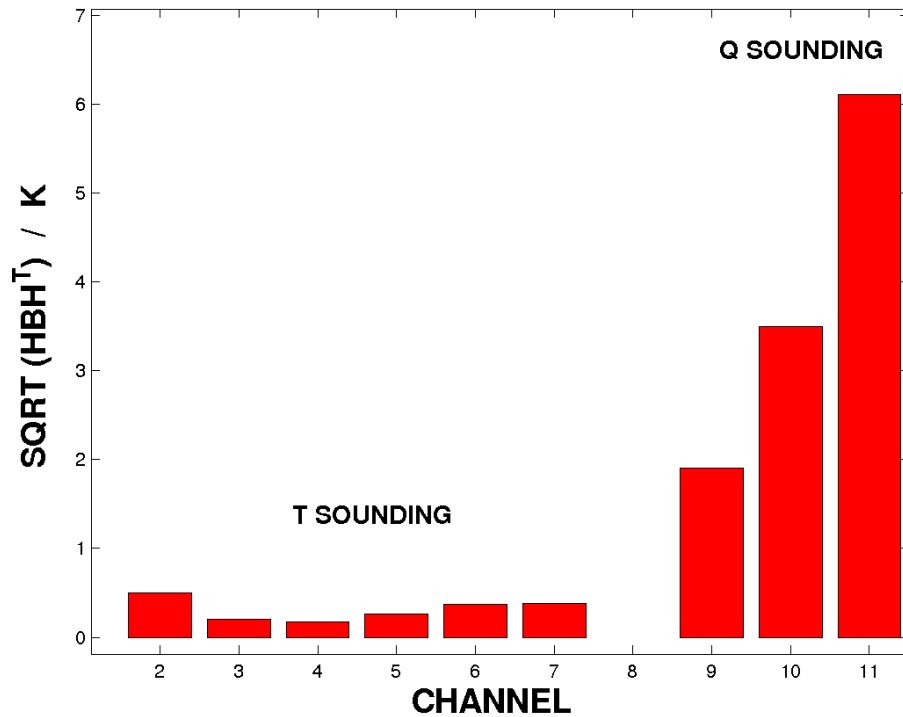


SSMI (WS)
SSMIS (T, q, WS)

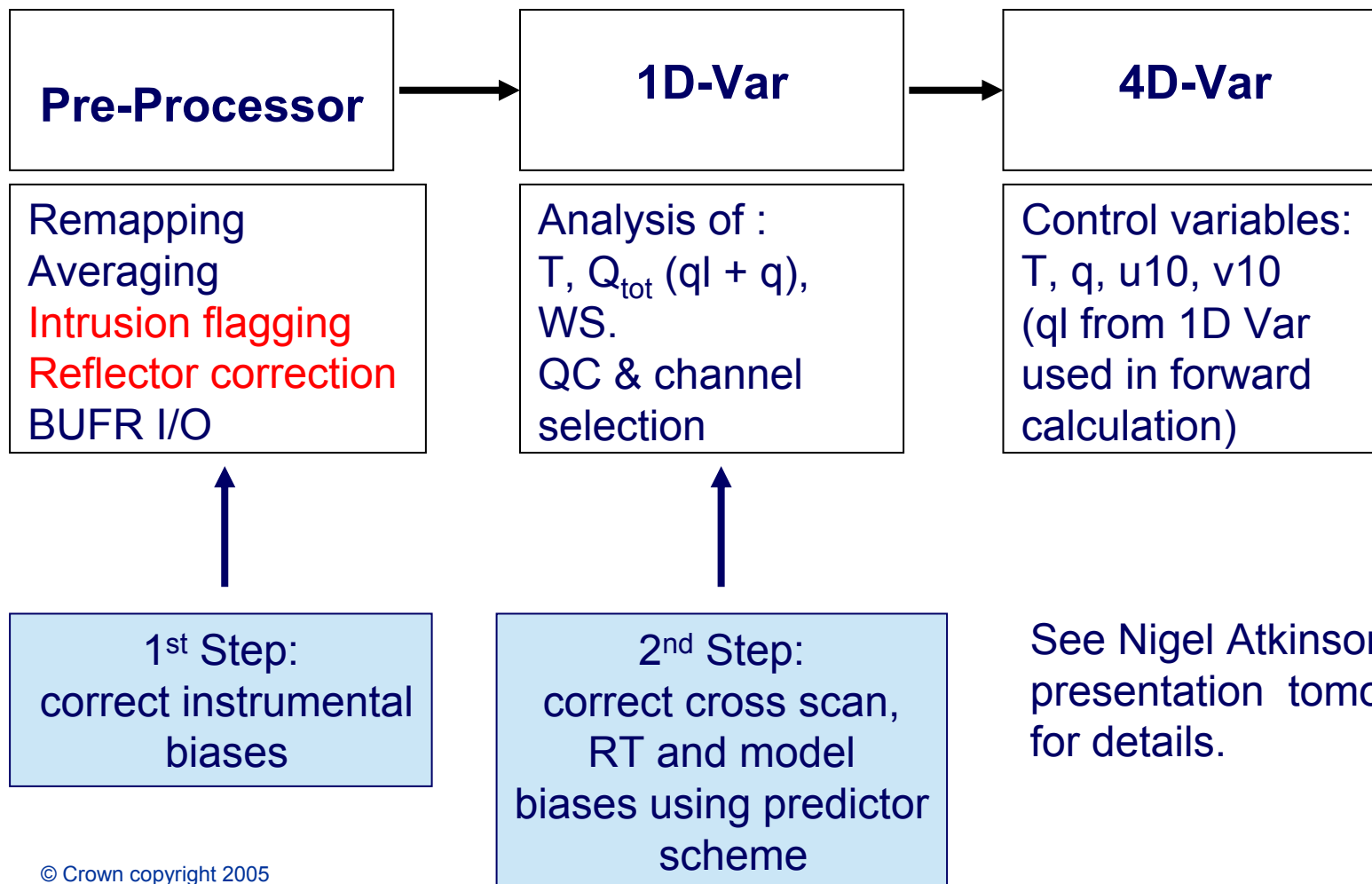


F17 – F20 planned for 2006 - 2011

Background: Accuracy Requirements and Initial Performance

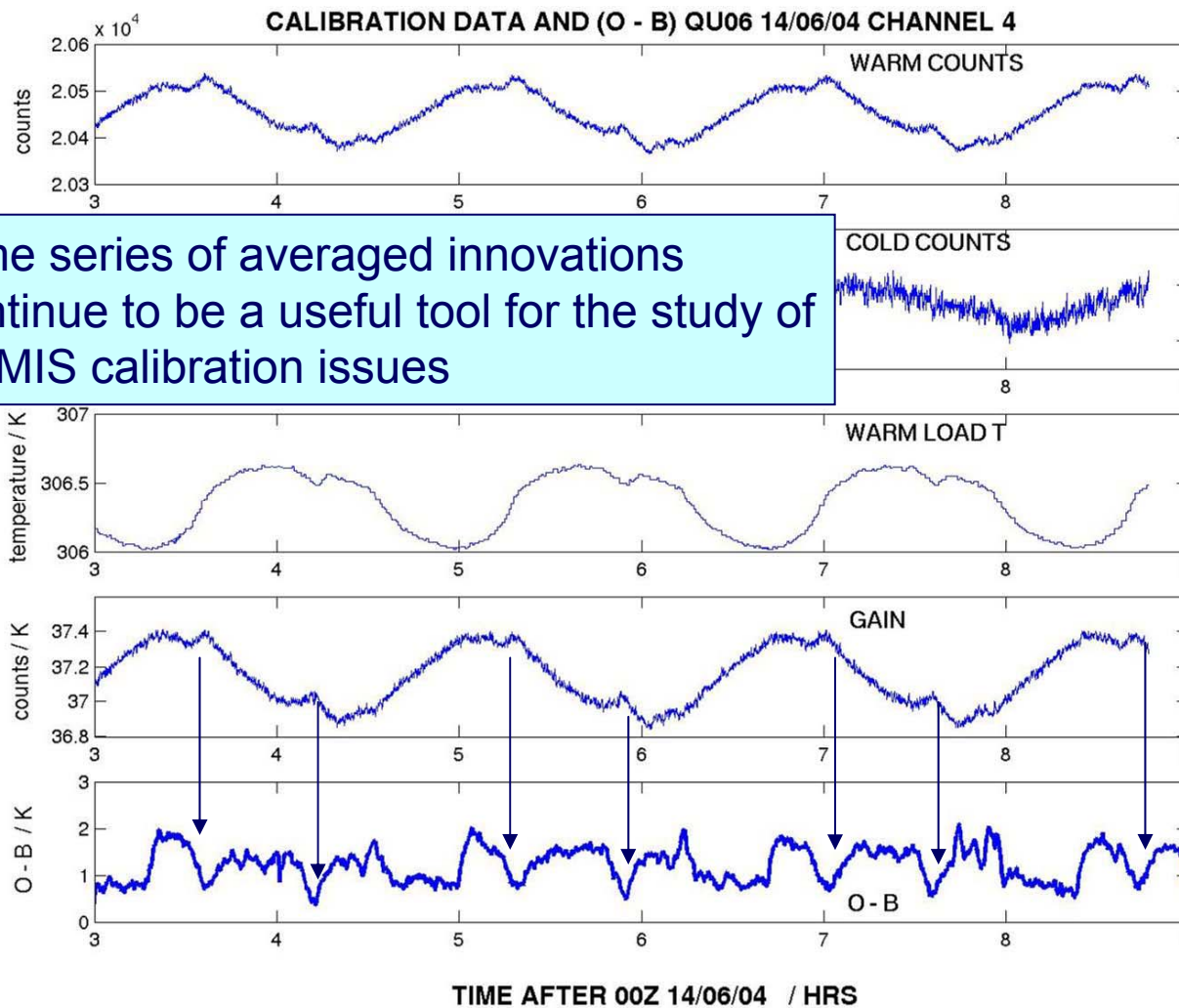


Background: two step approach to bias correction

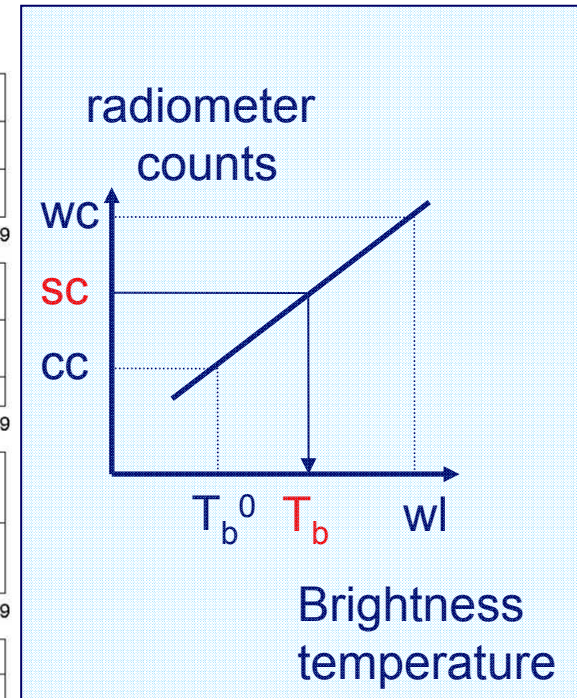


See Nigel Atkinson presentation tomorrow for details.

Instrumental Biases: warm load solar intrusions



Time series of averaged innovations continue to be a useful tool for the study of SSMIS calibration issues



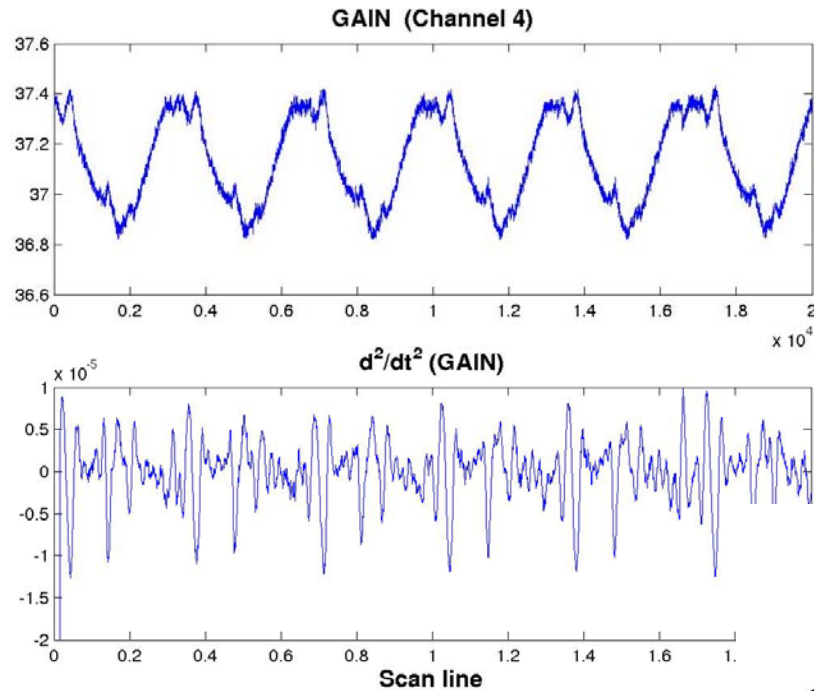
Instrumental Biases: warm load solar intrusions



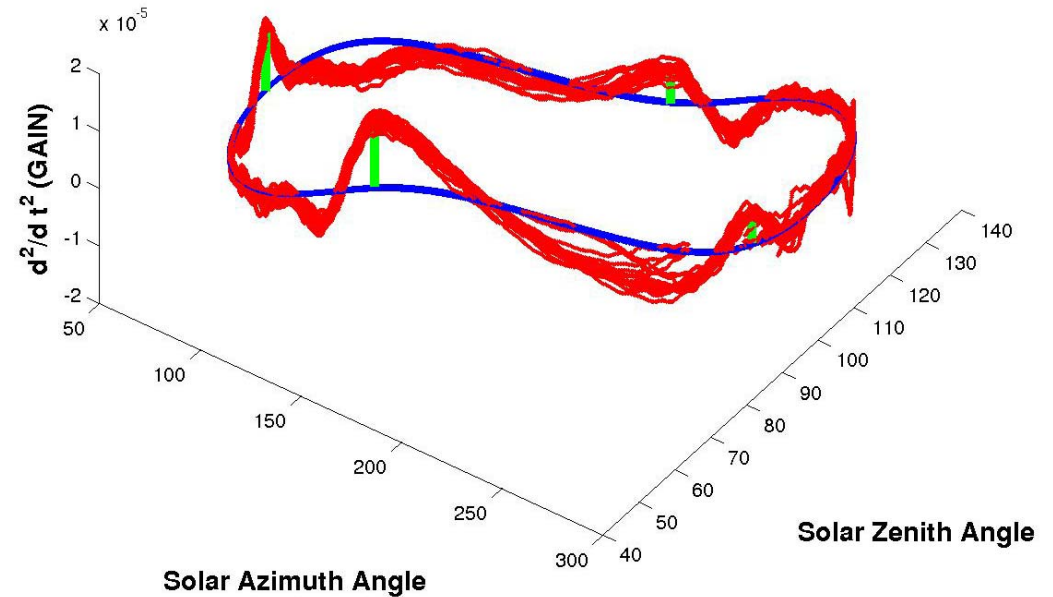
The screenshot shows the DGS Version 4.0 software interface. The main window displays a 3D model of a satellite instrument, labeled 'F16'. A white arrow points to a component on the instrument, labeled 'warm load'. A blue oval highlights a label 'Vehicle From Sun' in the top right corner. The interface includes a top menu bar with 'Views / Leonid / Satellites / Orbits / Earth / Stations / Window / DMSP_5D3 /'. On the left, there are several control panels: a top panel with sliders for 'Horizontal' (4.71) and 'Vertical' (-5.48); a 'Scale View' panel with sliders for 'Scale View' (9.86) and 'Scale Vehicles' (2.98); a 'Reset Window Scale Vehicles Exit' button; a 'Sun SSMIS' panel with 'Leo' selected; a 'Sat F16' panel with '73.1' Lat, '-136.2' Lon, and '855' Alt; a 'SSMIS Parts' panel with 'Fence' selected; a 'Sensor Beams' panel with 'M K UV W G LV Ka' selected; a 'vecs' panel with values '-35.7', '5.8', '5.3', '36.9', '123.8'; a 'sunaz sunel sunwl suncs suncl' panel; an 'IP' panel; a 'SSMIS 6.50' panel with a red 'R' button; a '280' panel; and a 'Beam Position 286.50 Scan Angle 229.20 deg' panel. The bottom of the interface shows a 3D model of the instrument with a yellow and orange component labeled 'warm load'. A blue oval highlights a label 'Vehicle From Sun' in the top right corner. A white arrow points to a component on the instrument, labeled 'warm load'. A blue oval highlights a label 'Vehicle From Sun' in the top right corner.

Visualisation Software (DGS)
Mike Warner, Aerospace Corp.

Offline signal processing to detect solar intrusions / gain anomalies



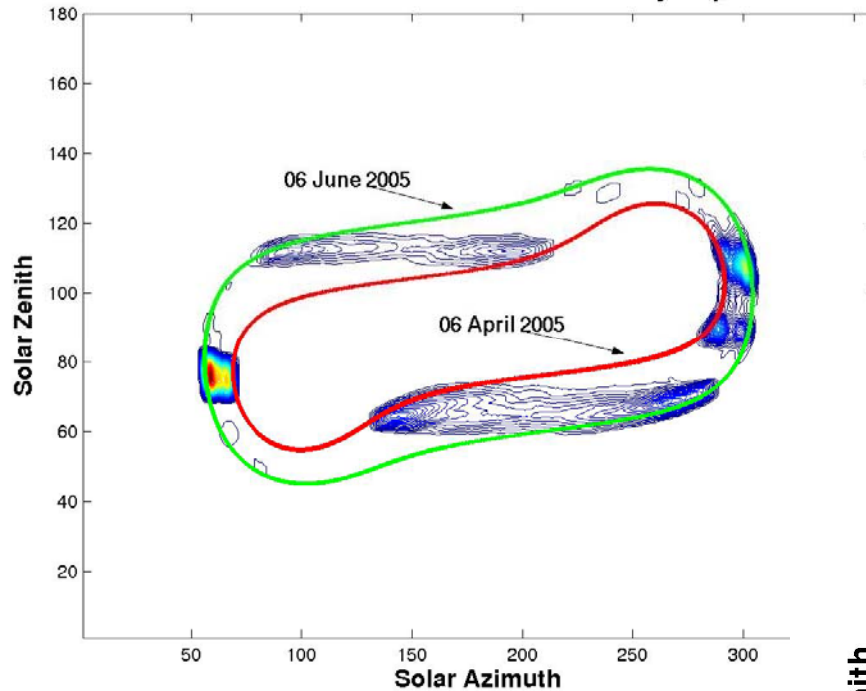
2nd derivative of gain wrt time plotted as a fn of local solar zenith/azimuth angle



Solar intrusion map



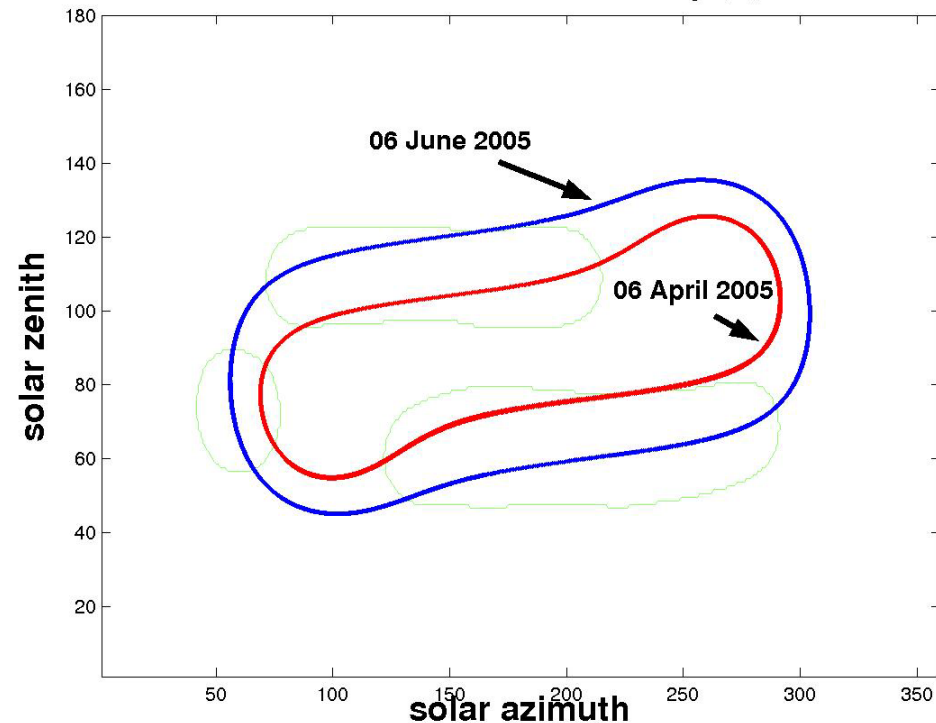
SSMIS Solar Intrusion / Gain anomaly map



Final map produced by 2D convolution of original map with gaussian – to account for temporal extent of intrusions



SSMIS solar intrusion map (5)



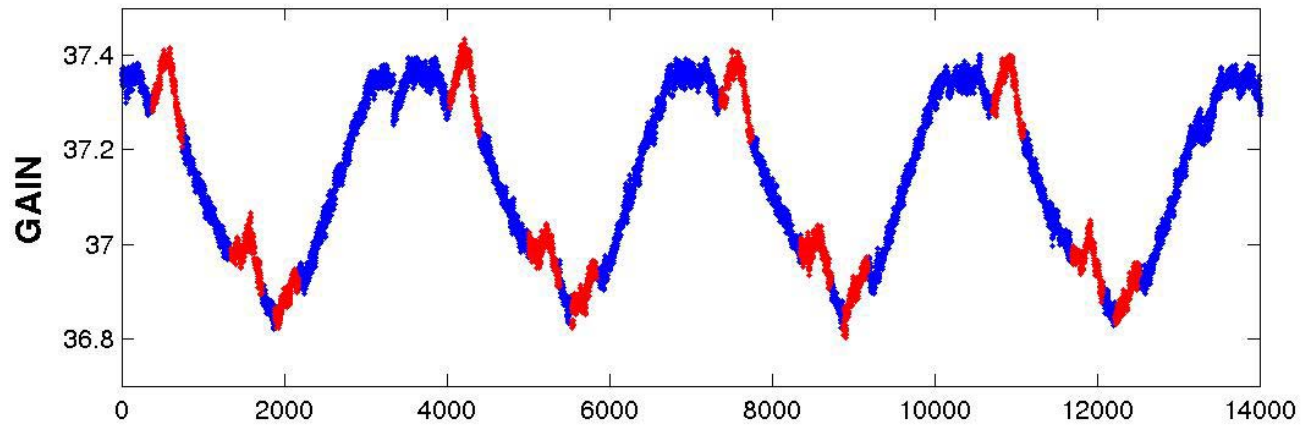
Map is 2D array (360×180) of 0's & 1's, indexed by az , zen

Should be complete after 1 year (assuming orbit stable) ?

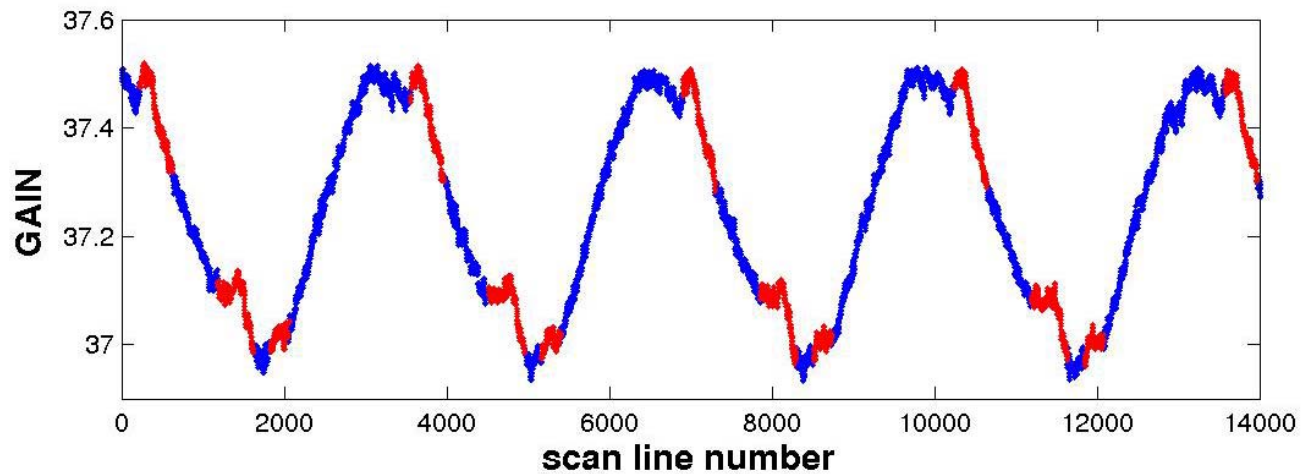
Performance: April – June 2005



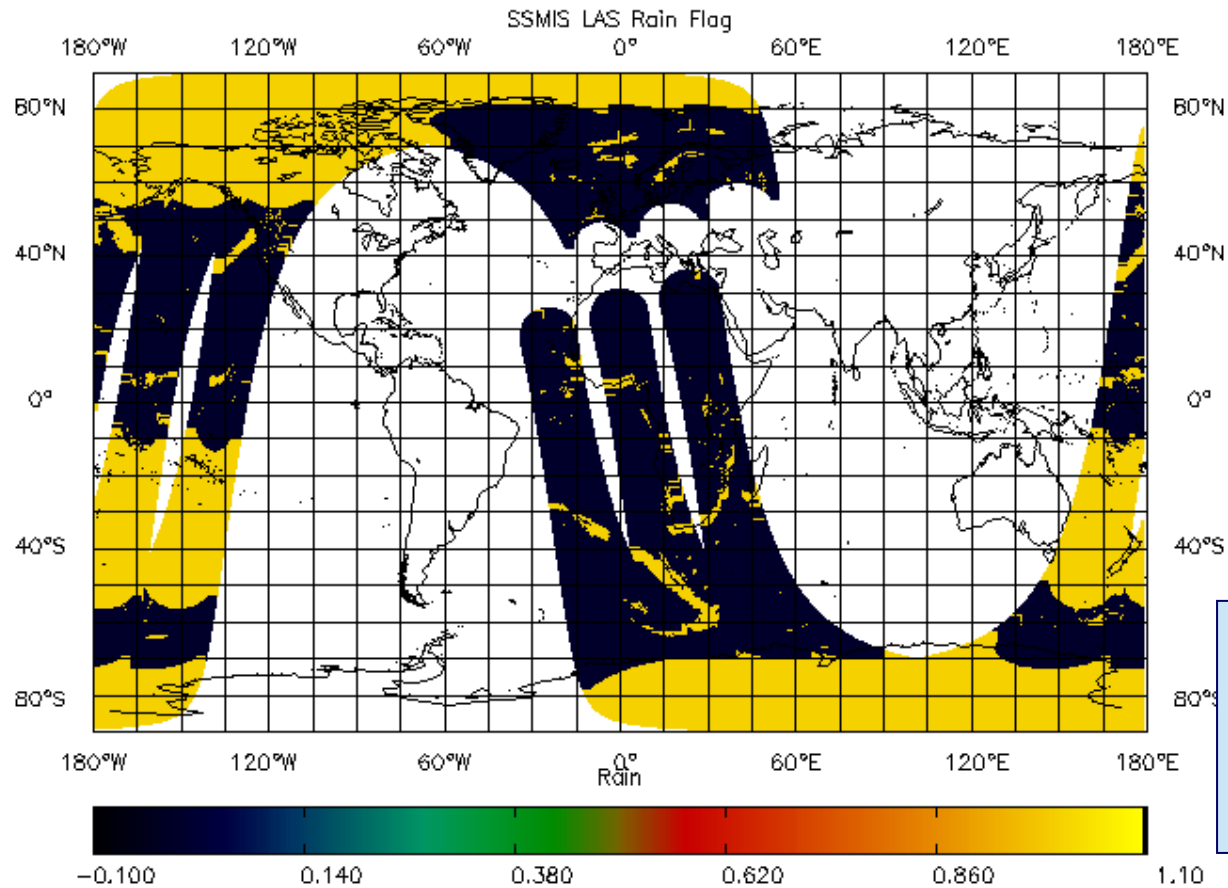
05/04/05



01/06/05

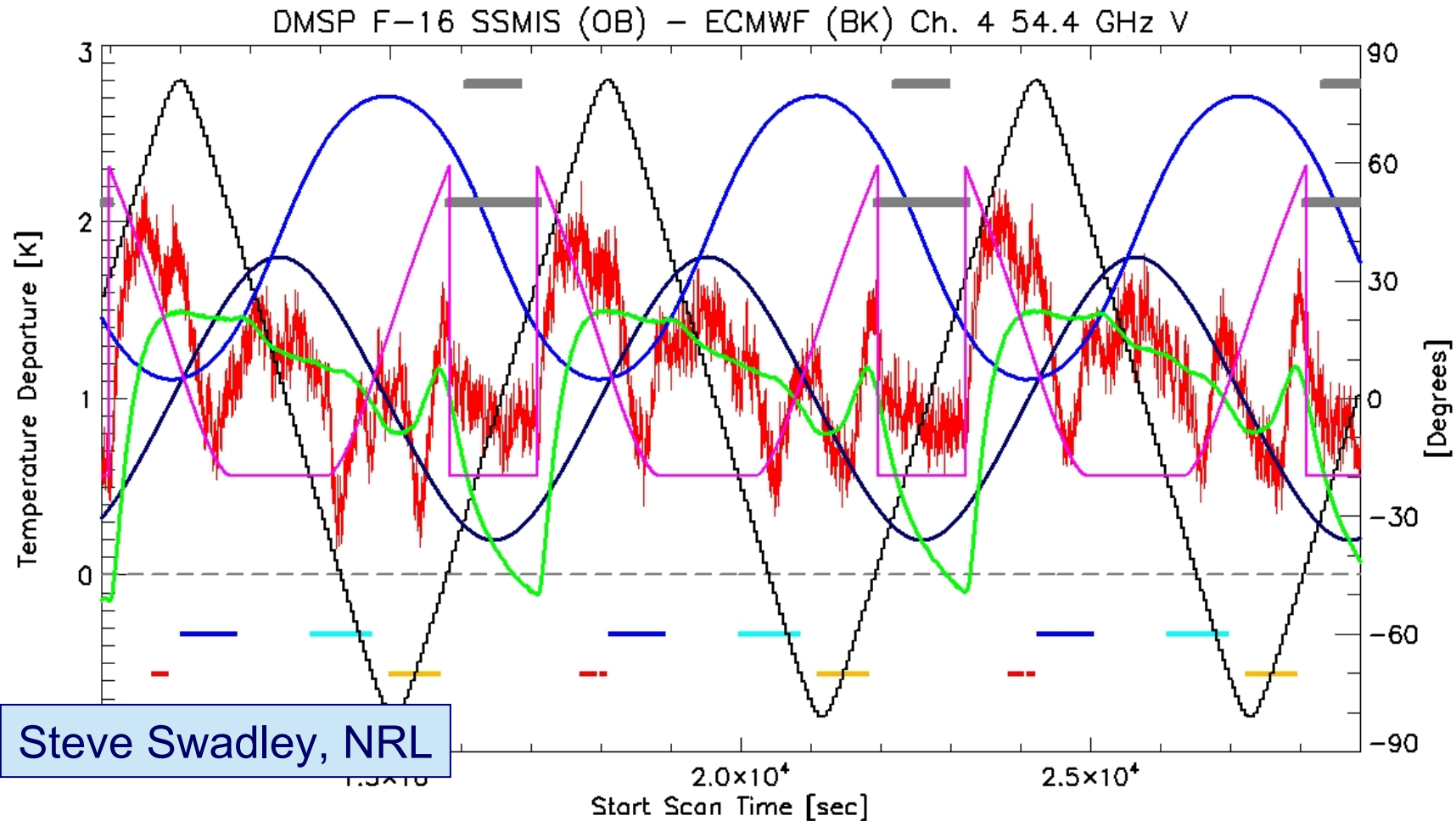


Intrusion flagging: coverage



Yellow : rejected
Black: OK
(30 - 40% data flagged)

Gain Correction using Fourier Filtering: no correction



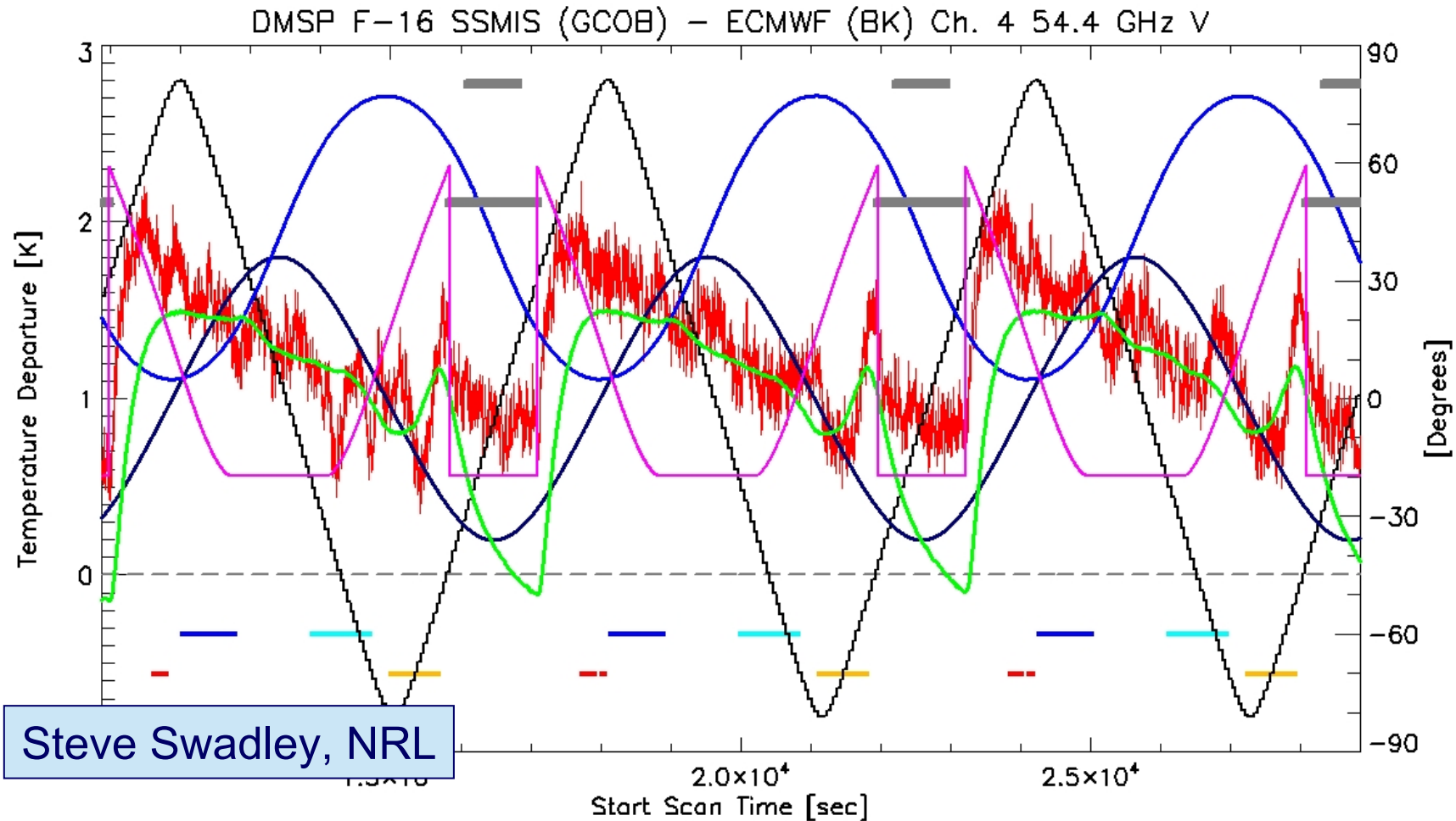
DTG: 2005100406
TDR Revs: 10121-10123

OB-BK
Lat Elevation

T_Rflct_Arm
Azimuth

T_Rflct
Shadow

Gain Correction using Fourier Filtering: corrected



DTG: 2005100406
TDR Revs: 10121-10123

OB-BK
Lat Elevation

T_Rflct_Arm
Azimuth

T_Rflct
Shadow

Reflector Emission: entering Earth shadow



Reflector Emission: emerging from Earth shadow



DGS Version 4.0

Views / Leonid / Satellites / Orbits / Earth / Stations / Window / DMSP_5D3 /

F16 Vehicle From Sun

Horizontal Vertical

Scale View

Reset Window Scale Vehicles Exit

Oct 4 2005 00:00:0.0 2005277 Frame 487

Step Refresh ELT 1:21:10

10 sec No Limit UTC 01:21:10

Sun SSMIS Leo

Sat F16 32.4 -82.7 846
Lat Lon Alt

SSMIS Parts Can Calh Dish Fence C

Sensor Beams M K UV W G LV Ka

-23.9 -27.9 17.1 16.7 99.3 vecs
sunaz sunel sunwl suncs suncl

IP

SSMIS 6.50 R

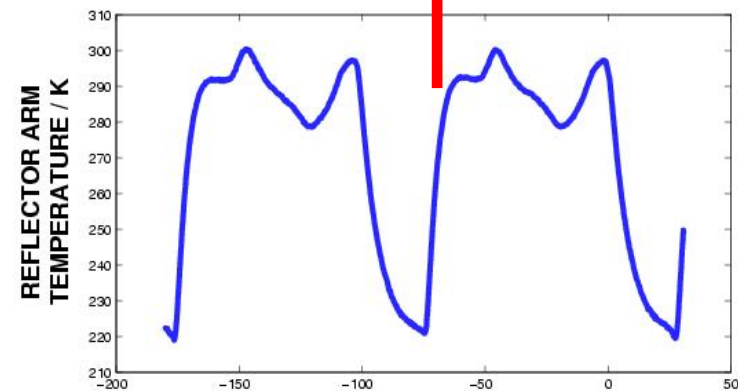
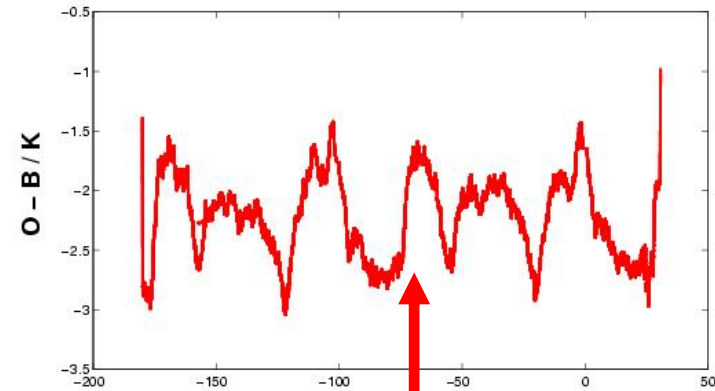
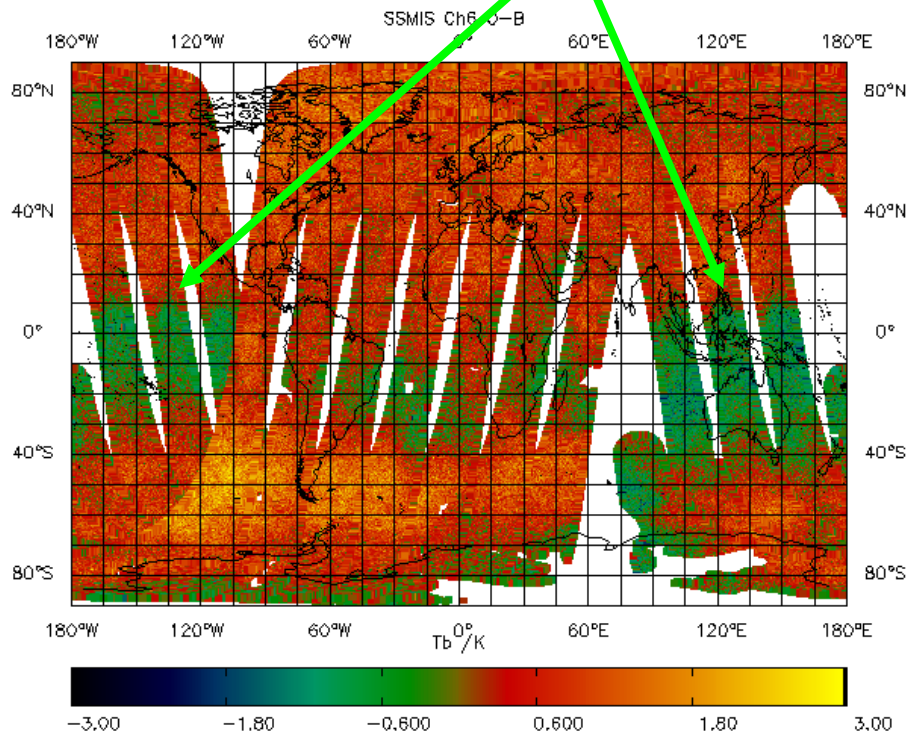
220

Beam Position 226.50 Scan Angle 181.20 deg

Reflector emission

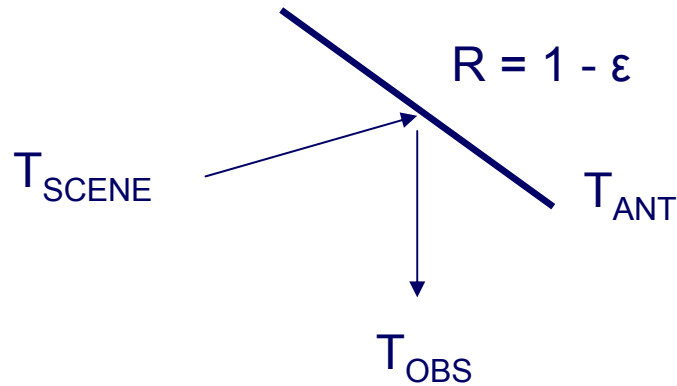


Problems in ascending node
not evident in descending node



TIME RELATIVE TO 18Z 06/06/05 / mins

Reflector emission correction



$$T_{obs} = (1 - \epsilon)T_{scene} + \epsilon T_{ant}$$

$$T_{scene} = \frac{T_{obs} - \epsilon T_{ant}}{(1 - \epsilon)}$$

Compute tolerable errors in ϵ and T_{ANT} ($\Delta\epsilon$ & ΔT_{ANT}) given tolerable errors in T_{SCENE} (ΔT_{SCENE})

$$\Delta\epsilon = \Delta T_{scene} \left[\frac{\partial T_{scene}}{\partial \epsilon} \right]^{-1}$$

$$\Delta T_{ant} = \Delta T_{scene} \left[\frac{\partial T_{scene}}{\partial T_{ant}} \right]^{-1}$$

Required accuracy in estimate of antenna emissivity and temperature



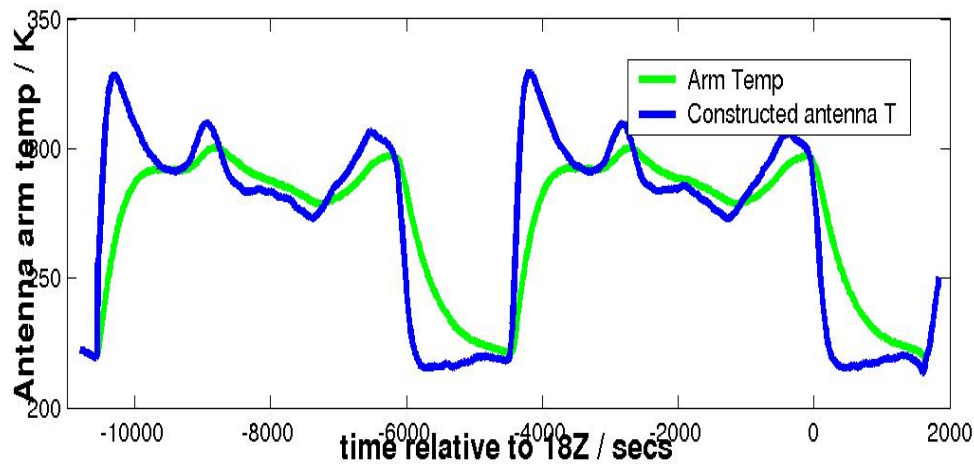
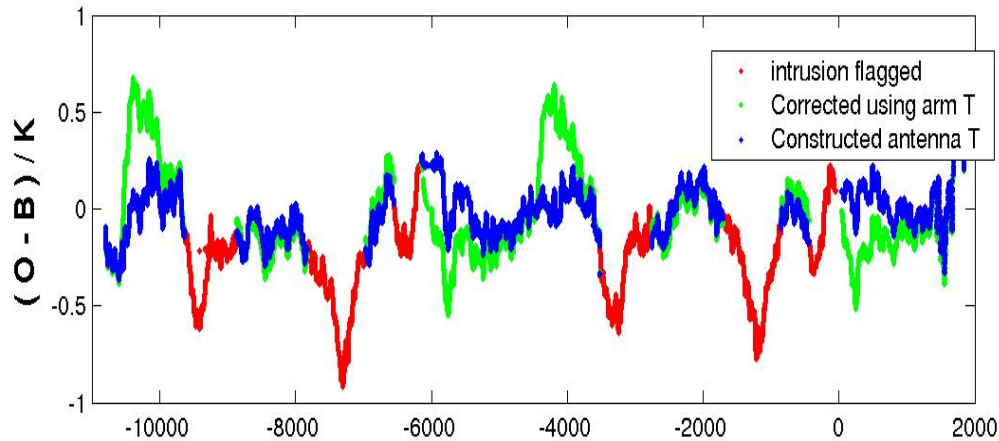
Ch #	pol	ΔT_{scene} /K	ϵ_{nom}	$\Delta \epsilon$	ΔT_{ant} /K
1 - 5	V	0.1	0.01	0.0008	10
6,7,19-24	RC	0.1	0.02	0.0010	5
9 - 11	H	0.5	0.04	0.0060	12
12 - 16	V/H	0.5	0.00	N/A	N/A

⇒ Require T_{ANT} to be accurate to 5K and emissivity estimates to be good to ~ 0.0008 for T sounding channels to keep T_{SCENE} errors below 0.1K

SSMIS – antenna emission correction using constructed antenna T



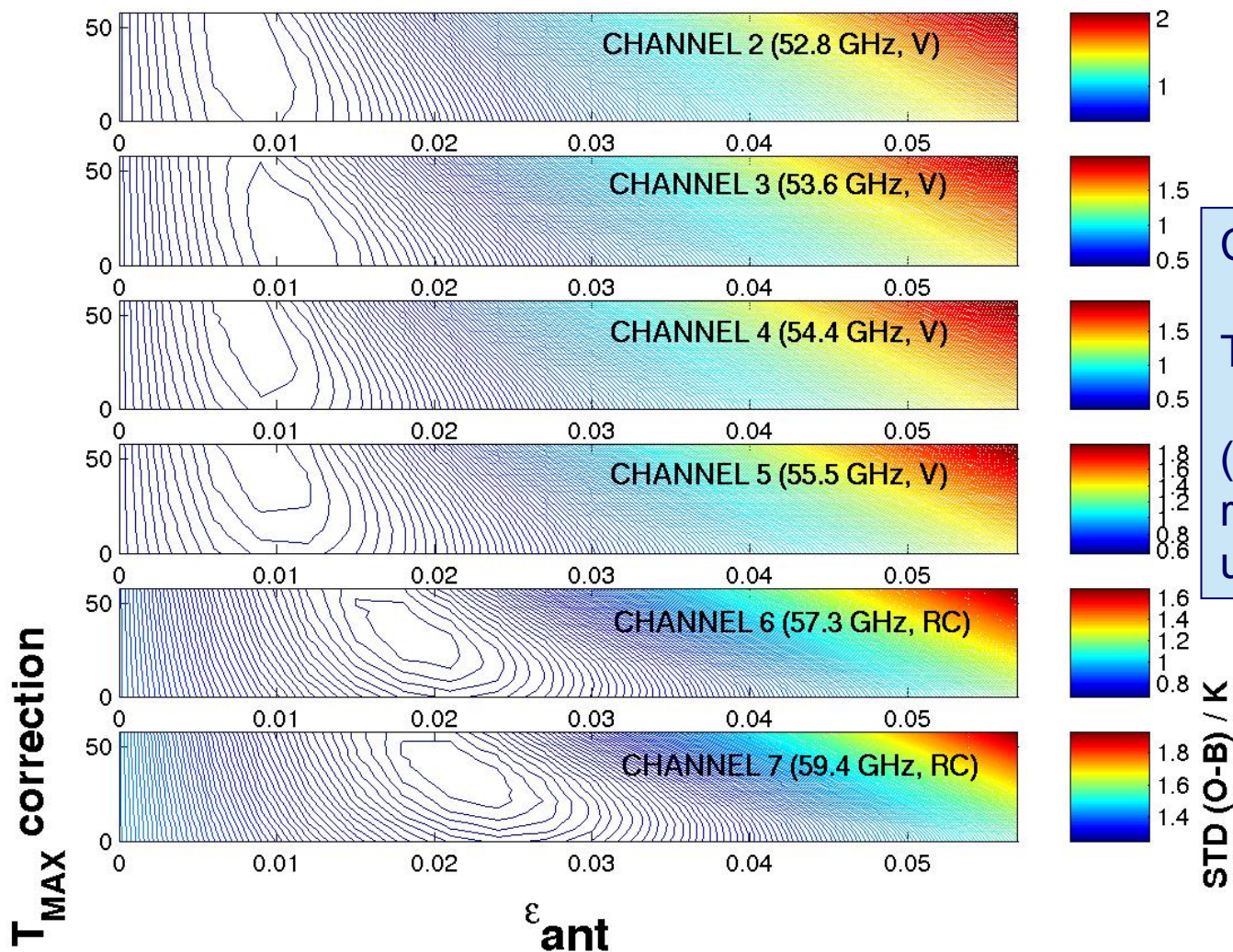
AVERAGED INNOVATIONS QU18 06/06/05



$$T_{ant}(t) = T_{arm}(t) + c_1 \frac{dT_{arm}}{dt}$$

$$T_{ant}(t) = T_{arm}(t) + c_1 \int_0^T c_2 e^{-\tau/\sigma} \frac{dT_{arm}}{dt}(t - \tau) d\tau$$

Characterising T_{ANT} & ϵ : Chs 2 – 7



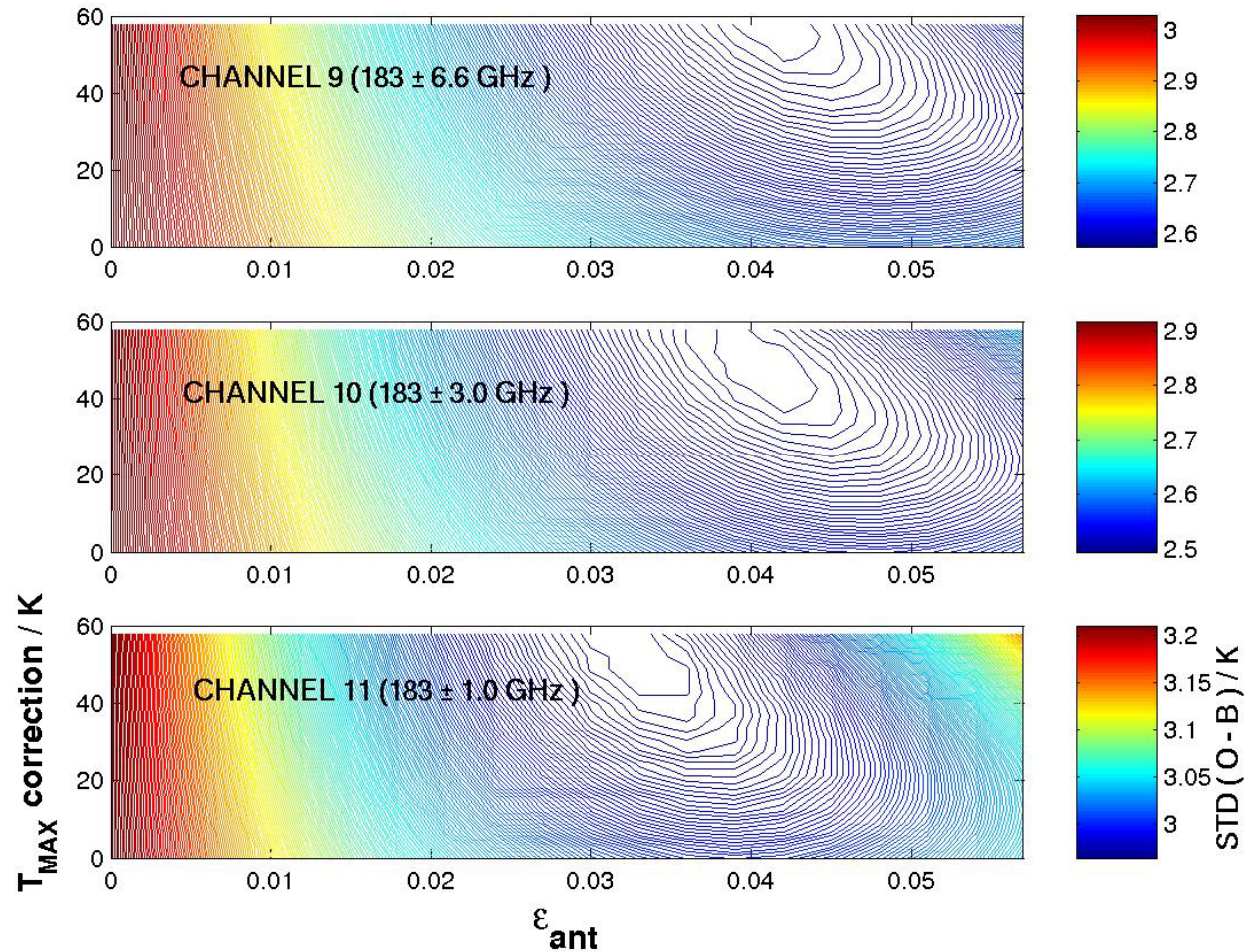
Ch 1 - 5 : $\epsilon = 0.01$
 6,7 : $\epsilon = 0.02$
 $T_{corr} = 30 - 40$ K

(effectively calibrating reflector emissivity using NWP T fields!?)

Characterising T_{ANT} & ϵ : Chs 9 - 11



QU18 08/06/05

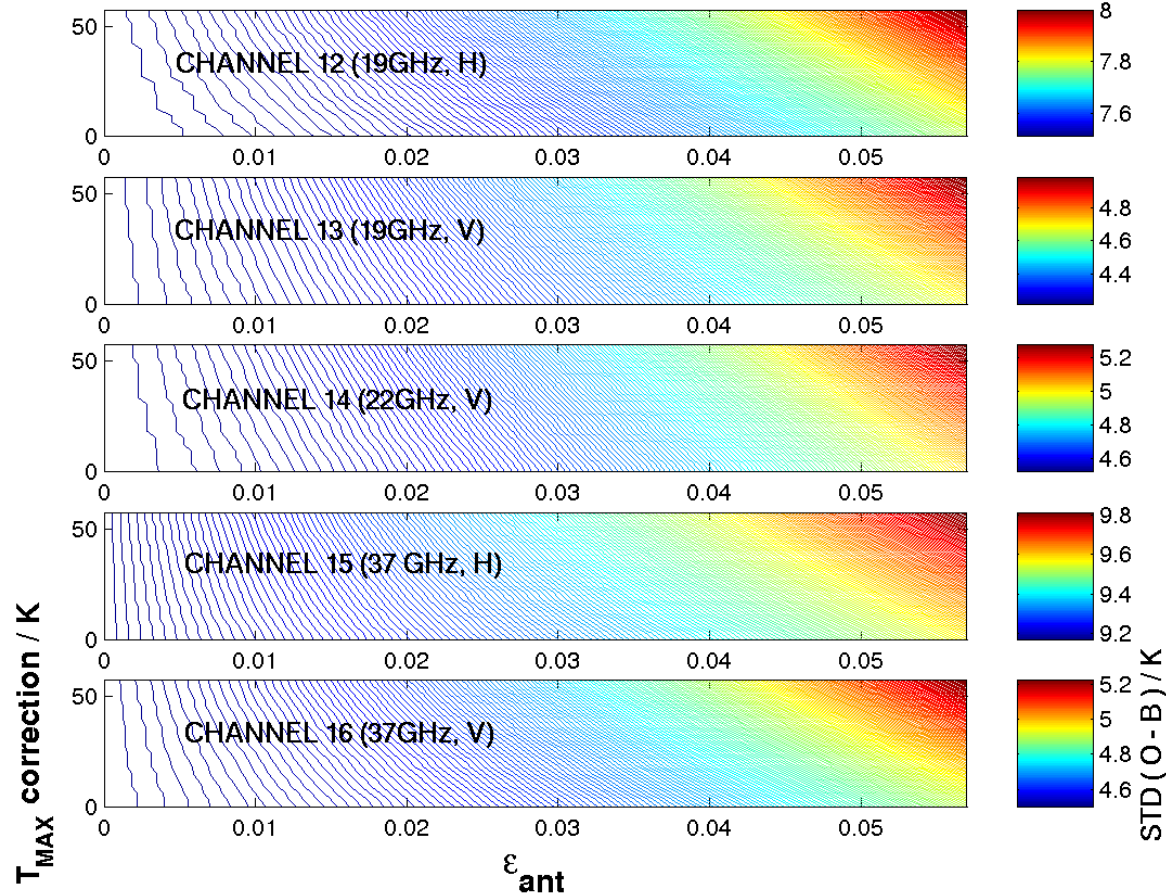


Determination of ϵ and T less Precise due to larger uncertainties in NWP q fields

Characterising T_{ANT} & ϵ : Chs 12 - 16

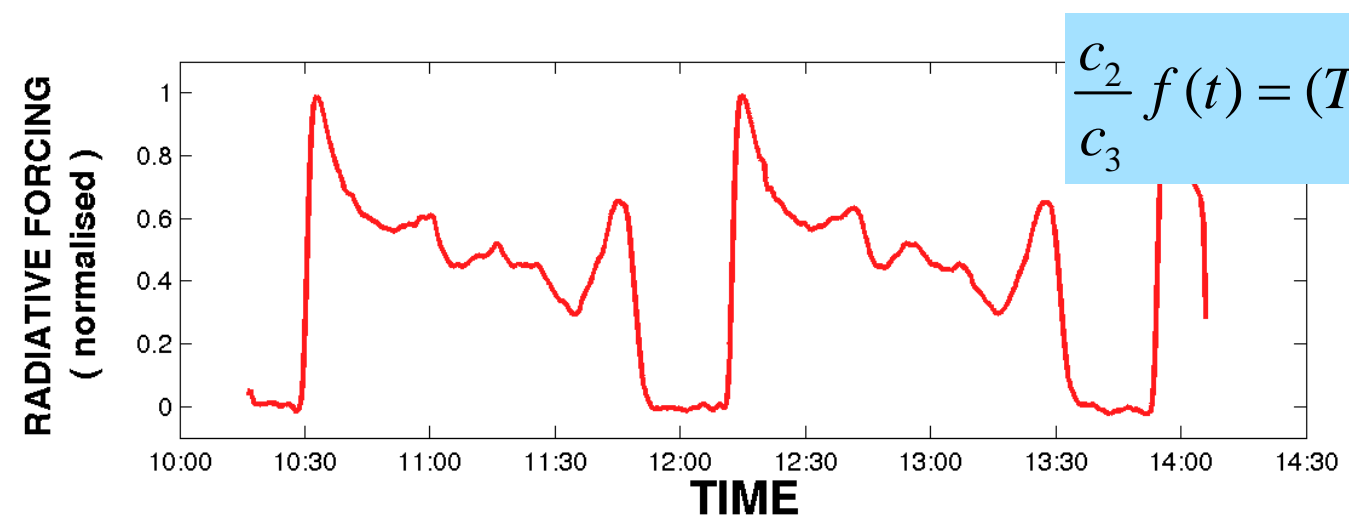
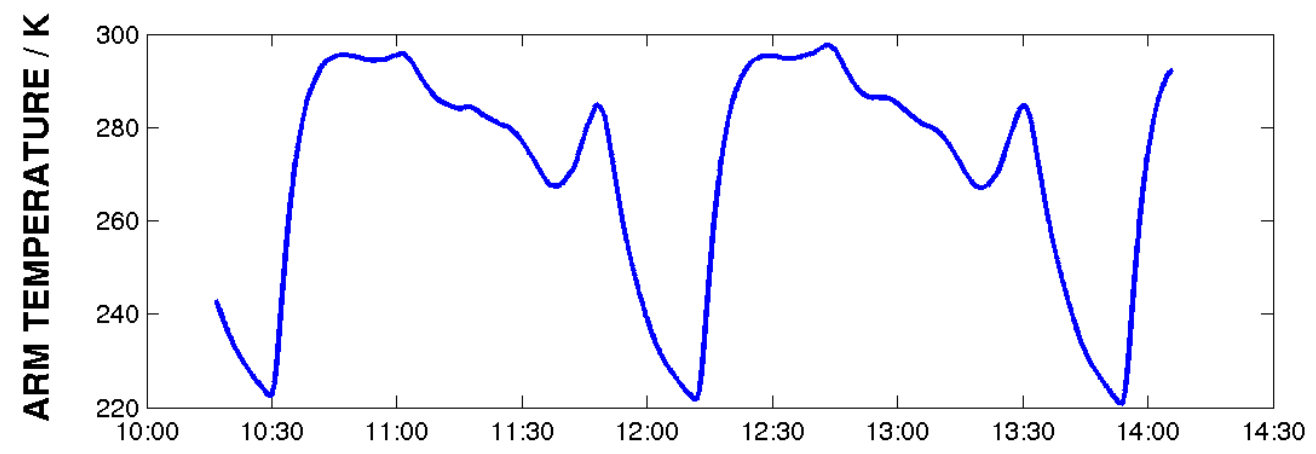


QU18 08/06/05



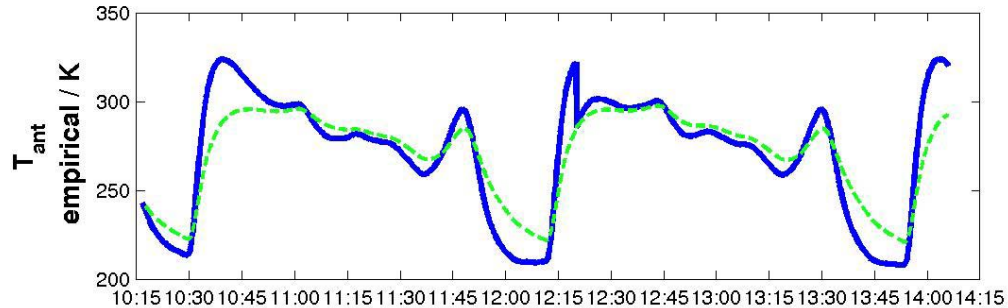
$\epsilon = 0$
(ie reflector emissivity shouldn't be a problem for SSMI like - channels)

Physical basis for empirical reflector correction (2)



$$\frac{c_2}{c_3} f(t) = (T_{arm} - T_0) + \frac{c_1}{c_3} \frac{\partial T_{arm}}{\partial t}$$

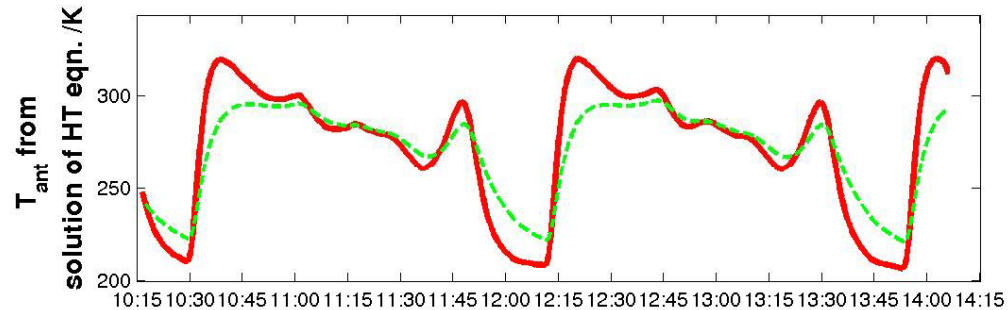
Physical basis for empirical reflector correction (3)



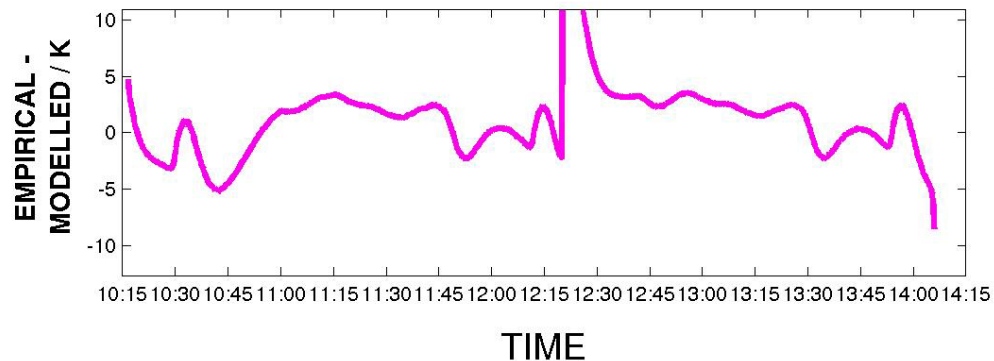
$$T_{ant}(t) = T_{am}(t) + c_1 \int_0^T c_2 e^{-\tau/\sigma} \frac{dT_{am}}{dt}(t-\tau) d\tau$$

Assuming reflector cools conductively, $T_{ant}(t)$ can be obtained from the solution of :

$$\frac{\partial T_{ant}}{\partial t} = a_1 f(t) - a_2 (T_{ant} - T_0)$$

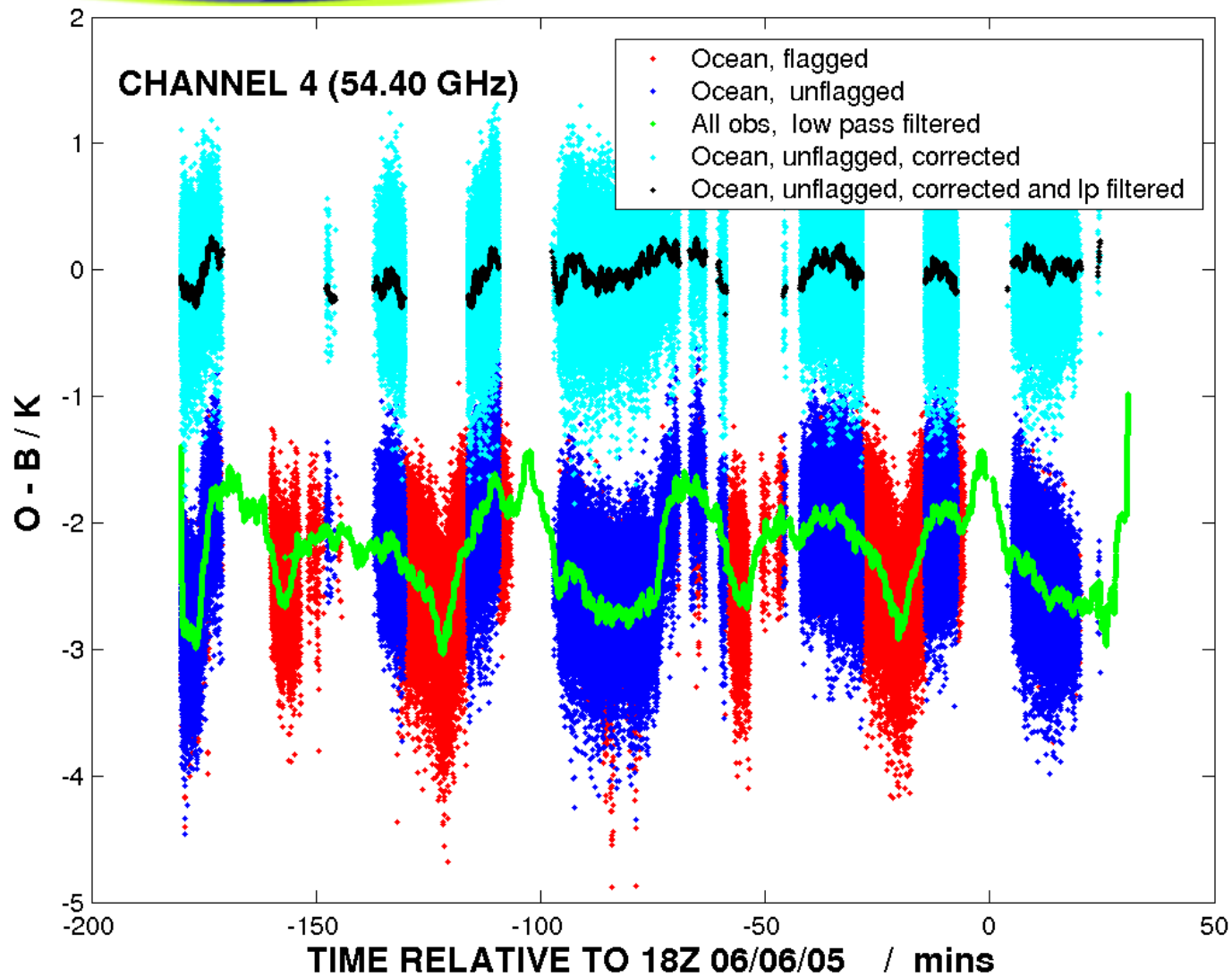


← Difference usually < 5K



Need to check a_1 and a_2 (fitted) are plausible given thermal properties of main reflector

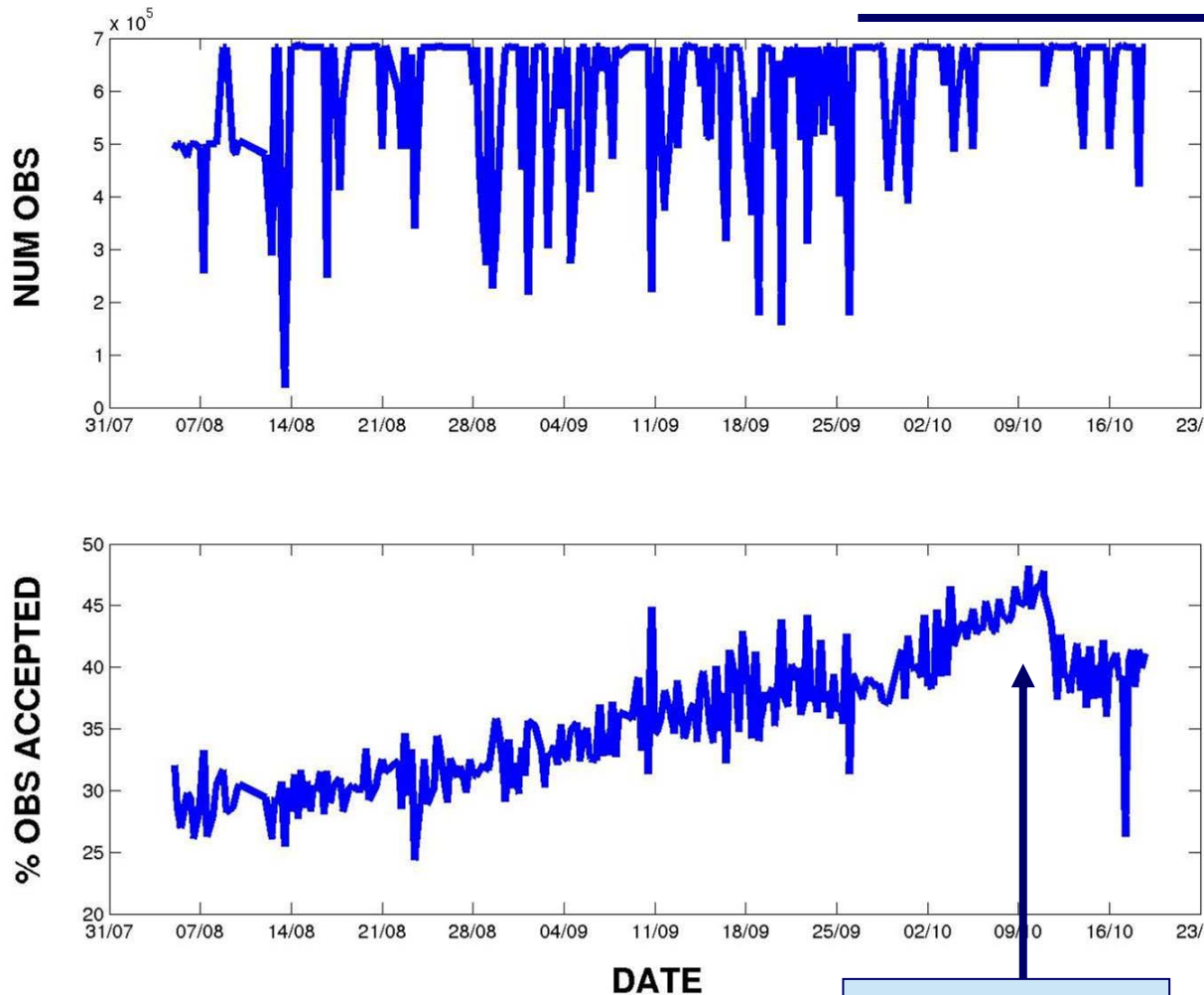
Performance of reflector emission correction



Monitoring Data from 00,06,12 & 18 Z cycles



Better handling of duplicate orbits



Typically, in 1D Var :

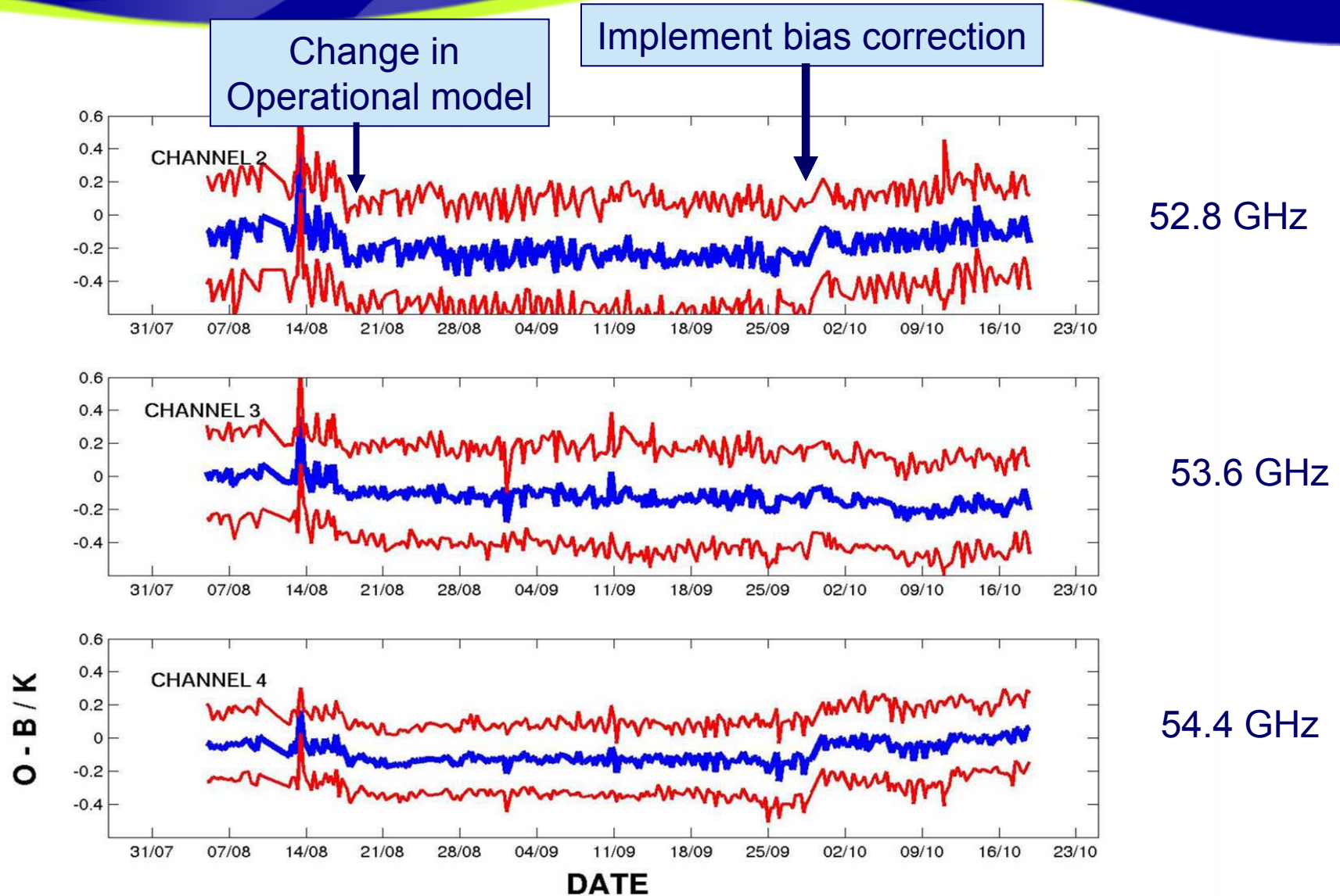
- 48 % are rain or intrusion flagged
- 8 % don't converge
- 2% bad background
- <1% fail in rttov, or fail gross O-B check

ie 58 % rejected at 1D Var step.

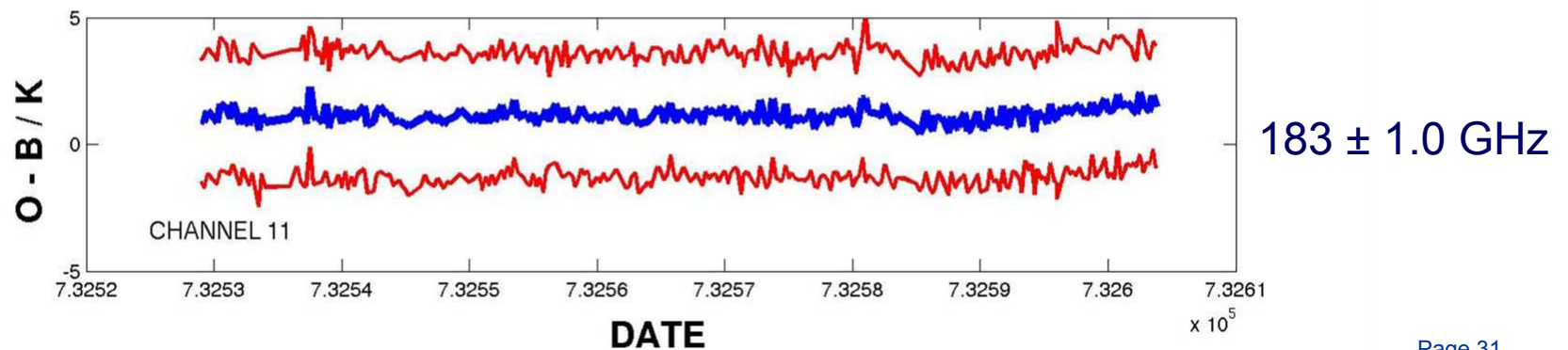
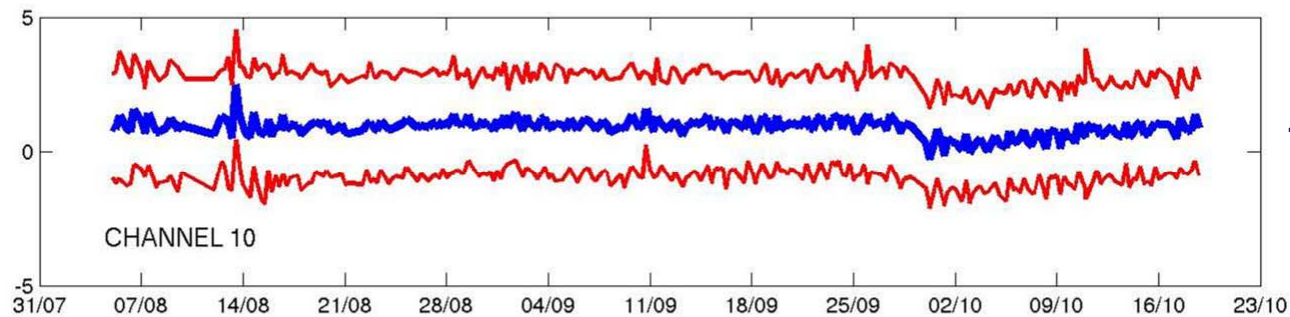
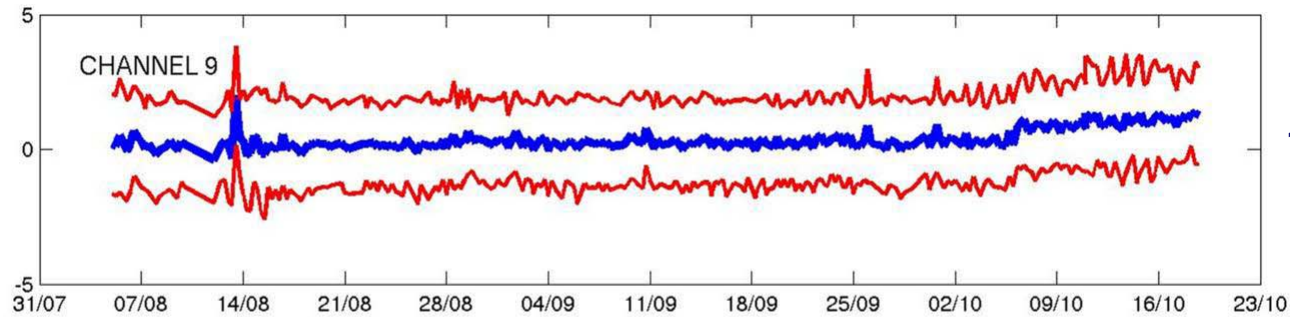
Further rejections in 4D Var based on retr LWP

Modified intrusion map

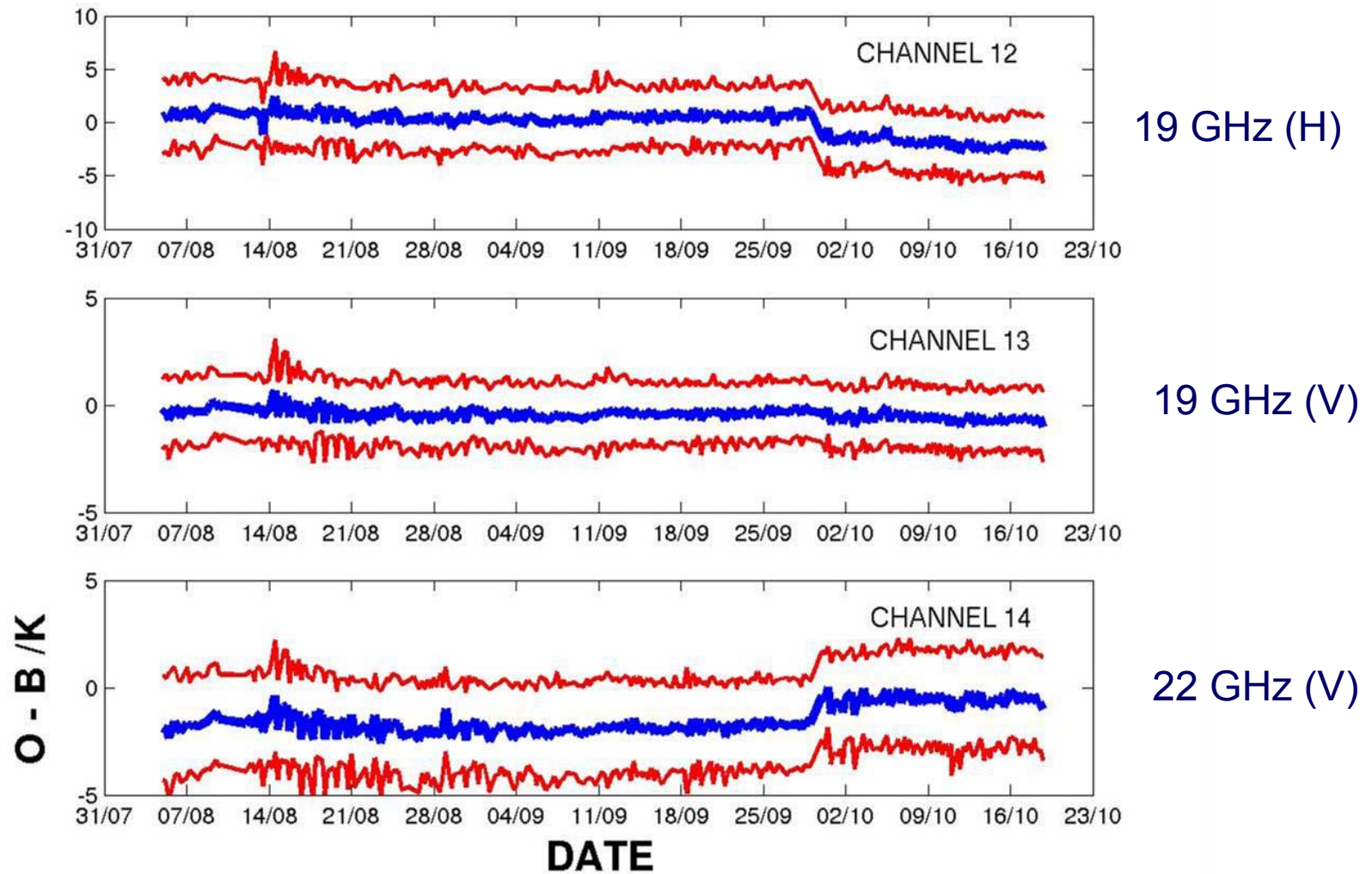
Radiance monitoring: LAS channels 2,3 & 4



Radiance monitoring: IMA channels 9,10 & 11



Radiance monitoring: ENV channels 12,13 & 14



Analysis increments



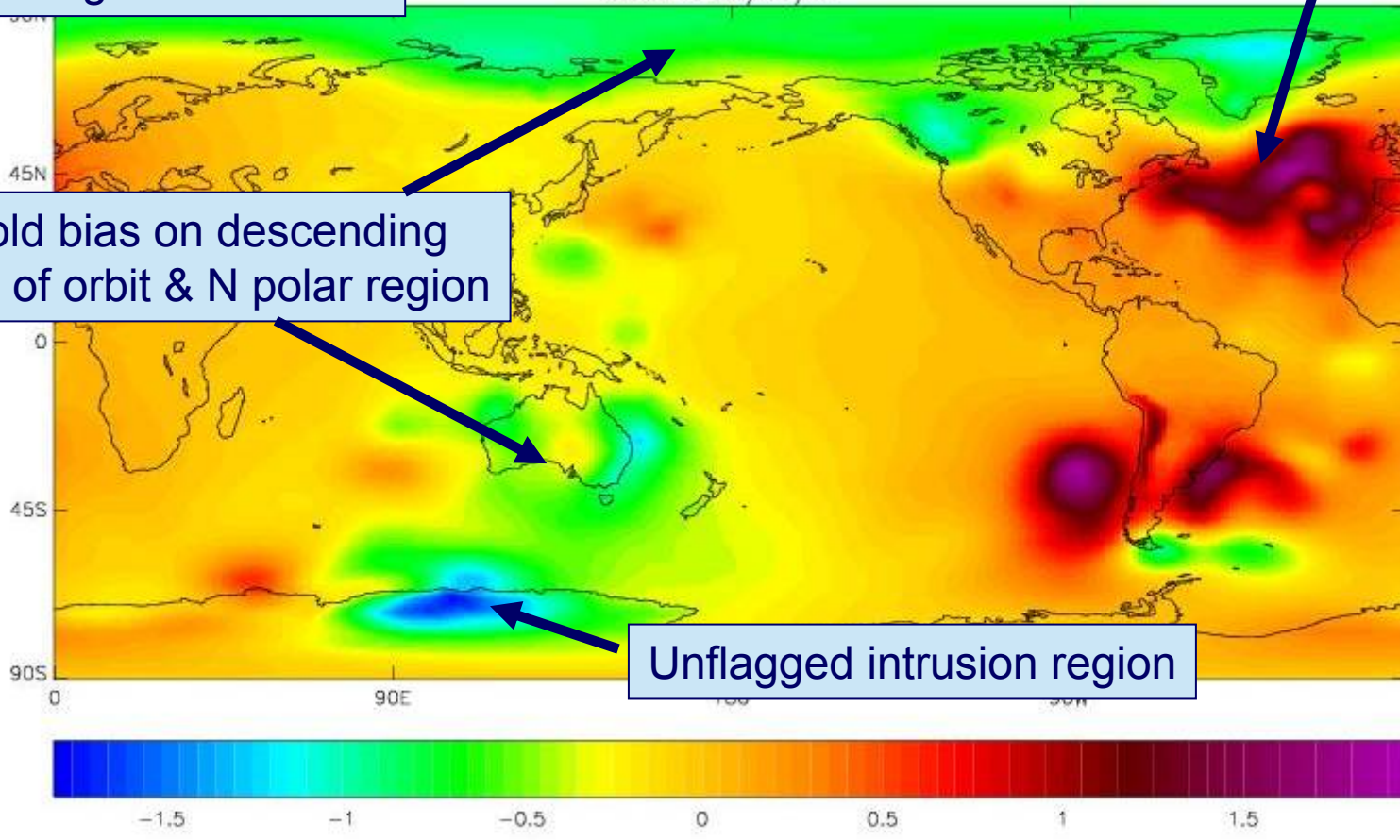
Channels 2 – 7
Obs errors: 0.25K (2 - 4)
 0.5K (5 - 7)
LWP < 5 g.m⁻²

Atmos theta after timestep at 2000. metres
at 2100 06/10/05

Warm bias on ascending part of orbit

Cold bias on descending part of orbit & N polar region

Unflagged intrusion region



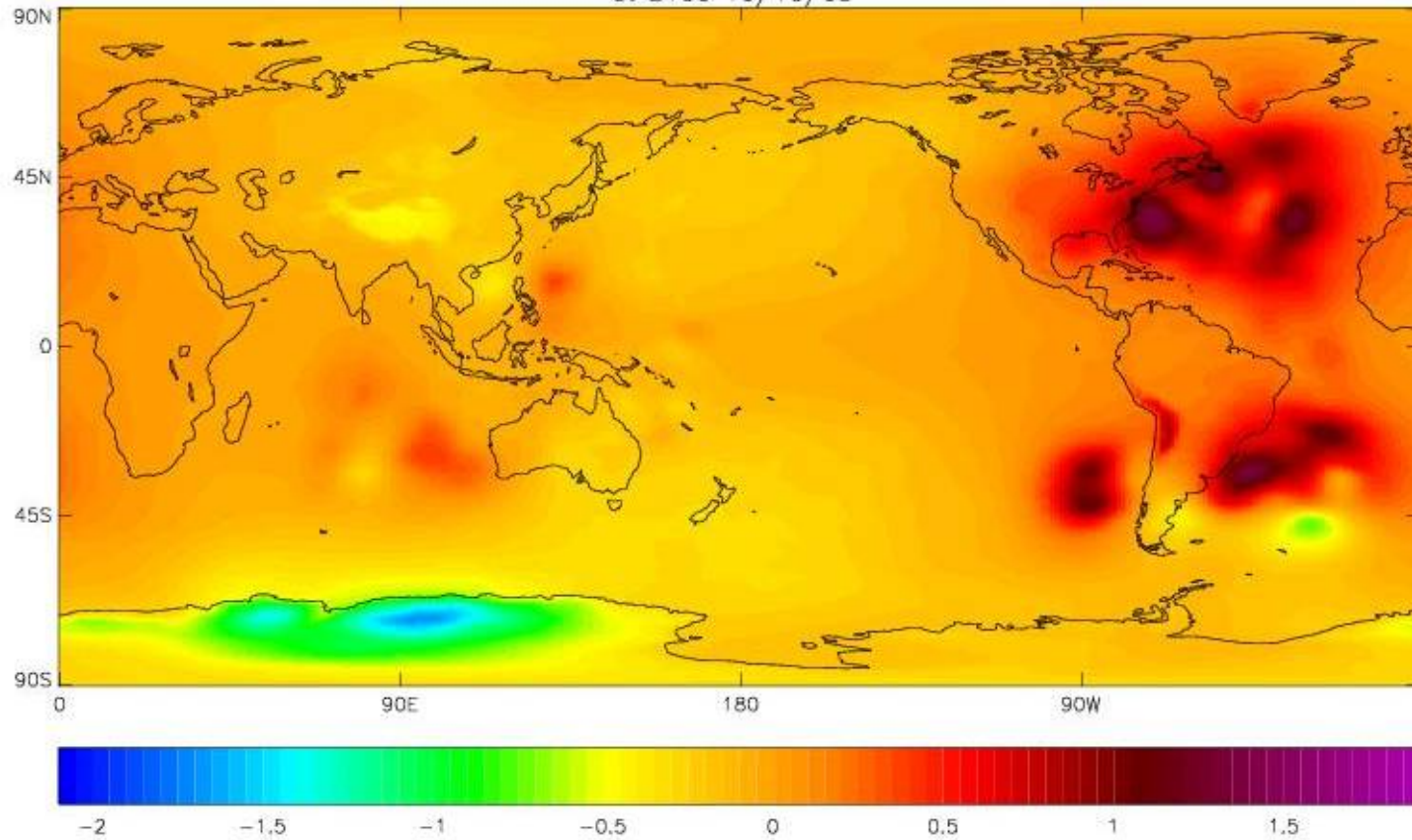
Analysis increments



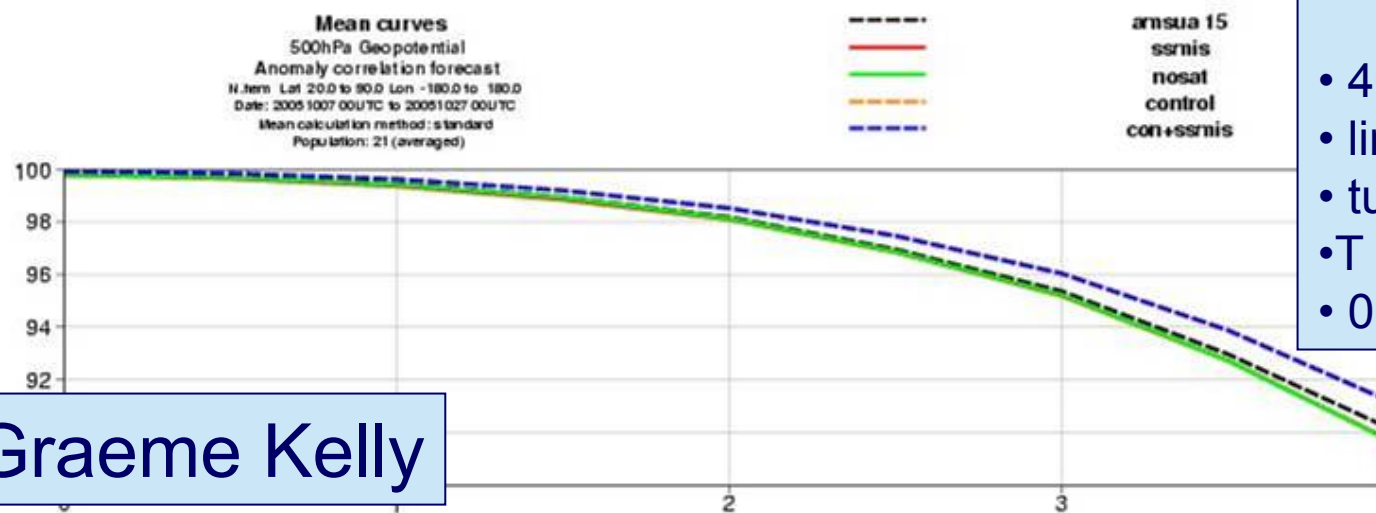
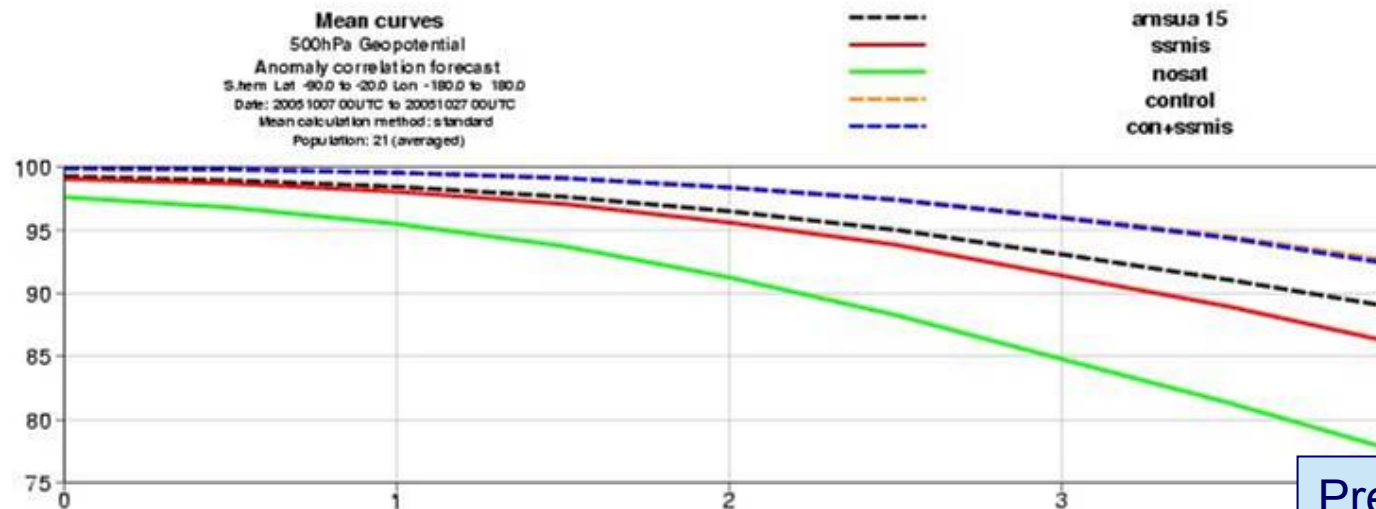
Channels 2 – 4 ONLY
Obs errors: 0.25K (2 - 4)
LWP < 5 g.m⁻²

$T_{\text{CORR}} = 25\text{K}$
Adjusted lag

Atmos theta after timestep at 2000. metres
at 2100 16/10/05



Forecast Impact Studies at ECMWF



Pre-processed data:

- 40 % flagged
- limited coverage
- tuning ongoing
- T sounding chs only
- 0.5K obs errors

Graeme Kelly

Forecast Impact Studies at ECMWF



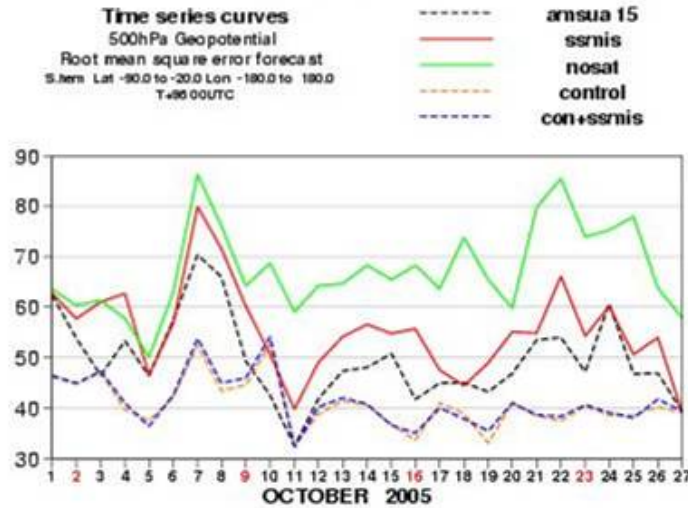
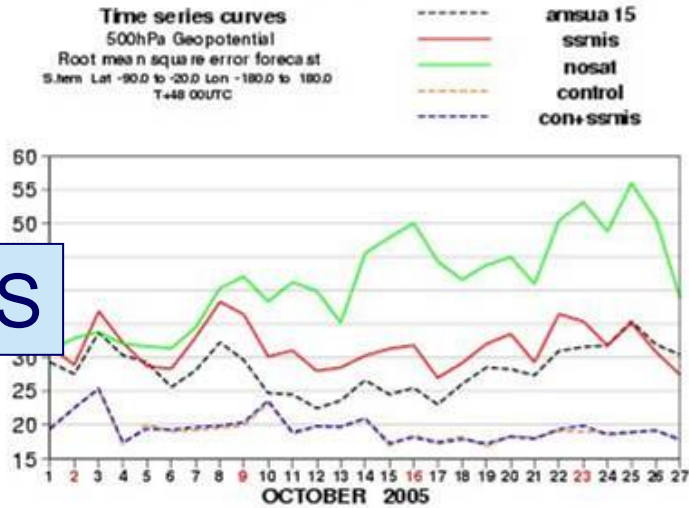
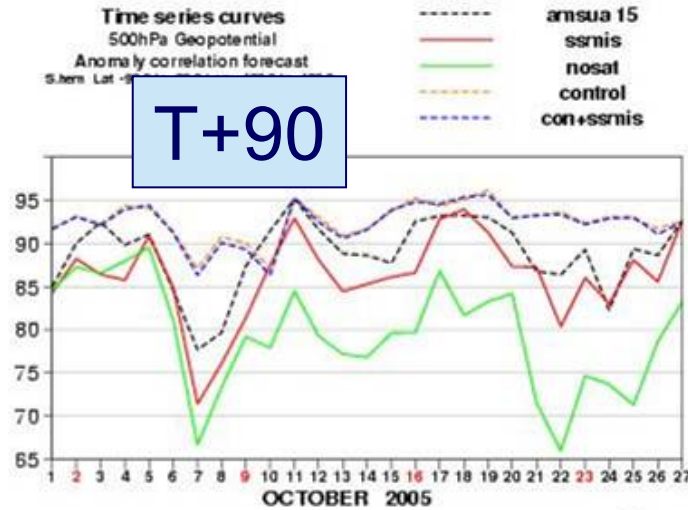
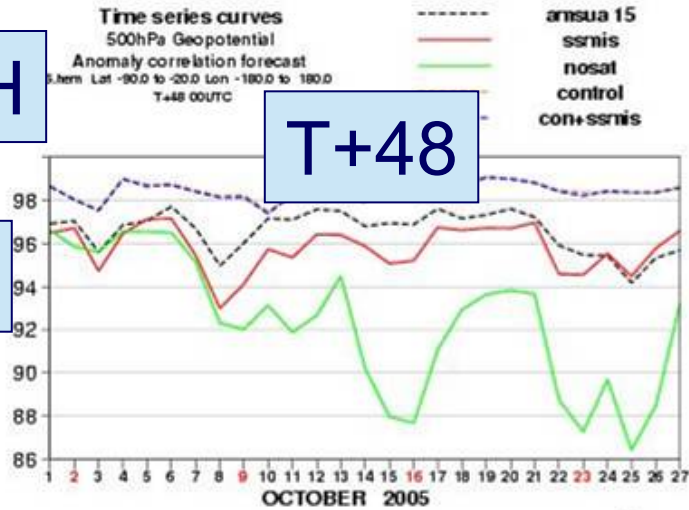
SH

T+48

AC

T+90

RMS



- Best correction algorithms (from NRL, Met Office and NOAA) will be incorporated in a pre-processor to be run at FNMOC, Monterey to produce a new data stream. Expected early 2006.
- Hardware modifications are in place for F17:
 - Fence to prevent direct solar intrusions
 - Temp sensor re-sited at centre of (back of) reflector (?)
- F17 launch June – Dec 2006

Summary & Conclusions



- In the 2 years since launch a number of important instrument biases in F16 SSMIS have been investigated and are now understood
- Correction algorithms have been developed and the best will be incorporated in a pre-processor to be run at FNMOC
- Baseline forecast studies show the impact of F16 SSMIS to be > 50 % impact of AMSU-A on N-15
- Further improvements expected as coverage is improved, corrections are tuned and more channels are used
- SSMIS should be an important component of NWP DA systems over the next 10 years

Summary & Conclusions (contd)



- Some instrumental biases are not easily dealt with in conventional predictor based schemes, new diagnostics are needed to study these and develop correction algorithms
- Ever more complex radiometry (conical scan, aperture synthesis, imaging interferometric) may pose even more complex bias problems – we need to be flexible in developing solutions
- NWP fields can be very useful in instrument Cal/Val – we should be prepared to contribute to Cal/Val efforts

The End

.....Thanks.