



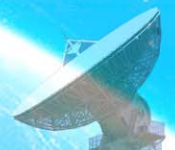
Aerospace Information Research Institute(AIR)
Chinese Academy of Sciences(CAS)

Aerosol polarization radiative transfer simulation and retrieval for DPC/GF-5

Zhengqiang Li*, Yisong Xie, Weizhen Hou

***E-mail: lizq@radi.ac.cn**

May 1, 2019





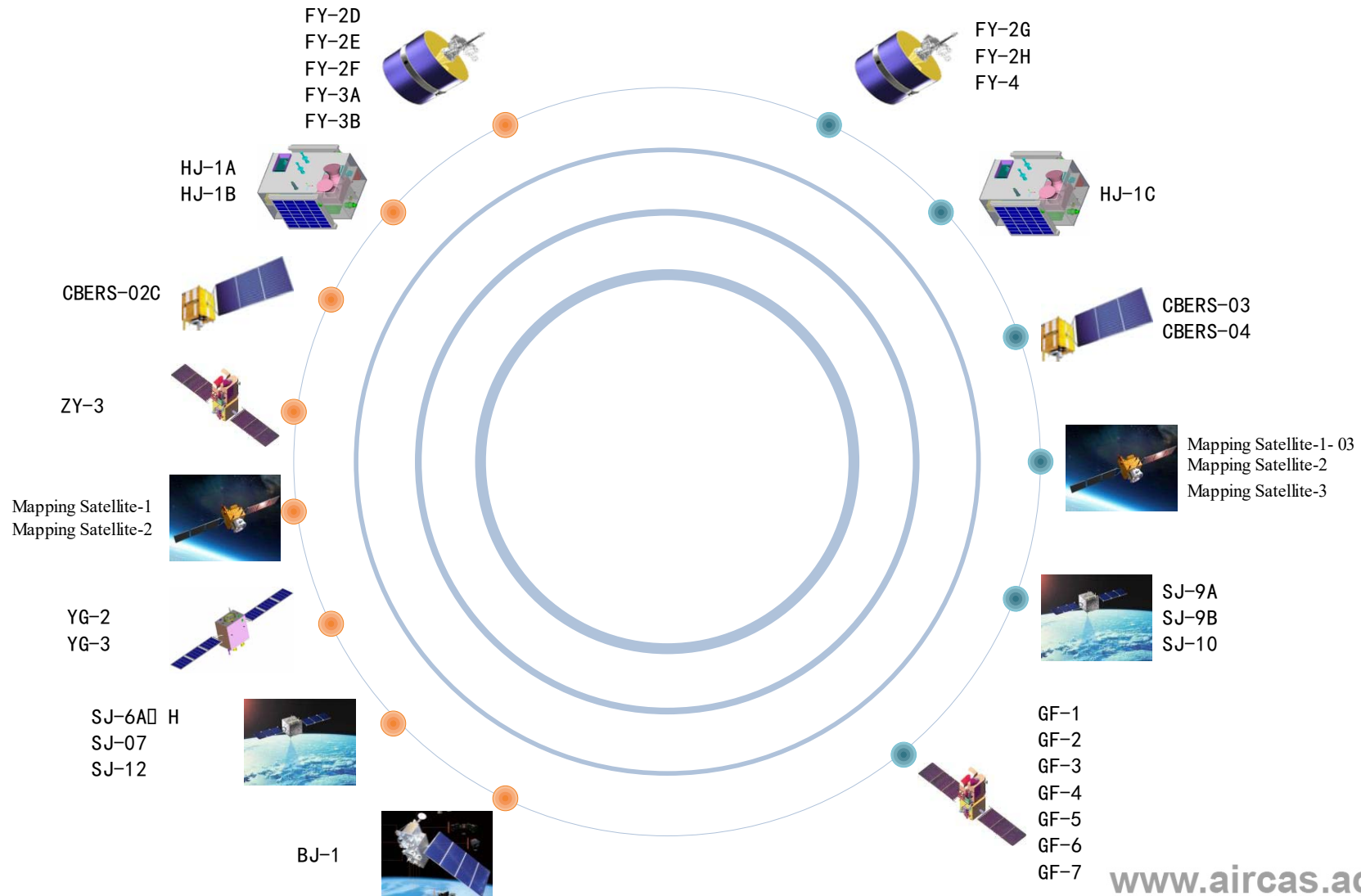
Outline

- **1. Polarimetric satellite remote sensing**
- 2. Inversion framework for DPC/GF-5
- 3. Aerosol retrieval & preliminary validation



Climate & Environment Satellite Programs in China

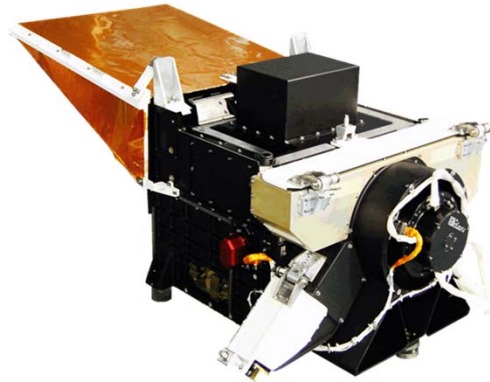
- ✓ High resolution (GF) program : 7 civil satellites
- ✓ Space Infrastructure (SI) program: 50+ satellites



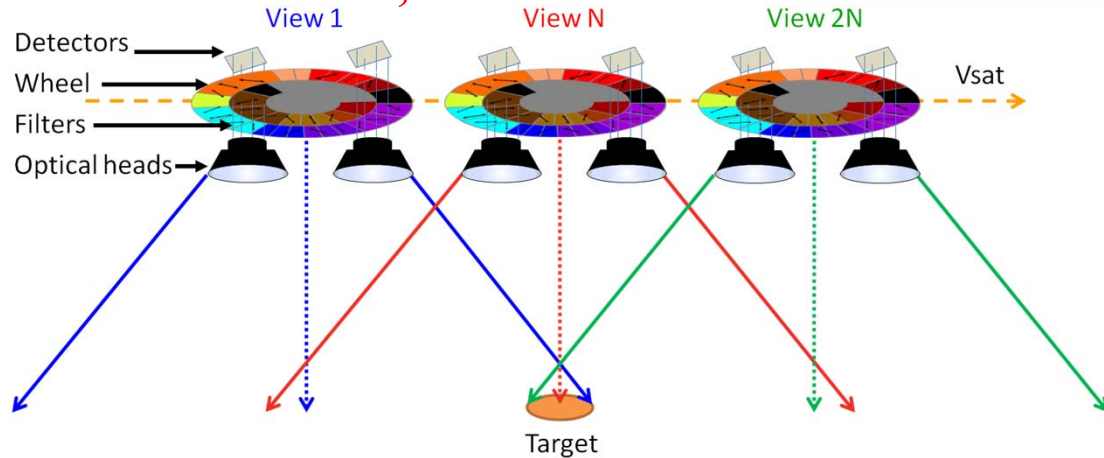


Satellite instruments for polarimetric remote sensing

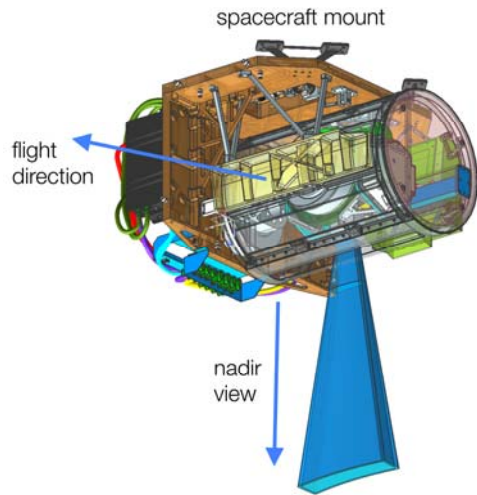
APS/Glory, NASA/USA



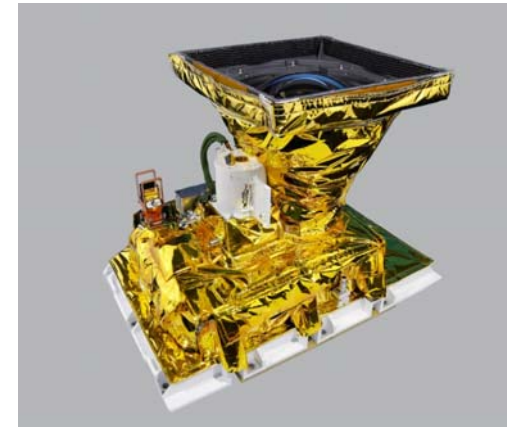
3MI, EUMETSAT/EU



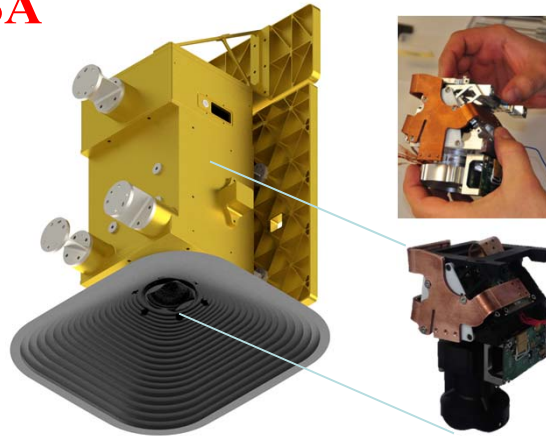
MAIA/OTB-2, NASA/USA



DPC/GF-5, China



HARP2/PACE, UMBC/USA



Dubovik, O. & Li, Z., et al. (2019), Polarimetric remote sensing of atmospheric aerosols: Instruments, methodologies, results, and perspectives, *JQSRT*, 224, 474-511



➤ Airborne instruments for polarimetric RS

RSP, NASA/USA



AirMSPI-2, NASA/USA



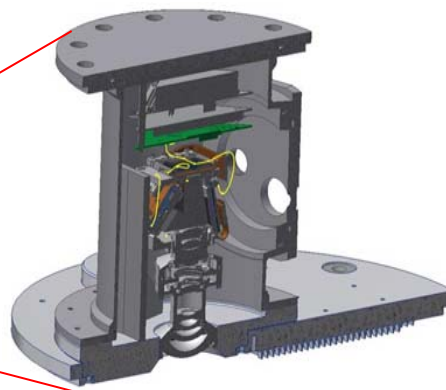
Airborne DPC, China



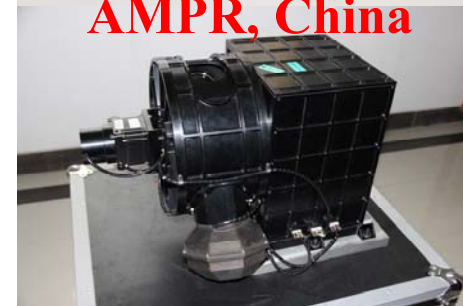
SMAC, China



AirHARP, UMBC/USA



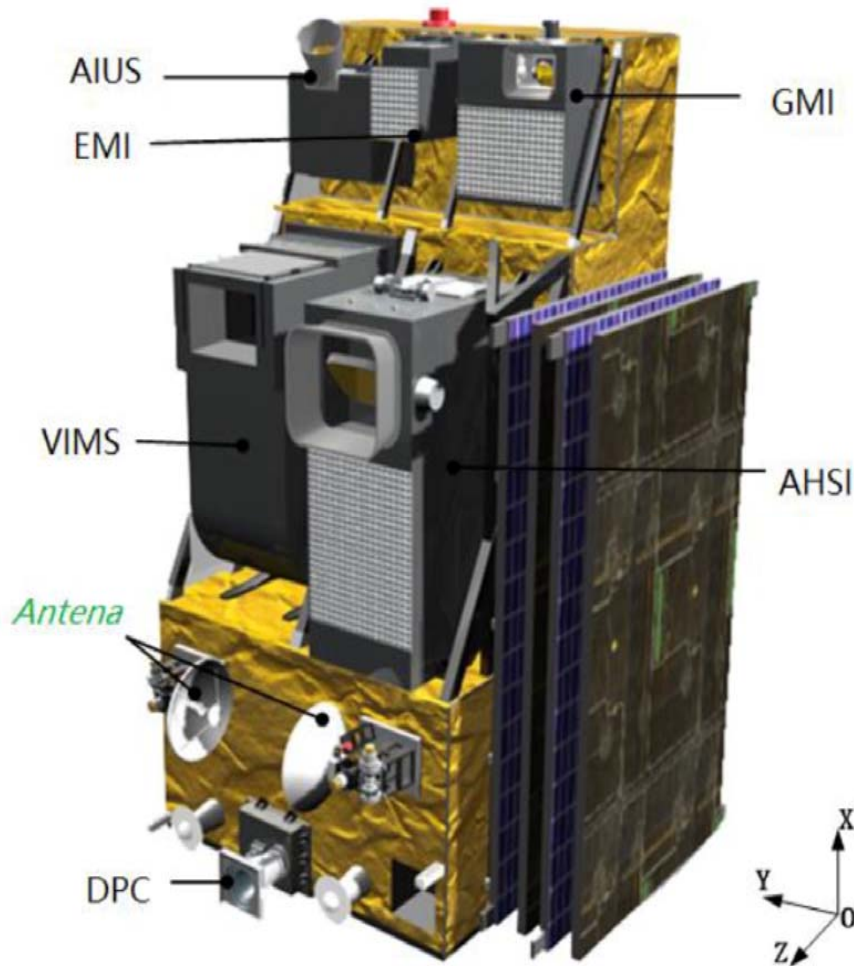
AMPR, China



Dubovik, O. & Li, Z., et al. (2019), Polarimetric remote sensing of atmospheric aerosols: Instruments, methodologies, results, and perspectives, *JQSRT*, 224, 474-511



➤ GF-5 satellite



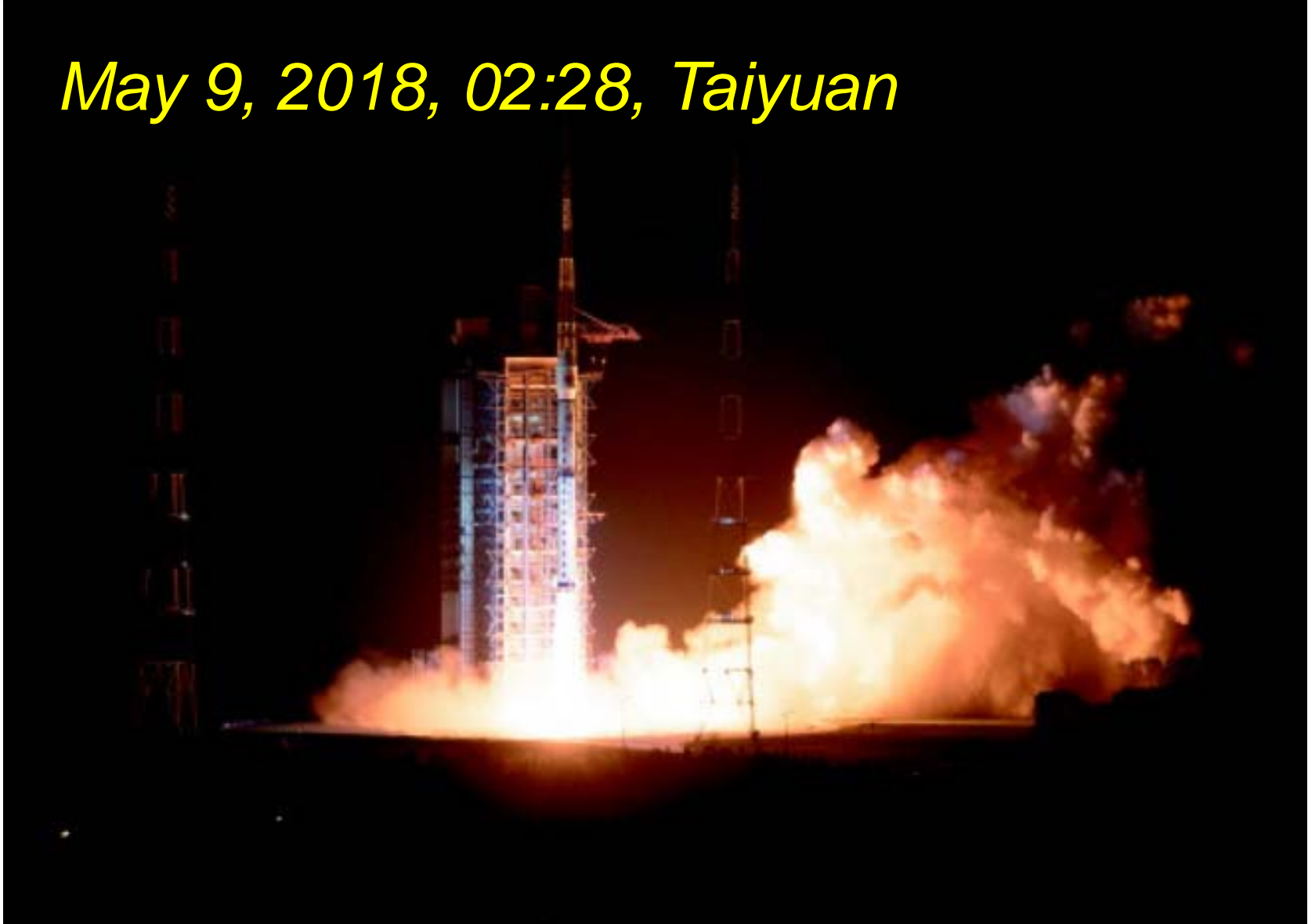
Sensor	Full Name
AHSI	Advanced Hyperspectral Imager
VIMS	Visual and Infrared Multispectral Sensor
AIUS	Atmospheric Infrared Ultra-spectral Sensor
EMI	Environment Monitoring Instrument
GMI	Greenhouse-gases Monitoring Instrument
DPC	Directional Polarization Camera

Li, Z., et al. (2018), Directional Polarimetric Camera (DPC): Monitoring aerosol spectral optical properties over land from satellite observation, *JQSRT*, 218, 21-37 www.aircas.ac.cn



➤ GF-5 satellite

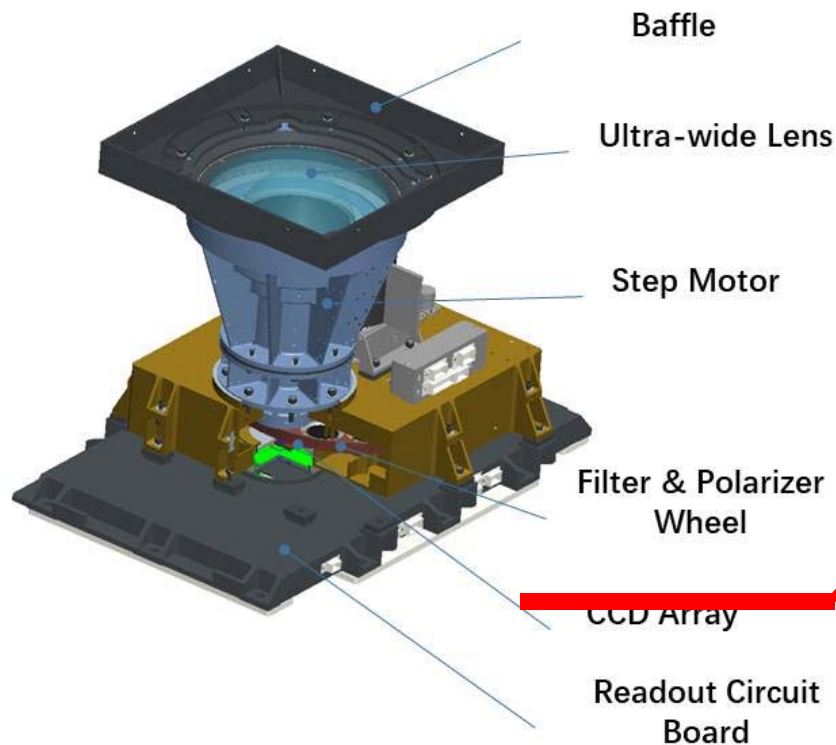
May 9, 2018, 02:28, Taiyuan



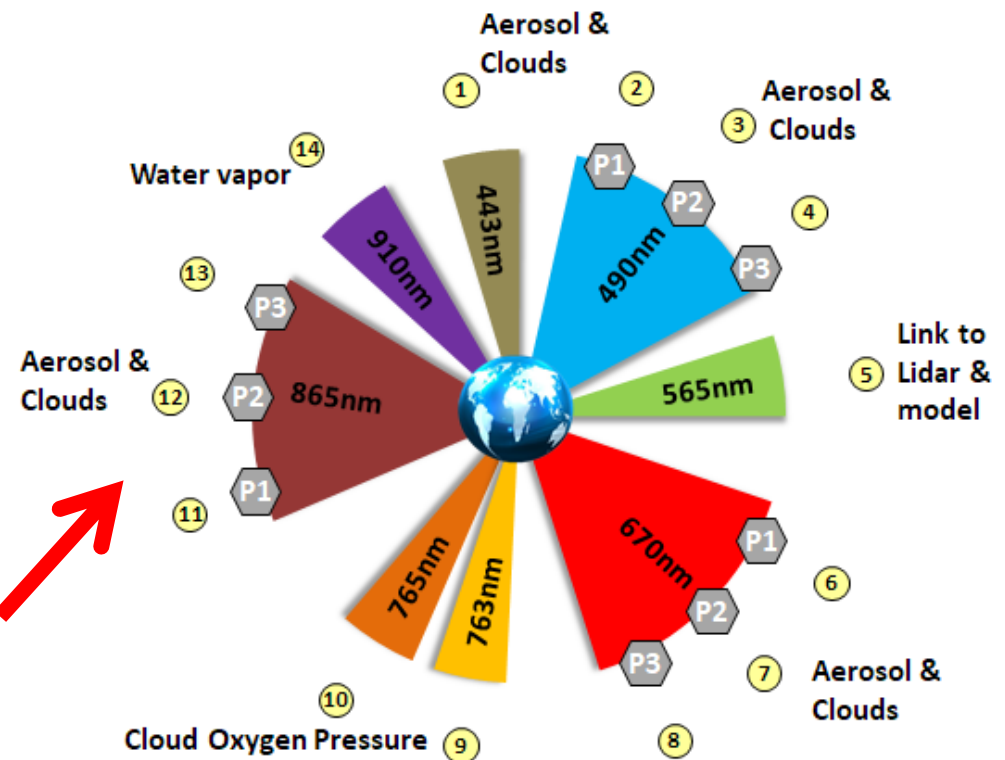


➤ Directional Polarimetric Camera (DPC)

Optical head of DPC/GF-5



Band & polarization configuration



Li, Z., et al. (2018), Directional Polarimetric Camera (DPC): Monitoring aerosol spectral optical properties over land from satellite observation, *JQSRT*, 218, 21-37. www.aircas.ac.cn



➤ Directional Polarimetric Camera (DPC)

Parameter	Value	Parameter	Value
Instrument FOV	$\pm 50^\circ$	Polarized angle	$0^\circ, 60^\circ, 120^\circ$
Spatial res. (km)	3.3	Stokes	I, Q, U
Swath width (km)	1850	Rad. Cal. Error	$\leq 5\%$
Multi-angle	≥ 9	Pol. Cal. Error	≤ 0.02
Image pixels	512×512	Band width	20, 20, 20, 20, 10, 40, 40, 20 nm
Spectral band	443, 490(P), 565, 670(P), 763,765, 865(P), 910 nm (P for polarization)		

- ✓ The DPC is the first Chinese multi-angle polarized earth observation satellite sensor, which is the type of POLDER polarimetric imager www.aircas.ac.cn



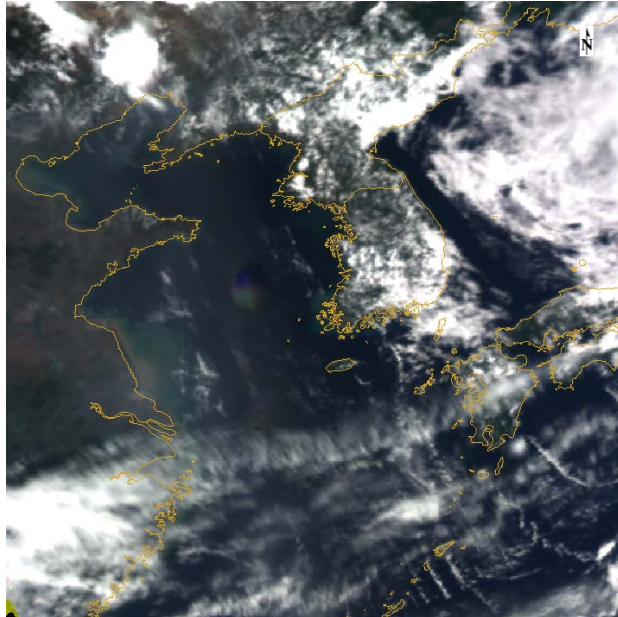
Intensity and polarization measurements

MODIS_2018-06-12-05:30
(Intensity)



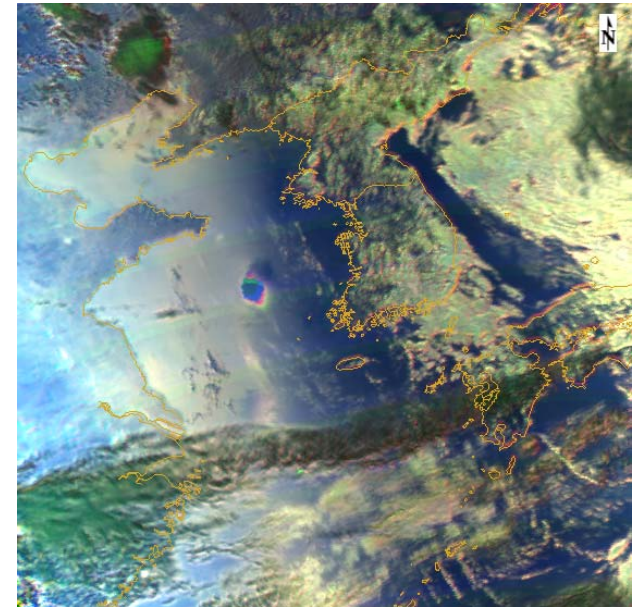
MODIS

DPC_2018-06-12-04:40
(Intensity)



DPC/GF-5

DPC_2018-06-12-04:40
(Polarization)



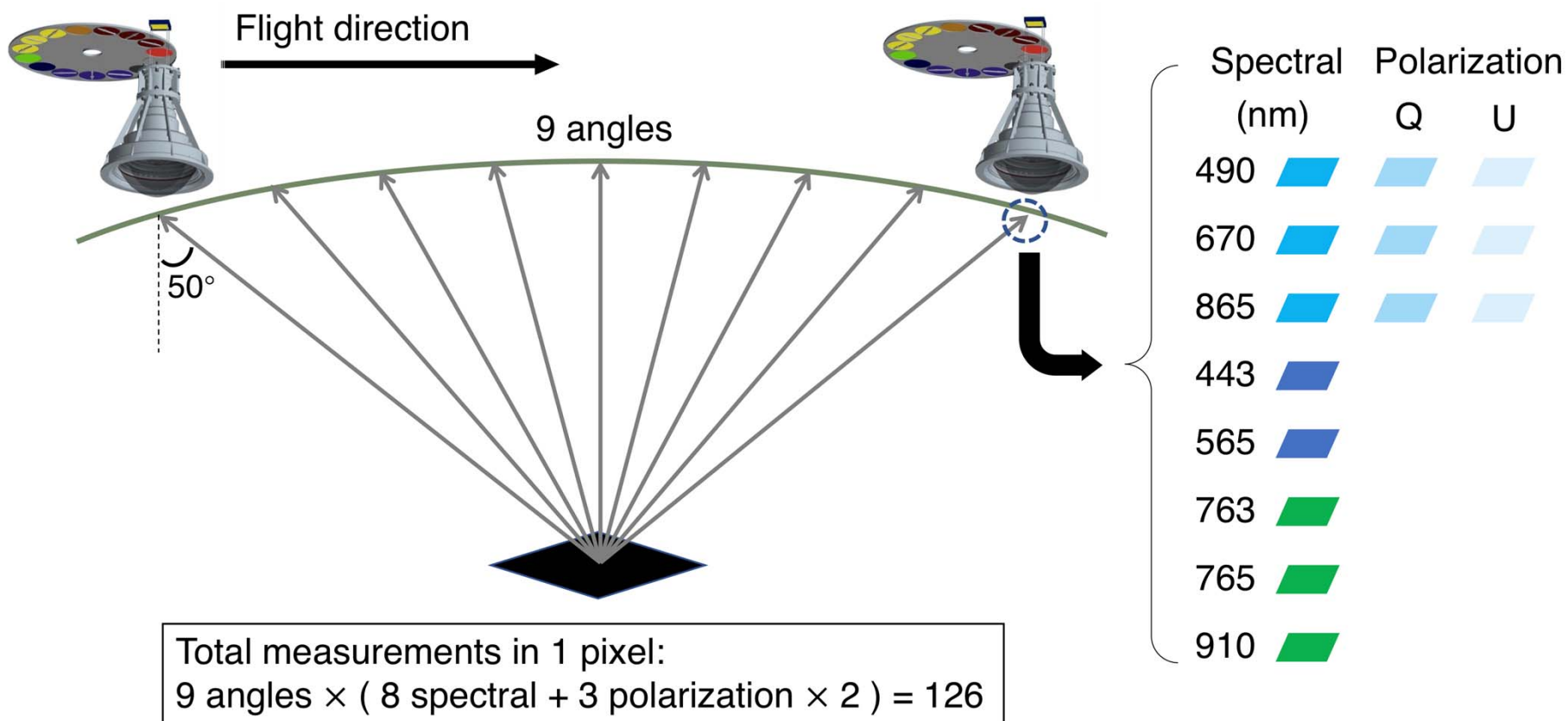


Outline

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- **2. Inversion framework for DPC/GF-5**
- 3. Aerosol retrieval & preliminary validation



➤ Multi-angle measurements of DPC



- ✓ By taking the measurements with 9 viewing angles as an example, the multi-angle observation principle and the description of measurement dataset of DPC are described.



➤ Ill-conditioning in inversion

y: Observation vector

x: State vector (unknowns, aerosol & surface parameters to be retrieved)

$$\mathbf{x} \in [V_0^f, V_0^c, f(\lambda), k_1, k_2, C, r_{\text{eff}}^f, v_{\text{eff}}^f, r_{\text{eff}}^c, v_{\text{eff}}^c, m_r^f(\lambda), m_i^f(\lambda), m_r^c(\lambda), m_i^c(\lambda)]^T$$

Case of DPC/GF-5: No. of bands (λ) is 5 \longrightarrow No. of x elements is 34!

$$\mathbf{y} = \mathbf{F}(\mathbf{x}) + \boldsymbol{\epsilon}$$

So many unknowns to be retrieved!

If number of y elements $<$ that of x : **ill-conditioning problem**



Radiative transfer simulation



www.unl-vrtm.org

UNL-VRM Features

Unified Linearized Vector Radiative Transfer Model

$$\mathbf{S} = \begin{bmatrix} I \\ Q \\ U \\ V \end{bmatrix}$$

Vector RTM for simulation of light intensity and polarization



Information content analysis for future satellite sensors



Accurate UV-to-IR (0.2 - 40 micron) hyperspectral RTM



Flexible and easy-to-read modular Fortran programming

$$\mathbf{J} = \begin{bmatrix} \frac{\partial F_1}{\partial x_1} & \dots & \frac{\partial F_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial F_m}{\partial x_1} & \dots & \frac{\partial F_m}{\partial x_n} \end{bmatrix}$$

Online analytical Jacobian of Stokes to particle, gas, and surface properties



Complementary Python utility package, [pyunlvrtm](#)

(Wang et al., JQSRT, 2015; Xu & Wang, JGR, 2015)

www.aircas.ac.cn



➤ Inversion framework

❖ Forward model

(Rodgers, 2000):

$$\mathbf{y} = \mathbf{F}(\mathbf{x}) + \boldsymbol{\varepsilon}$$

UNL-VRTM

❖ State vector

(retrieval parameters):

$$\mathbf{x} = [V_0^f, V_0^c, f(\lambda_1), \dots, f(\lambda_5), k_1, k_2, C]^T$$

Aerosol volume concentration
Improve BRDF parameter
BPDF parameter

❖ Aerosol model

(a priori):

$$\mathbf{b} = [r_{\text{eff}}^f, v_{\text{eff}}^f, r_{\text{eff}}^c, v_{\text{eff}}^c, m_r^f(\lambda), m_i^f(\lambda), m_r^c(\lambda), m_i^c(\lambda)]^T$$

Size distribution for fine & coarse
Refractive indices parameters for fine & coarse

❖ Cost function (optimized):

$$J(\mathbf{x}) = \frac{1}{2} [\mathbf{y} - \mathbf{F}(\mathbf{x})]^T \mathbf{S}_\varepsilon^{-1} [\mathbf{y} - \mathbf{F}(\mathbf{x})] + \frac{1}{2} (\mathbf{x} - \mathbf{x}_a)^T \mathbf{S}_a^{-1} (\mathbf{x} - \mathbf{x}_a)$$

❖ Gradient vector (iteration):

Jacobians by UNL-VRTM

$$\nabla_{\mathbf{x}} J(\mathbf{x}) = -\mathbf{K}^T \mathbf{S}_\varepsilon^{-1} [\mathbf{y} - \mathbf{F}(\mathbf{x})] + \mathbf{S}_a^{-1} (\mathbf{x} - \mathbf{x}_a), \mathbf{K}_{j,i} = \frac{\partial y_j}{\partial x_i}, (i = 1, \dots, n; j = 1, \dots, 15, m)$$



➤ Inversion framework

- ❖ **Surface reflectance matrix** (Dubovik et al., 2011):

$$R(\theta_0, \theta_v, \varphi, \lambda) = \rho^s \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} + \frac{\rho_{\text{Maignan}}}{2} \begin{bmatrix} r_l^2 + r_r^2 & r_l^2 - r_r^2 & 0 & 0 \\ r_l^2 - r_r^2 & r_l^2 + r_r^2 & 0 & 0 \\ 0 & 0 & 2r_l r_r & 0 \\ 0 & 0 & 0 & 2r_l r_r \end{bmatrix}$$

- ❖ **Improved BRDF model** (Litvinov et al., 2011):

$$r_\lambda(\mu_0, \mu_v, \phi) = f(\lambda) [1 + k_1 f_{\text{geom}}(\mu_0, \mu_v, \phi) + k_2 f_{\text{vol}}(\mu_0, \mu_v, \phi)]$$

- ❖ **BPDF model** (Maignan et al., 2009):

$$R_p^s(\theta_0, \theta_v, \varphi) = \rho_{\text{Maignan}} F_p(\gamma, n_i) = \frac{c \exp[\tan(\gamma)] \exp(\text{NDVI})}{\cos(\theta_0) + \cos(\theta_v)} F_p(\gamma, n_i)$$



➤ Inversion framework

❖ Spectral aerosol optical depth (AOD):

$$\tau_a(\lambda) = \tau_a^f(\lambda) + \tau_a^c(\lambda) = \frac{3V_0^f}{4r_{\text{eff}}^f} Q_{\text{ext}}^f(\lambda) + \frac{3V_0^c}{4r_{\text{eff}}^c} Q_{\text{ext}}^c(\lambda)$$

❖ Angstrom exponent (α)

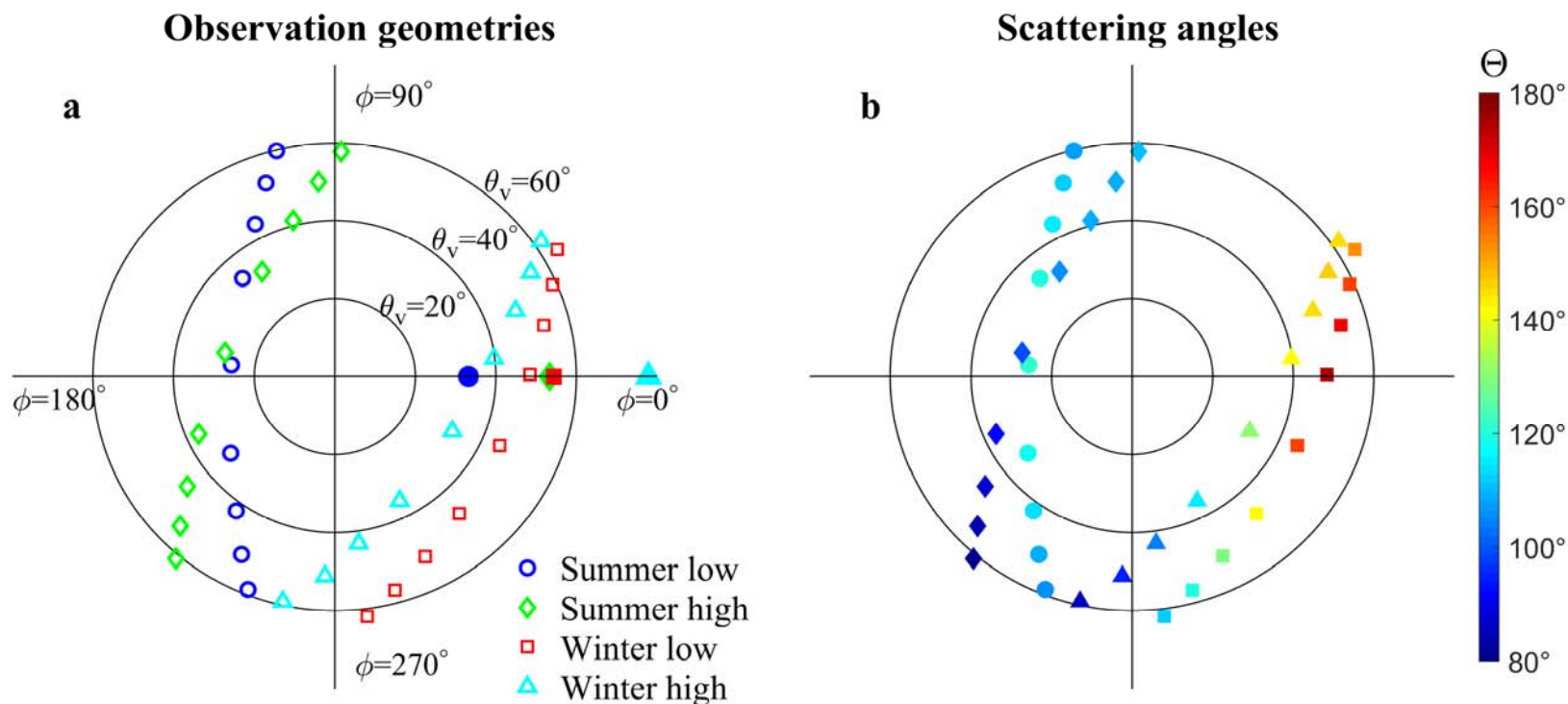
$$\alpha = \ln \frac{\tau_a(\lambda_p)}{\tau_a(\lambda_q)} / \ln \frac{\lambda_q}{\lambda_p}$$

❖ Fine-mode fraction (FMF):

$$\text{FMF}(\lambda) = \tau_a^f(\lambda) / \tau_a(\lambda)$$



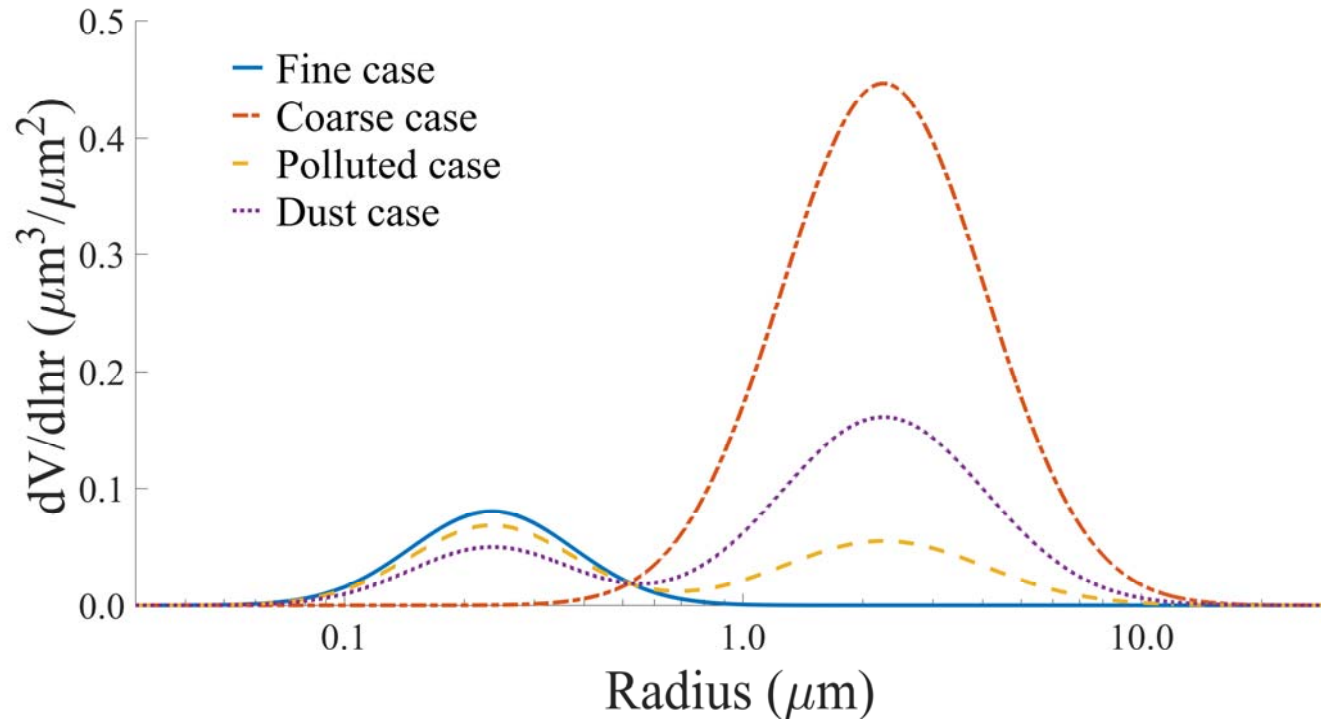
➤ Multi-viewing observation geometries for forward simulations



- ✓ 4 multi-viewing observation geometries are considered with the combinations of different solar zenith angles (θ_0), viewing zenith angles (θ_v) and relative azimuth angles (ϕ) to represent the typical observations in different location.



➤ Aerosol model used for simulations

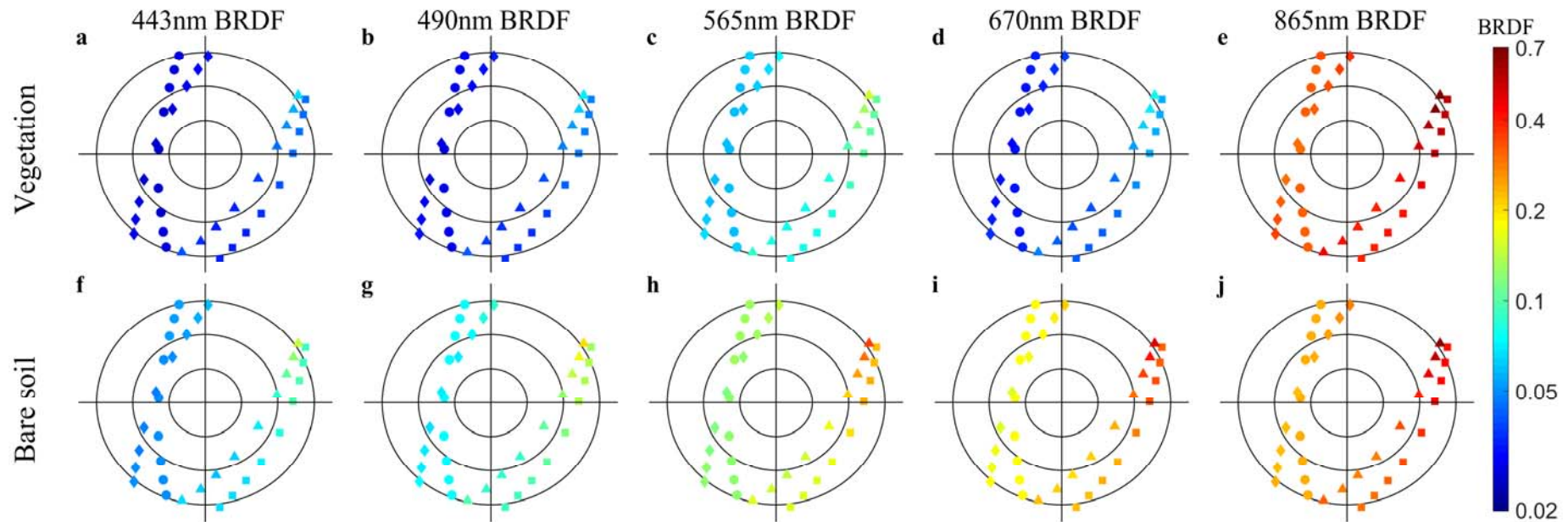


$$\frac{dV}{d\ln r} = \frac{V_0^f}{\sqrt{2\pi\ln\sigma_g^f}} \exp\left[-\frac{(\ln r - \ln r_V^f)^2}{2\ln^2\sigma_g^f}\right] + \frac{V_0^c}{\sqrt{2\pi\ln\sigma_g^c}} \exp\left[-\frac{(\ln r - \ln r_V^c)^2}{2\ln^2\sigma_g^c}\right]$$

- ✓ Based on climatology analyses of **Sun-sky radiometer observation network (SONET)** measurements, for the polluted and dust aerosols, we assume that these 2 aerosol cases are mixed with different relative percentage between the fine and coarse modes (**Li et al., BAMS, 2018**).



➤ Surface BRDF for simulations



Kernel-driven Ross-Li BRDF model:

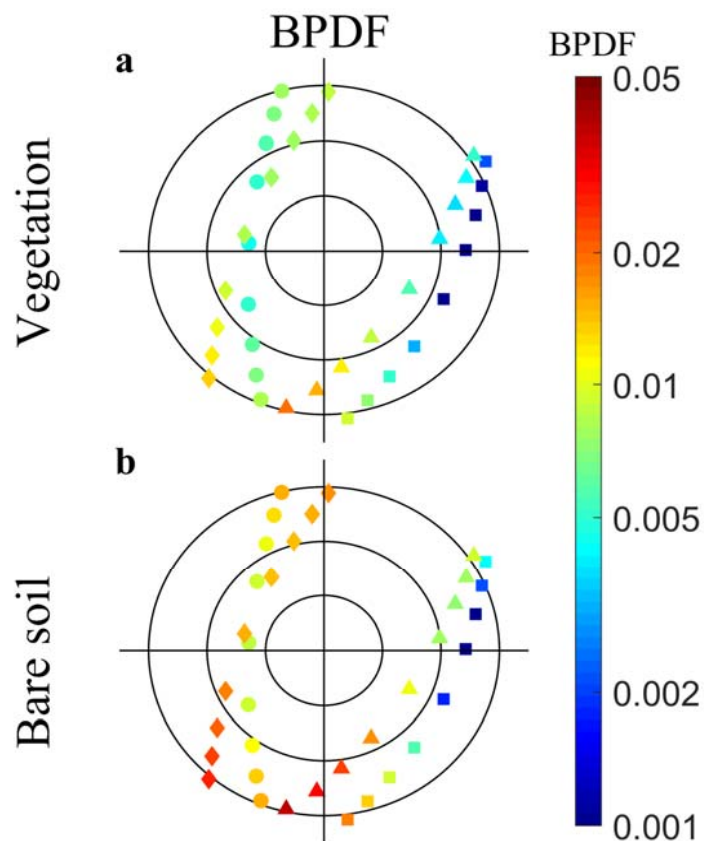
$$r_{\lambda}(\mu_0, \mu_v, \phi) = f_{\text{iso}}(\lambda) + k_1(\lambda)f_{\text{geom}}(\mu_0, \mu_v, \phi) + k_2(\lambda)f_{\text{vol}}(\mu_0, \mu_v, \phi)$$

Improved BRDF model:

$$r_{\lambda}(\mu_0, \mu_v, \phi) = f(\lambda)[1 + k_1f_{\text{geom}}(\mu_0, \mu_v, \phi) + k_2f_{\text{vol}}(\mu_0, \mu_v, \phi)]$$



➤ Surface BPDF for simulations



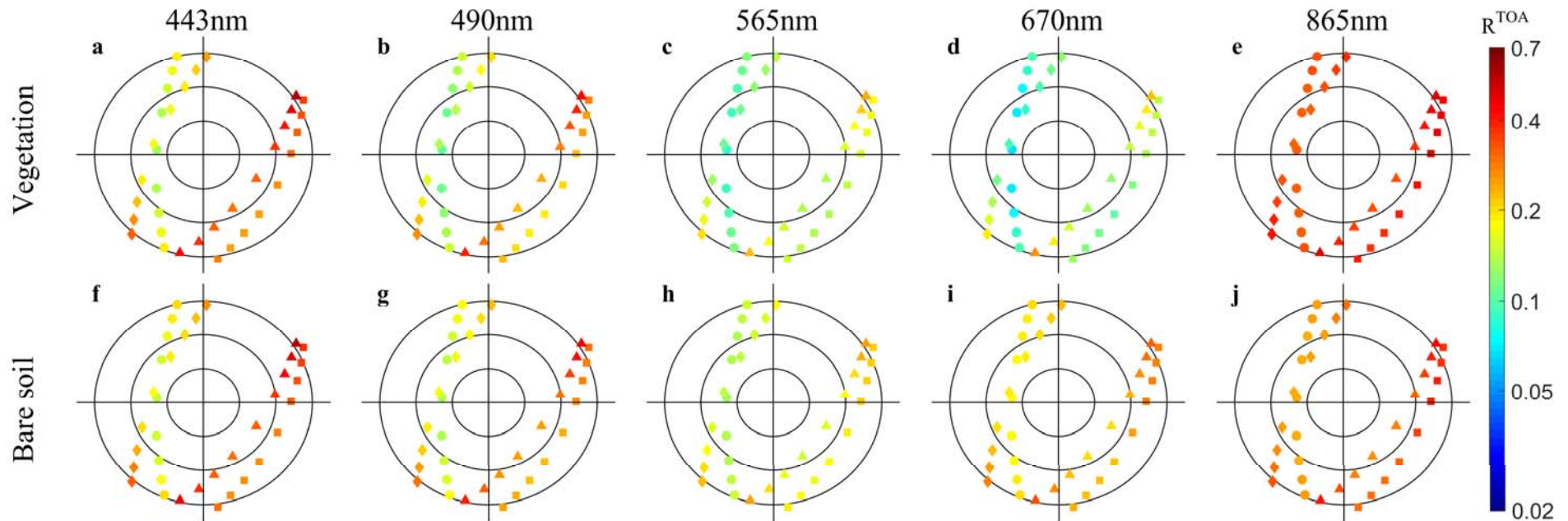
$$R_p^S(\mu_0, \mu_v, \varphi) = \rho_{\text{Maignan}} \mathbf{F}_{1,2}(\gamma, n_i)$$

$$\rho_{\text{Maignan}} = \frac{C \exp(\tan \gamma) \exp(\text{NDVI})}{4(\mu_0 + \mu_v)}$$

- ✓ The surface-polarized reflectance is regarded as independent on the wavelength.



➤ Simulated TOA reflectance of DPC

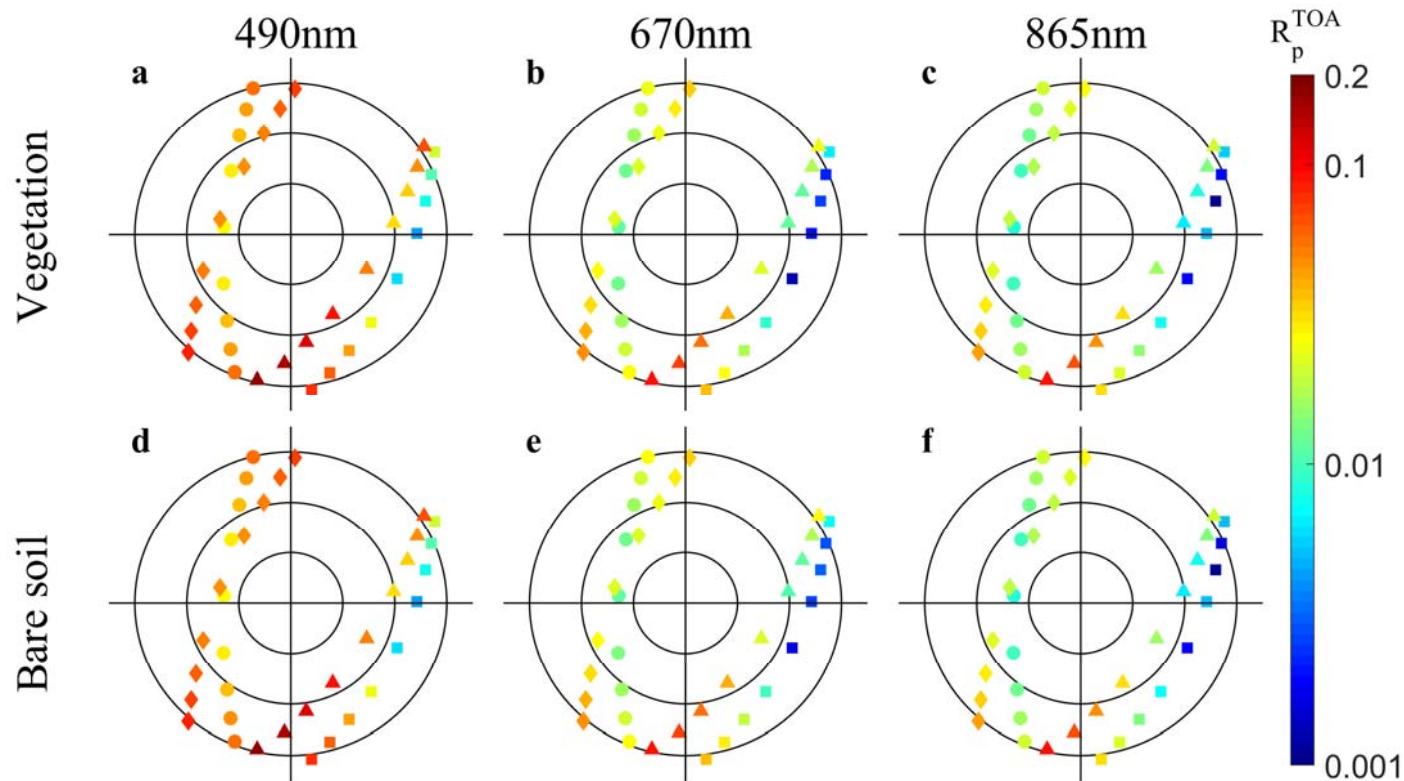


The simulations are for polluted case with AOD = 0.6 at 550nm.

Li, Z., et al. (2018), Directional Polarimetric Camera (DPC): Monitoring aerosol spectral optical properties over land from satellite observation, *JQSRT*, 218, 21-37. www.aircas.ac.cn



➤ Simulated TOA polarized reflectance of DPC



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➤ Information content analysis

- ❖ To test the retrieval capability from DPC, we introduce the **averaging kernel matrix**:

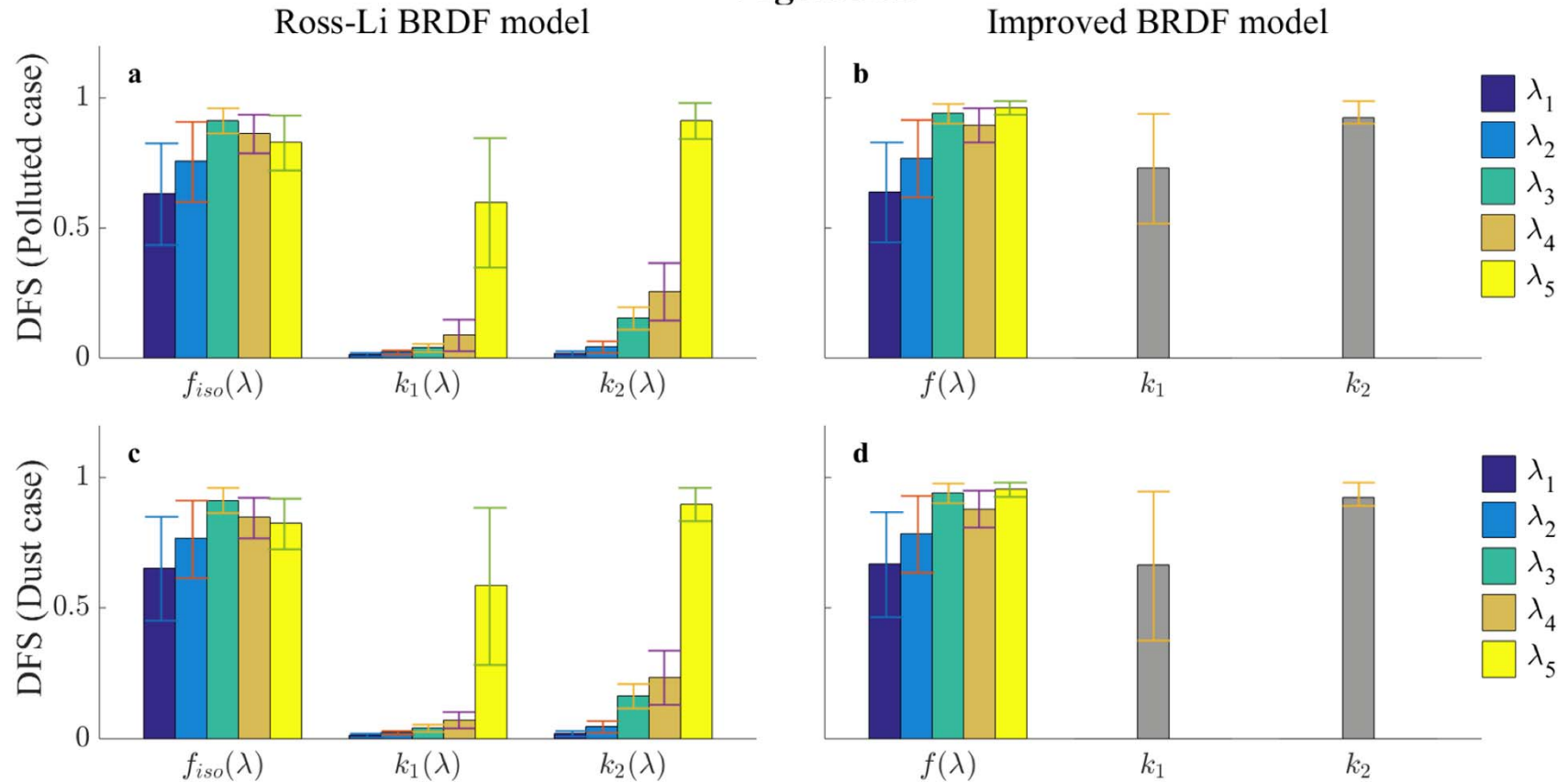
$$\mathbf{A} = (\mathbf{K}^T \mathbf{S}_\epsilon^{-1} \mathbf{K} + \mathbf{S}_a^{-1})^{-1} \mathbf{K}^T \mathbf{S}_\epsilon^{-1} \mathbf{K}$$

- ✓ The trace of \mathbf{A} is equivalent to **the number of independent pieces of information** from the TOA measurements, also called the **degree of freedom for signal (DFS)**.
- ✓ As long as the DFS result $\mathbf{A}_{i,i} > 0.5$, we assume that the retrieval of parameter x_i could be carried out.



Performance of improved BRDF model

Vegetation



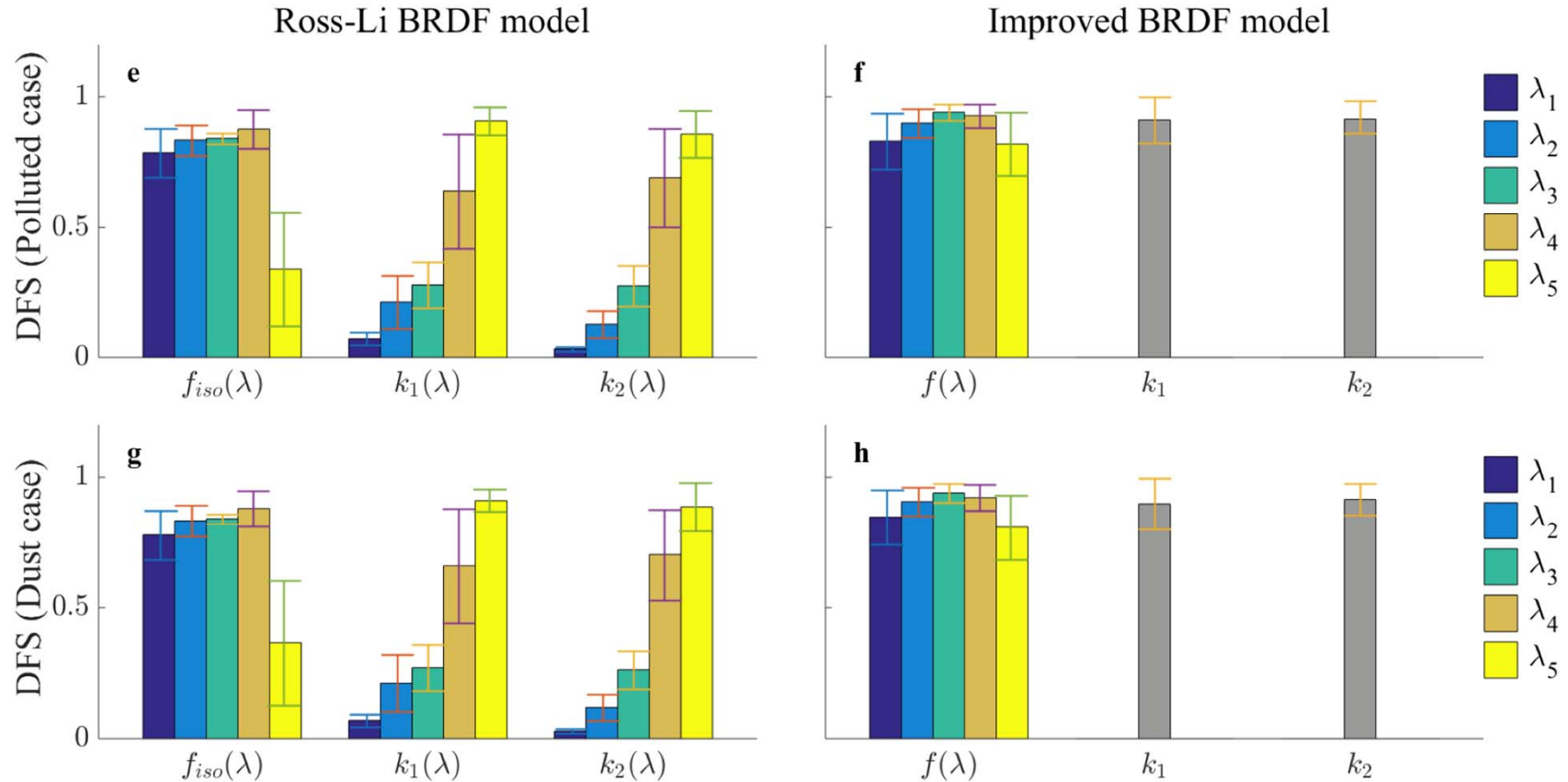
$$\begin{aligned}
 r_{\lambda}(\mu_0, \mu_v, \phi) &= f_{iso}(\lambda) + k_1(\lambda) f_{geom}(\mu_0, \mu_v, \phi) \\
 &+ k_2(\lambda) f_{vol}(\mu_0, \mu_v, \phi)
 \end{aligned}$$

$$\begin{aligned}
 r_{\lambda}(\mu_0, \mu_v, \phi) &= f(\lambda) [1 + k_1 f_{geom}(\mu_0, \mu_v, \phi) \\
 &+ k_2 f_{vol}(\mu_0, \mu_v, \phi)]
 \end{aligned}$$



Performance of improved BRDF model

Bare soil



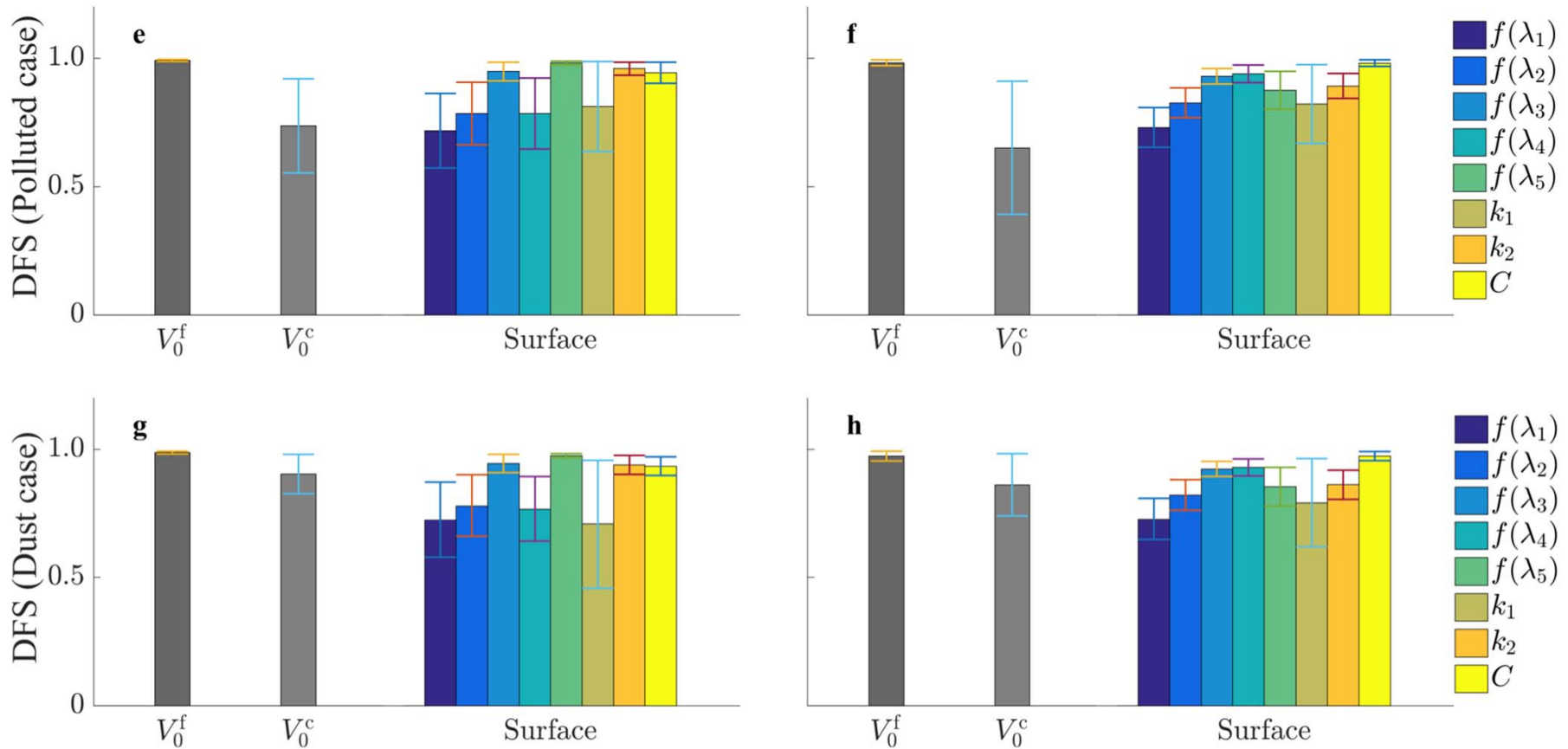
$$\begin{aligned}
 & r_{\lambda}(\mu_0, \mu_v, \phi) \\
 &= f_{iso}(\lambda) + k_1(\lambda) f_{geom}(\mu_0, \mu_v, \phi) \\
 &+ k_2(\lambda) f_{vol}(\mu_0, \mu_v, \phi)
 \end{aligned}$$

$$\begin{aligned}
 & r_{\lambda}(\mu_0, \mu_v, \phi) \\
 &= f(\lambda) [1 + k_1 f_{geom}(\mu_0, \mu_v, \phi) \\
 &+ k_2 f_{vol}(\mu_0, \mu_v, \phi)]
 \end{aligned}$$



➤ Retrieval capability for typical cases

- ✓ For the 2 realistic aerosol types (polluted and dust), the retrieval performances are all quite good in most cases.



$$r_\lambda(\mu_0, \mu_v, \phi) = f(\lambda) [1 + k_1 f_{\text{geom}}(\mu_0, \mu_v, \phi) + k_2 f_{\text{vol}}(\mu_0, \mu_v, \phi)]$$



➤ Retrieval capability for aerosol spectral optical properties

Equivalent DFS of $\tau_a(\lambda)$	Vegetation	Bare Soil
Fine case	0.99	0.98
Coarse case	0.91	0.88
Polluted case	0.87	0.84
Dust case	0.91	0.89

- ✓ Over various surface types, the spectral aerosol parameters $\tau_a(\lambda)$ can be well determined (Li et al., JQSRT, 2018).
- ✓ The pure fine particles cases can be perfectly determined, while DFS of the pure coarse particle cases are relatively lower.



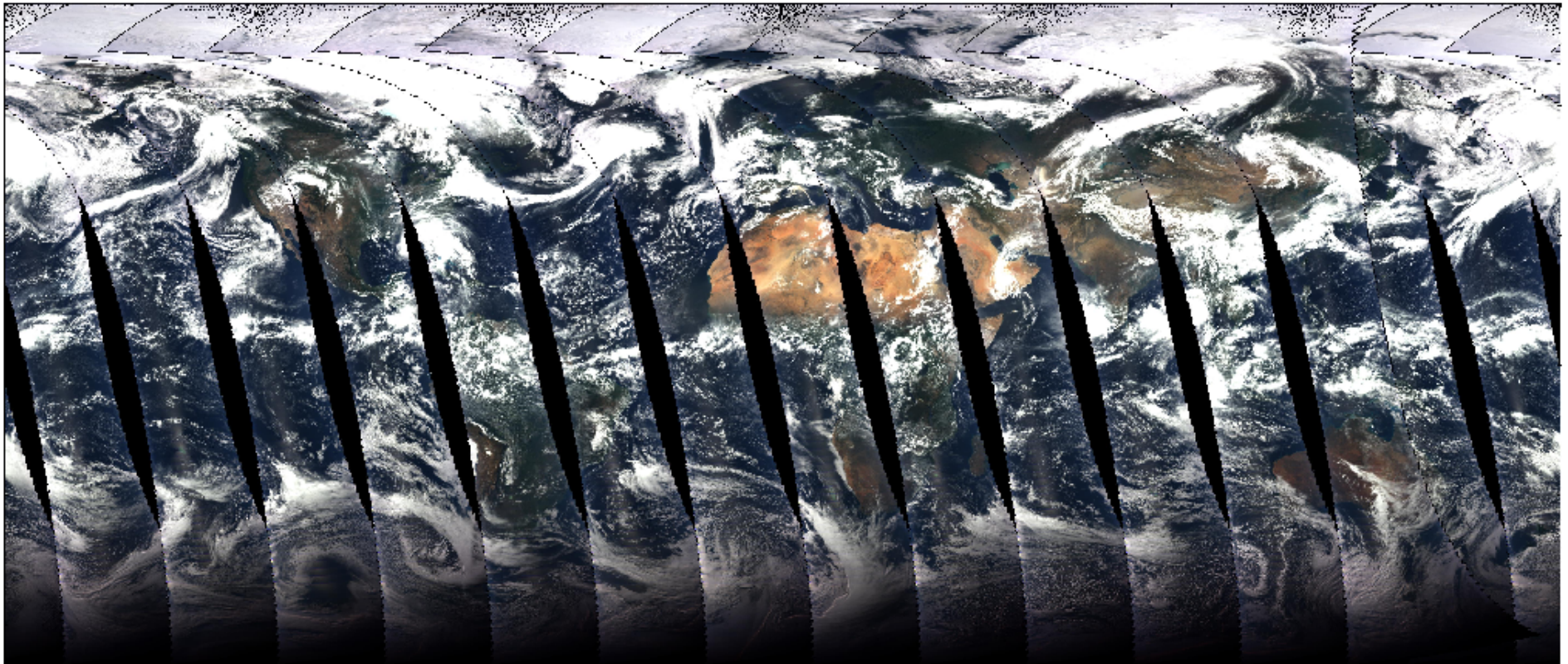
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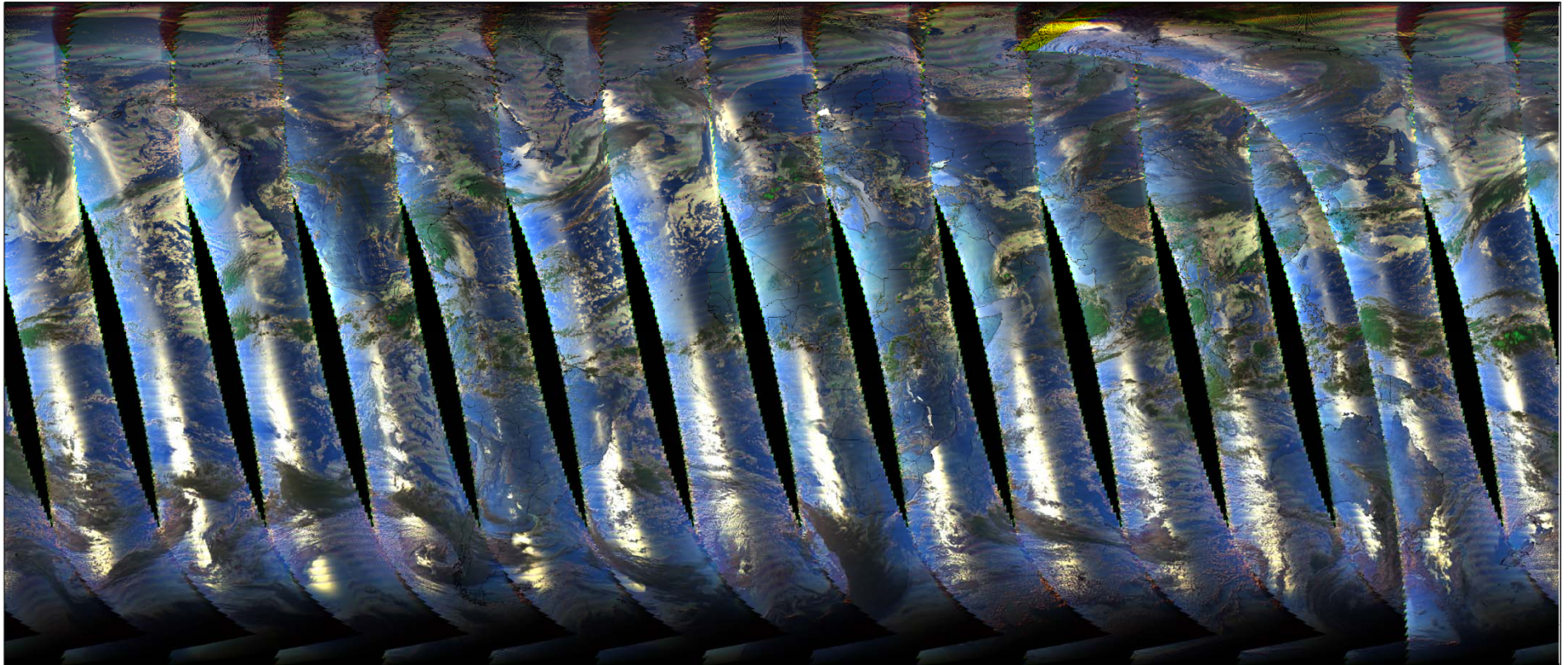
► First global map of DPC/GF-5

❖ Intensity data at 490, 565, 670 nm



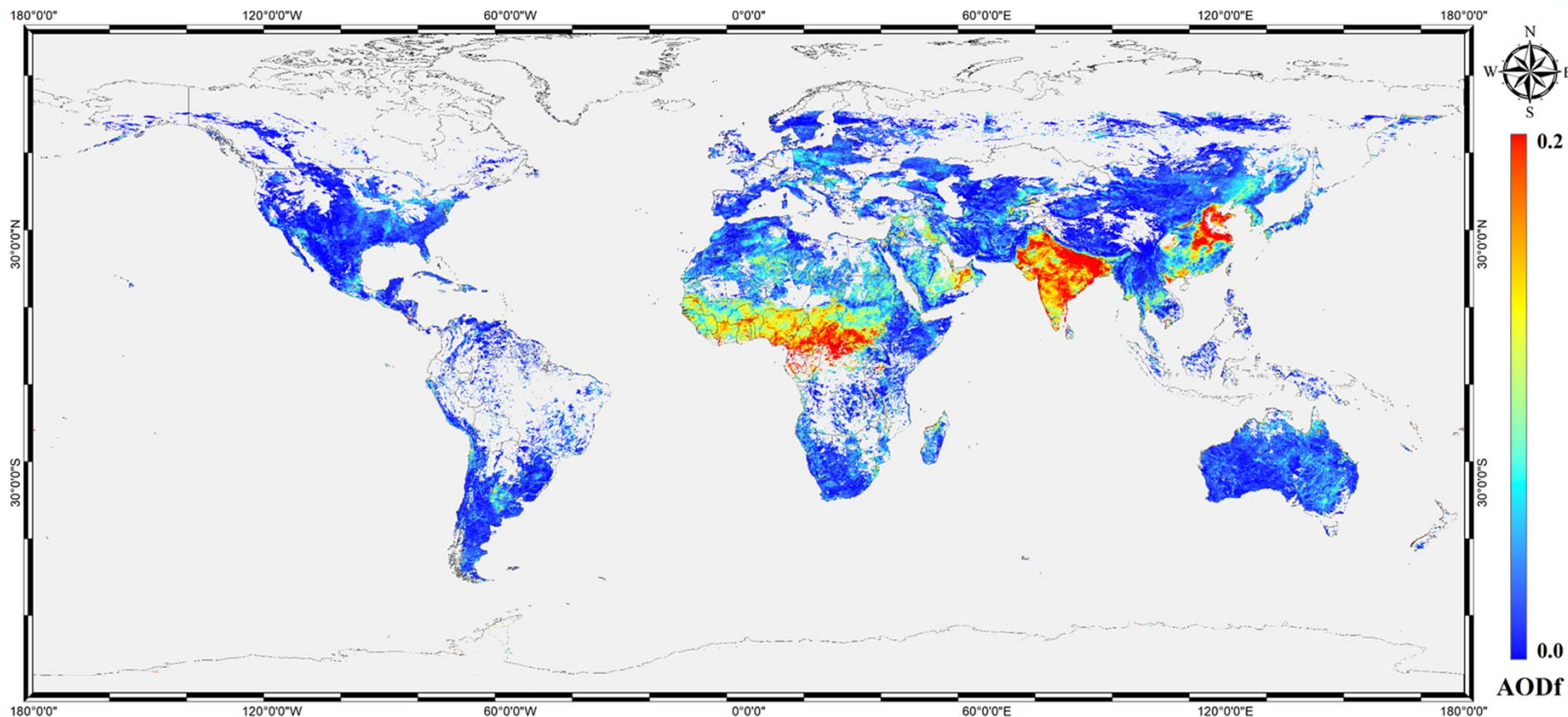


❖ Polarimetric data at 490, 670, 865 nm





First global map of fine-mode AOD (AOD_f) retrieved from DPC/GF-5



高分五号多角度偏振成像仪 (DPC)

数据时间: 2018年11月23日—11月30日

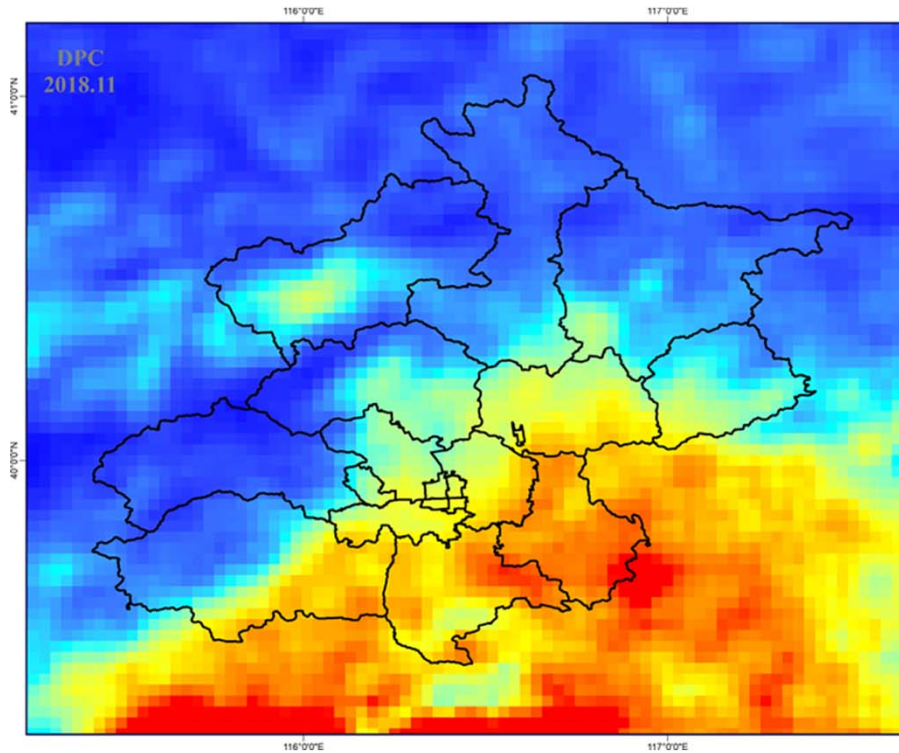
0 2,500 5,000 7,500 10,000 Kilometers

制图单位: 中国科学院空天信息研究院

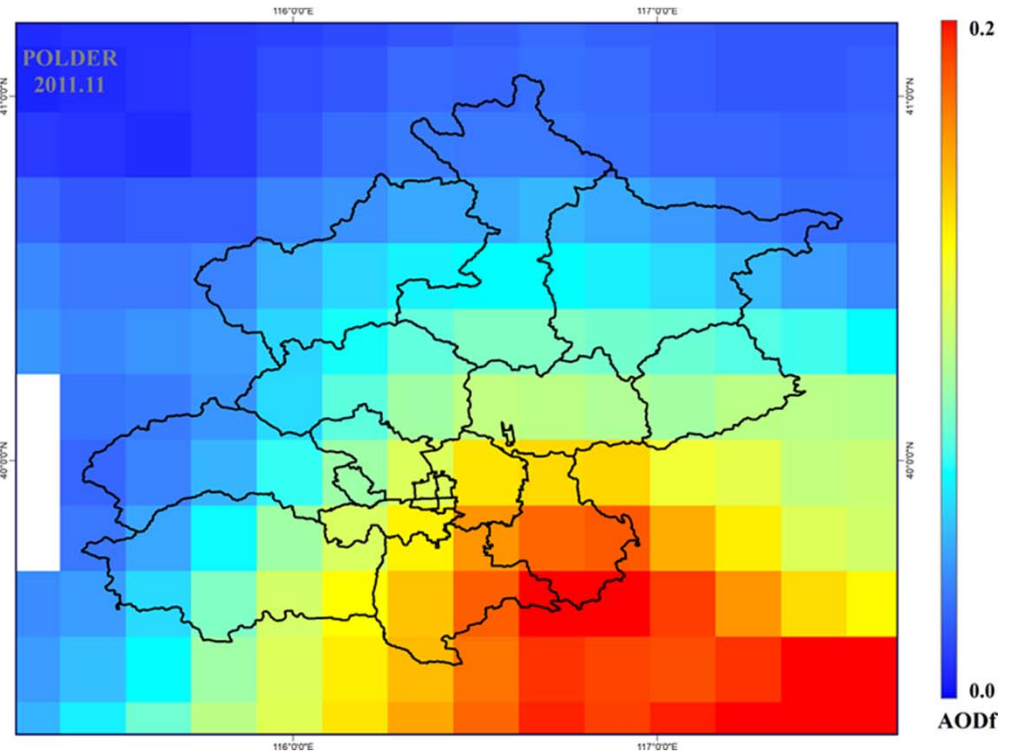
制图时间: 2019年4月9日



❖ Comparison of AOD_f from DPC and POLDER in Beijing



**3.3km of DPC
in Nov. 2018**



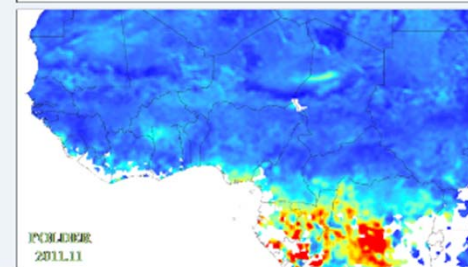
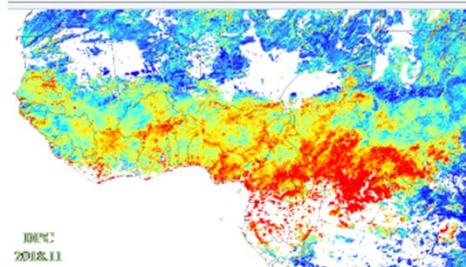
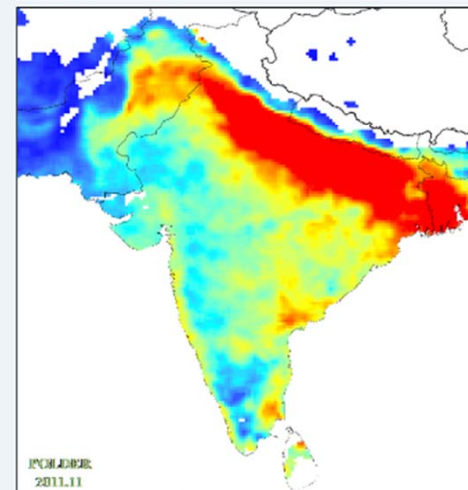
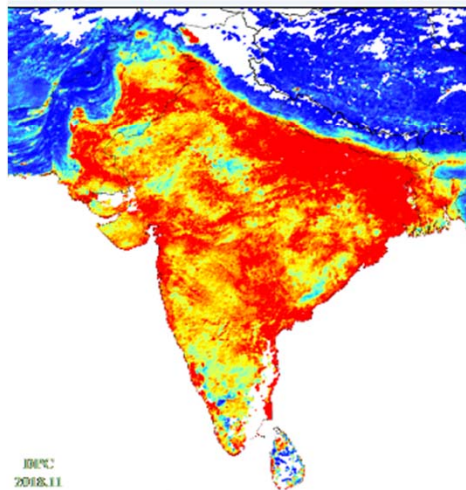
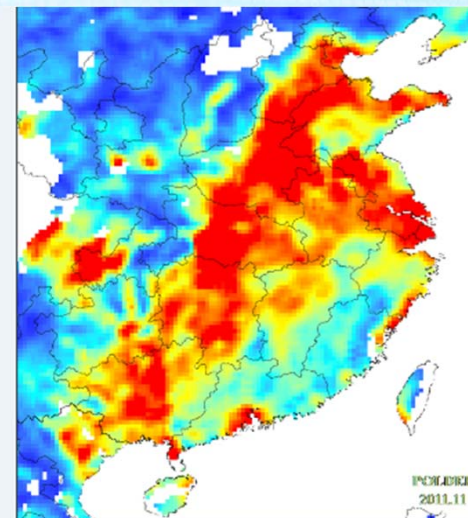
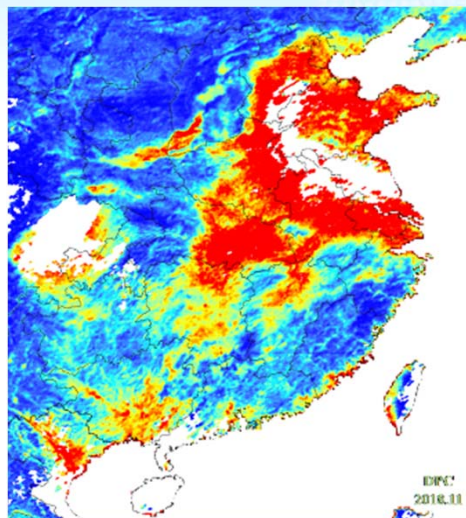
**18.5km of POLDER
in Nov. 2011**



❖ **Comparison of AODf from DPC and POLDER in China, India and Africa**

**3.3km of DPC
in Nov. 2018**

**18.5km of POLDER
in Nov. 2011**

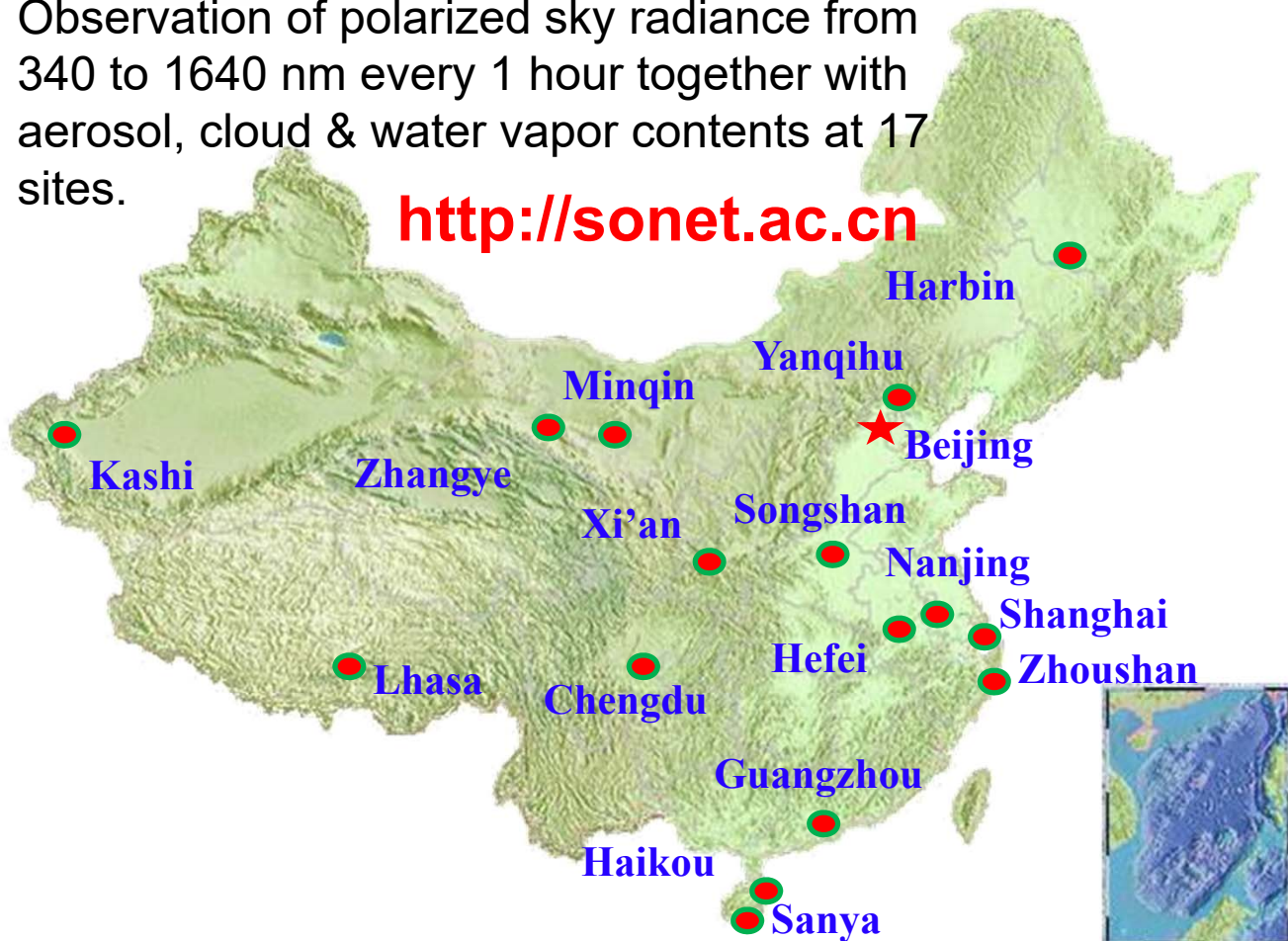




The polarized Sun-sky radiometer network (SONET)

Observation of polarized sky radiance from 340 to 1640 nm every 1 hour together with aerosol, cloud & water vapor contents at 17 sites.

<http://sonet.ac.cn>





❖ SONET instrument parameters and sites

TABLE I. Wavelengths, bandwidths, and polarization of the sun-sky radiometer CE318-DP.
FWHM = full width at half maximum.

Bands (nm)	340	380	440	500	675	870	936	1,020	1,640
FWHM (nm)	2	4	10	10	10	10	10	10	25
Polarization (yes/no)	Yes	Yes	Yes	Yes	Yes	Yes	No	Yes	Yes

Climate	Site	Location	Alt (m)	Start time	Aerosol characteristics
Tropical	Sanya	18.3°N, 109.4°E	29	Aug 2014	Maritime + urban
	Haikou	20.0°N, 110.3°E	22	Mar 2014	Maritime + urban
Temperate	Guangzhou	23.1°N, 113.4°E	28	Nov 2011	Maritime + urban/PRD region
	Zhoushan	29.9°N, 122.1°E	29	Jan 2012	Maritime + urban
	Shanghai	31.3°N, 121.5°E	84	Mar 2013	Maritime + urban/YRD region
	Hefei	31.9°N, 117.2°E	36	Jan 2013	Urban/YRD region
	Nanjing	32.1°N, 119.0°E	52	Jan 2013	Urban/YRD region
	Chengdu	40.6°N, 104.0°E	510	May 2013	Urban (basin)
	Songshan	34.5°N, 113.1°E	475	Nov 2013	Urban + dust
Continental	Xi'an	34.2°N, 108.9°E	389	May 2012	Urban + dust
	Beijing	40.0°N, 116.3°E	59	Mar 2010	Urban/Beijing–Tianjin–Hebei region
Dry	Harbin	45.7°N, 126.6°E	223	Dec 2013	Urban
	Minqin	38.8°N, 100.3°E	1,589	Feb 2012	Dust
	Zhangye	38.6°N, 103.0°E	1,364	Jul 2012	Dust
	Kashi	39.5°N, 75.9°E	1,320	Jun 2013	Dust
	Lhasa	29.6°N, 91.2°E	3,678	Sep 2013	Background



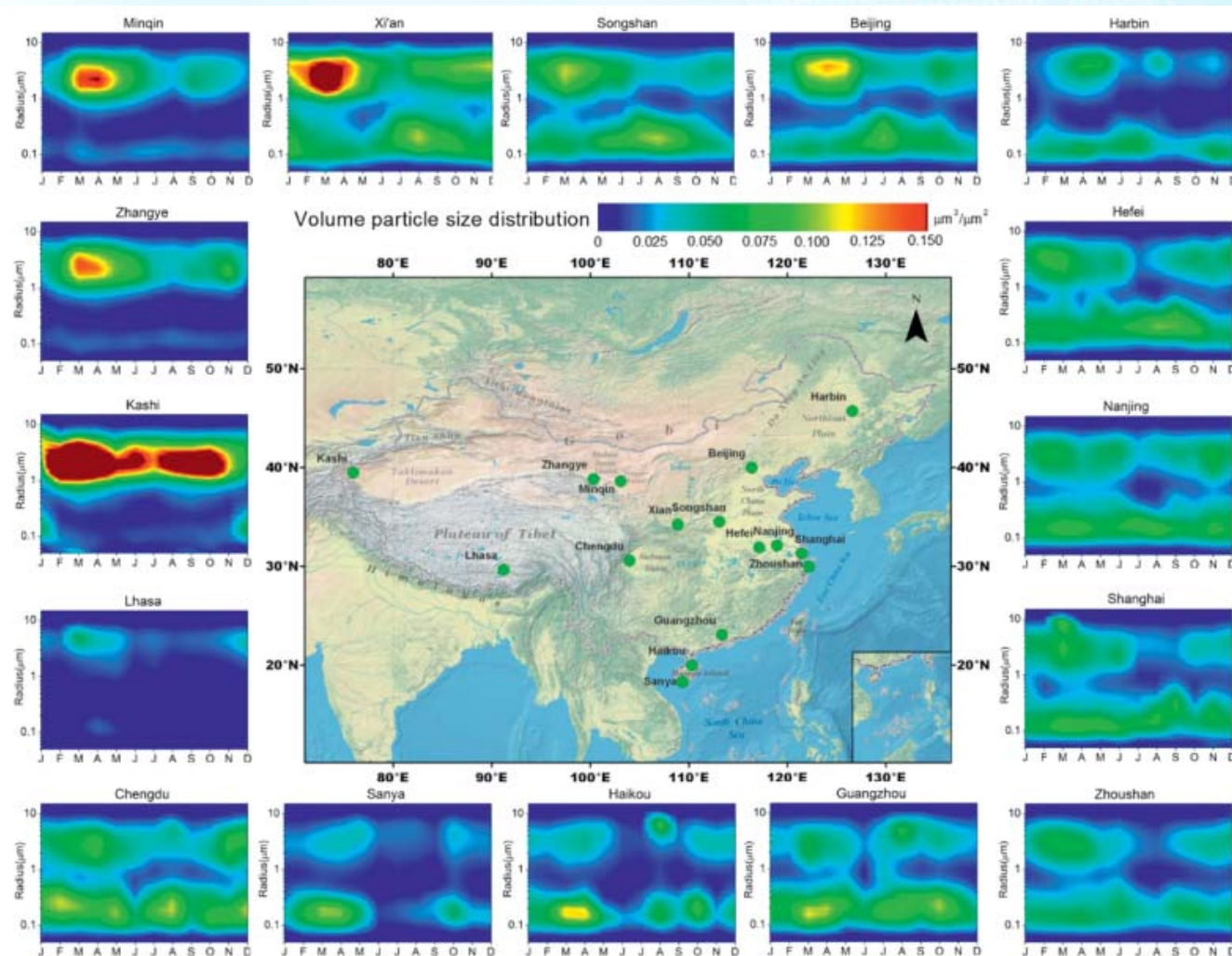
❖ SONET data products

Products	Description	Unit
AOD (λ)	Aerosol optical depth (340, 380, 440, 500, 675, 870, 1,020, and 1,640 nm)	—
AE	Ångström exponent (440–870 nm)	—
FMF	Fine-mode fraction of aerosol optical depth (500 nm)	—
SSA (λ)	Single-scattering albedo (440, 675, 870, and 1,020 nm)	—
$F_{11}(\lambda)$	Scattering phase function (440, 675, 870, and 1,020 nm)	—
$-F_{12}(\lambda)$	Polarization phase function (440, 675, 870, and 1,020 nm)	—
$g(\lambda)$	Asymmetry factor (440, 675, 870, and 1,020 nm)	—
$S(\lambda)$	Lidar ratio (440, 675, 870, and 1,020 nm)	—
$dV/d\ln r$	VPSD with 22 bins for radius from 0.05 to 15.0 μm	$\mu\text{m}^3 \mu\text{m}^{-2}$
$n(\lambda)$	Refractive index (real part) (440, 675, 870, and 1,020 nm)	—
$k(\lambda)$	Refractive index (imaginary part) (440, 675, 870, and 1,020 nm)	—
r_{eff}	Effective radius (total, fine, and coarse modes)	μm
V	Volume concentration (total, fine, and coarse modes)	$\mu\text{m}^3 \mu\text{m}^{-2}$
NS (%)	Percentage of nonspherical particles	—
RF	Shortwave aerosol radiative forcing (0.3–2.8 μm) at TOA or BOA	W m^{-2}
RFE	Shortwave aerosol radiative forcing efficiency [i.e., RF normalized by AOD (550 nm)]	W m^{-2}
AW (%)	Percentage of mass concentration of water uptake of aerosols	—
FS (%)	Percentage of mass concentration of fine-mode scattering components (e.g., sulfate, nitrate and light non-absorbing organic matters)	—
CM (%)	Percentage of mass concentration of coarse-mode components (dust or sea salt)	—
BrC (%)	Percentage of mass concentration of brown carbon components	—
BC (%)	Percentage of mass concentration of black carbon components	—

Li, Z., et al. (2018), Comprehensive study of optical, physical, chemical and radiative properties of total columnar atmospheric aerosols over China: An overview of Sun-sky radiometer Observation NETwork (SONET) measurements, *BAMS*, 99(4), 739–755



❖ SONET volume particle size distribution



Li, Z., et al. (2018), Comprehensive study of optical, physical, chemical and radiative properties of total columnar atmospheric aerosols over China: An overview of Sun-sky radiometer Observation NETwork (SONET) measurements, *BAMS*, 99(4), 739–755



Validation of AOD_f from DPC/GF-5



N = 215

$y = 0.772 * x + 0.05$

R = 0.908, RSE = 0.028, MAE = 0.009 www.aircas.ac.cn

Thank you!

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